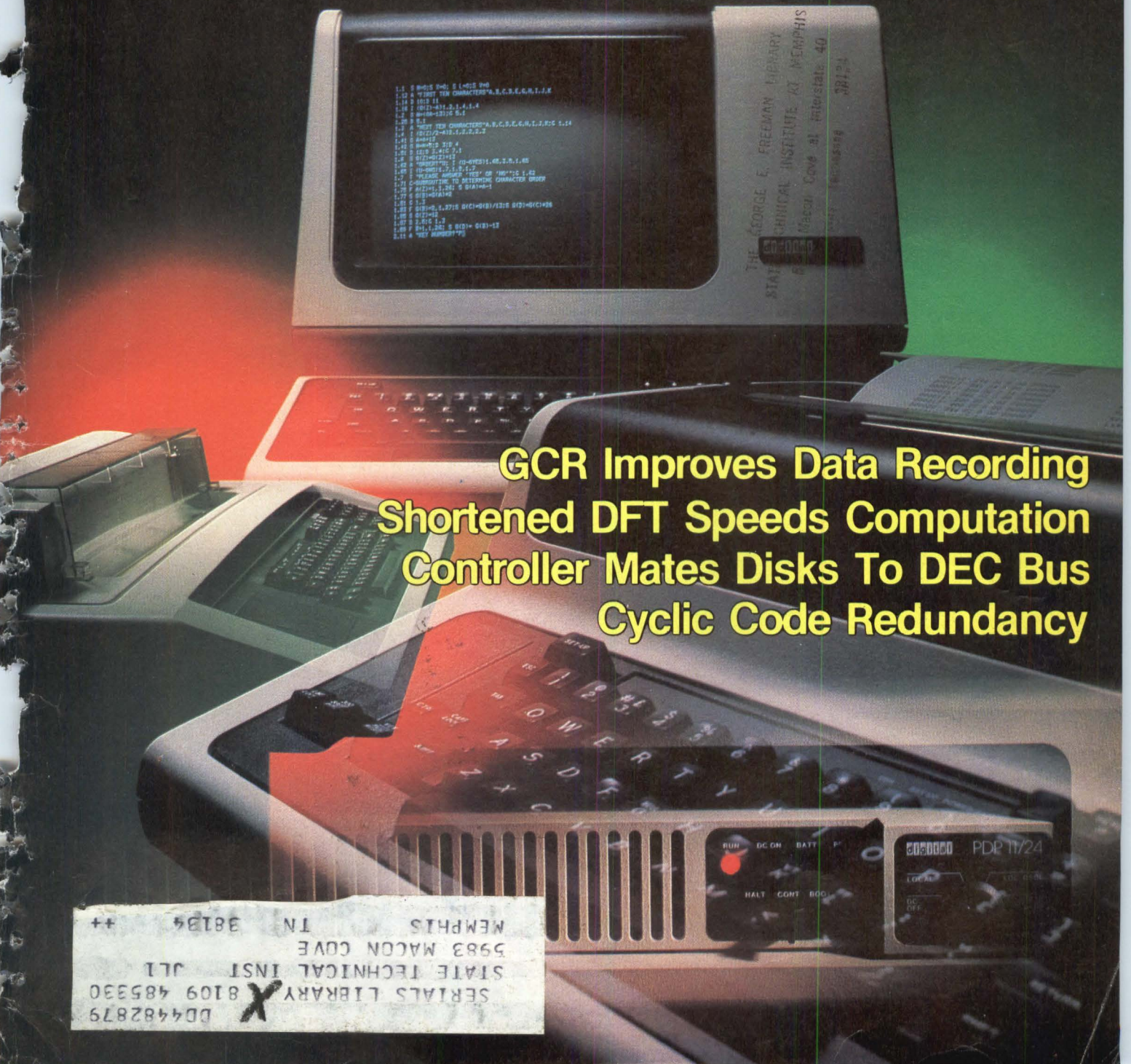


# Digital Design

Computers • Peripherals • Systems

## DEC Directory



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Shortened DFT Speeds Computation  
Controller Mates Disks To DEC Bus  
Cyclic Code Redundancy**

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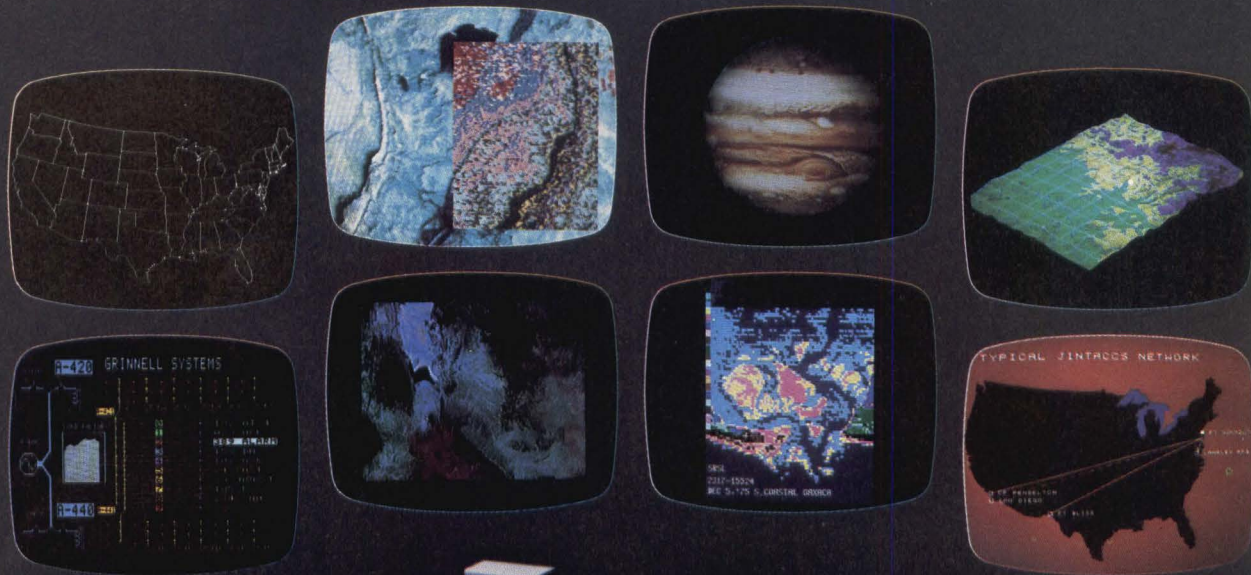
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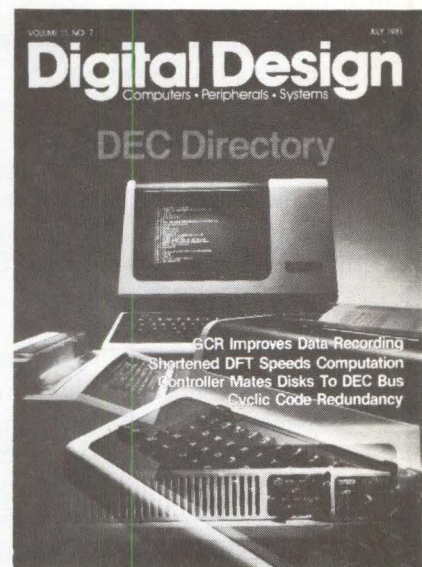
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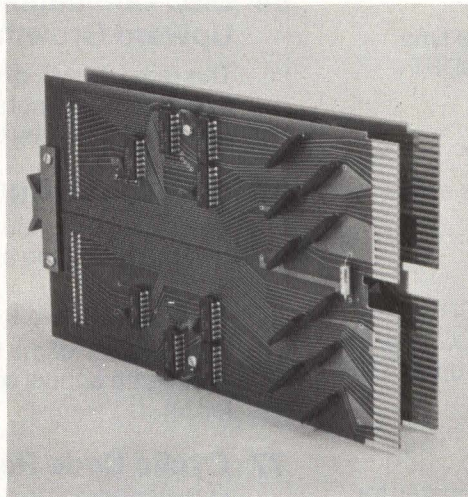
*Symbolizing the growing trend toward DEC computer products in the minicomputer, microcomputer and ancillary processor and peripheral fields, this cover captures the essence of this issue, which includes an extensive DEC-prepared directory of DEC products, specs and prices.*

Photo courtesy of Digital Equipment Corp.



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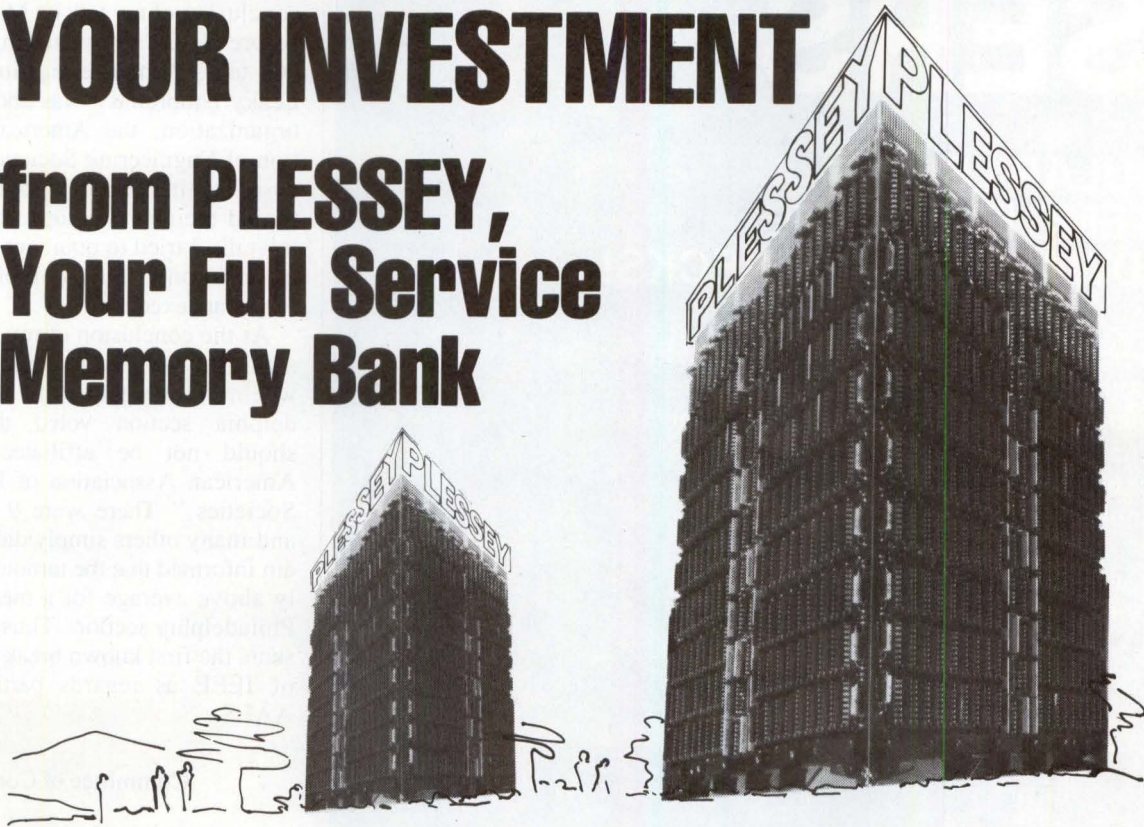
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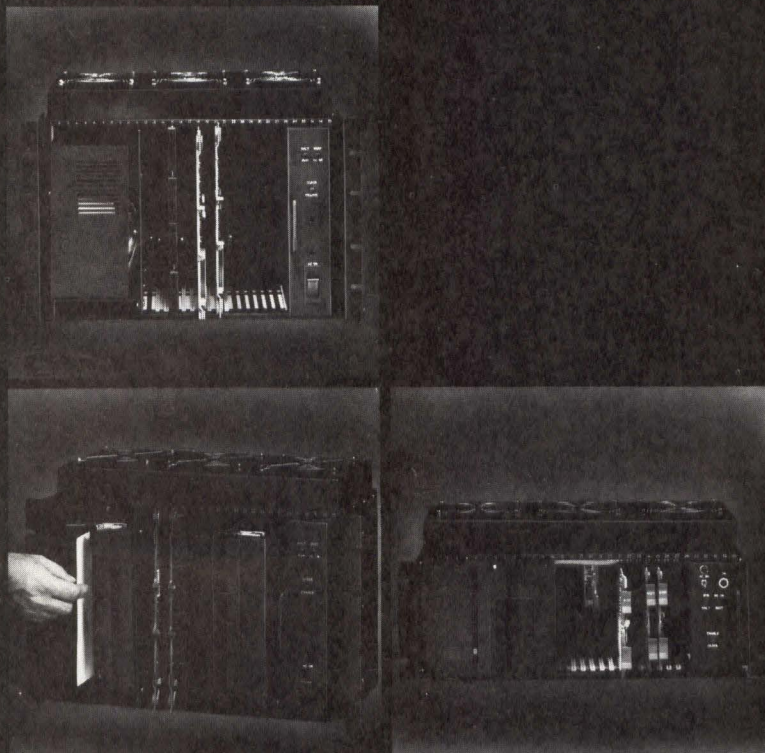
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# Letters

## AAES

Dear Editor:

I am writing to inform you of a very significant event that occurred at the conclusion of my talk on May 19, 1981 before IEEE's Philadelphia section. My talk, "Engineering Societies and Leaky Umbrellas" was about the new organization, the American Association of Engineering Societies, that you described in your May Speakout. IEEE forced members to support AAES. In my talk, I tried to point out how AAES benefits only college professors and corporate executives.

At the conclusion of my talk, a very significant vote was taken: by an overwhelming margin, 16 to 1, the Philadelphia section voted that "IEEE should not be affiliated with the American Association of Engineering Societies." There were 9 abstentions and many others simply did not vote. I am informed that the turnout was slightly above average for a meeting of the Philadelphia section. Thus, this represents the first known break in the ranks of IEEE as regards participation in AAES.

Irwin Feerst  
Committee of Concerned EEs  
Box 19  
Massapequa Park, NY 11762

## programmable gain amplifier

Dear Editor:

Many adjustment problems of the programmable gain amplifier described in a Designers' Notebook (December 1980) would be eliminated if the designer had used a non-inverting amplifier configuration rather than the inverting configuration used.

Prof. S. Ben-Yaakov  
Electronic Engr.  
Ben-Gurion University  
Beer-Sheva, Israel

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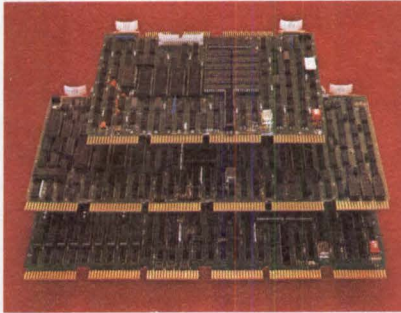
**The TC-151** single board NRZI tape controller interfaces any industry-standard drive to the LSI-11.\* Add a dual width Phase Encode Board for the same performance as the TC-131.

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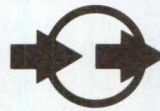
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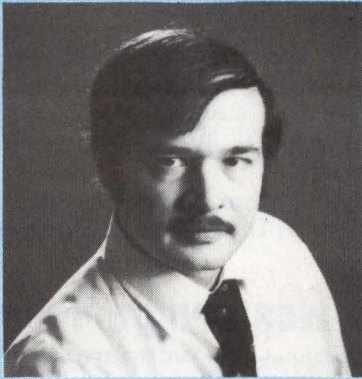


\*Trade name of Digital Equipment Corporation.

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## Do Prices Count?



**Paul Snigier, Editor**

Do you consider price an important factor when specifying a service or product? From the lack of pricing information on some new product releases that we've received, you'd get the distinct impression that prices don't matter to these firms, their agencies and their PR departments. Unfortunately, our readers see it in a different light: if a firm doesn't bother to give a price, it has something to hide — namely a price that's too steep. If written in this (or any other) computer publication, such items draw less response. Certain high-interest items draw more than those in highly-competitive product areas. Different magazines and tabloids have come up with different figures, but all agree that reader response to these "priceless wonders" is down significantly. We agree that it's a serious disservice to new

product editors, to readers and to the company introducing these products.

If a new product is priced high, then the press release should begin with the product's "claim to fame." Yes, a high price will turn off some readers. But it is far better to qualify readers and eliminate those uninterested engineers at the start and not force them to request material. They will not specify the product anyway, and it is a disservice to the firm and a waste of its money to send out material to such readers.

Other reasons for priceless product releases include the great variety of certain product lines. This applies to semiconductor families released at the same time, to cables, to power supplies and a few other items. In such cases, we suggest that it's better to include a price range or the price of a typical or anticipated best-selling member of the family rather than on price.

This type of reasoning, using the priceless new product as a come-on, has been with the trade press as far back as anyone remembers; it has constituted roughly 15% of all new product releases. Today, however, a new type of priceless product release is arriving with growing frequency; it is due to inflation and rapid product changes. Activity is so brisk that prices decline rapidly to meet competitors' price threats. All of this has created a hectic, chaotic and rapidly-changing price situation. It's not surprising that more manufacturers are leaving off prices on their new product releases; they reason that it's safer for them to be on the cautious side. This creates problems for everyone. The new product editors must phone the firms. Too often the individual authorized to provide the information isn't in; too frequently he may not return the call; or, if he does, cannot reach the editor. At times the new product editor may get an argument. This consumes time, and still does not get us the correct pricing information. Many times editors don't bother on many publications; and we notice that this trend is growing.

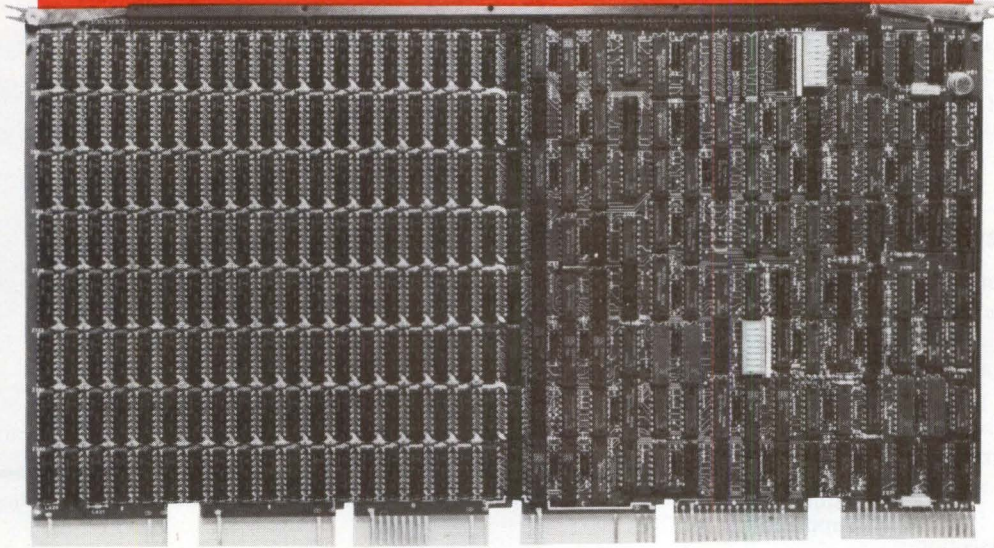
It's the privilege of any agency, PR department or firm not to include pricing on a new product release. We feel it's also the right of every new product editor to take this factor into consideration when he makes the decision to publish — or not publish — that particular product.

We would like your views on the matter of priceless new product releases. Do you feel that we should not publish new product releases that lack prices? Or, should we merely consider it as a negative factor in the overall judgment? If so, how would you want to see it weighted? Let us know. D

*Paul Snigier*



# 1.0MB ADD-IN FOR PDP-11/44



The DR-144S is another industry first from Dataram. This 1.0MB semiconductor ADD-IN quadruples the size of 16K RAM-based ADD-INS available from either Digital Equipment Corporation (DEC) or ADD-IN memory suppliers.

Unlike other manufacturers, Dataram's ADD-IN memory for the PDP-11/44 uses a double word organization with ECC (32 data + 7 ECC) making it completely software compatible with DEC's memory diagnostics. A Mother Board and two Array Boards are joined together by pluggable pins (as shown below) to provide the 1.0MB DR-144S system.

The Mother Board is the only board of the DR-144S assembly which interfaces to the host PDP-11/44. This means that there is only one unit load and

that 1.0MB power requirements are dramatically reduced compared to the approach of using four separate 256KB modules. Also, the DR-144S current drains are much lower in the battery backup mode.

The DR-144S is available with only the Mother Board and in versions including one or two array boards. The DR-144S Mother Board provides a capacity of 256KB. The DR-144S Mother Board with one array board is 512KB; with two array boards, the DR-144S capacity can be either 768KB or 1.0MB.

The DR-144S is an exciting product, but we're not resting on our laurels. You can be assured that when 64K RAMs are more cost effective than the 16K RAMs, the DR-144S will be able to accommodate them. Think of it — a 4.0MB PDP-11/44 ADD-IN!

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- \$9,000/MB in single quantity
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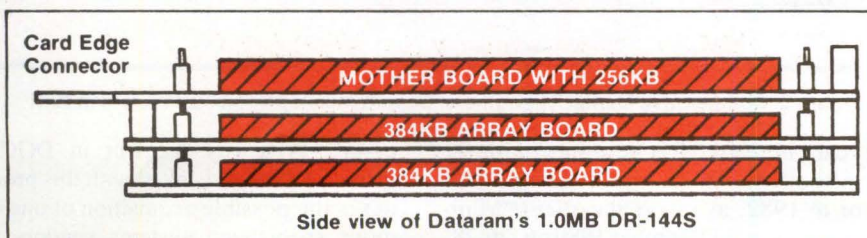
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# Technology Trends

## Users Graduate to Superminis

High-performance superminicomputers have become "hot" items, with more than a dozen suppliers struggling to keep pace with "scorching" user demand. IRD of Norwalk, CT, in a report, attributes supermini popularity to an increased user sophistication and "irresistible" price-performance characteristics. Shipments of 32-bit superminis this year should reach \$300 million, with 60% increase to \$480 million predicted for 1982.

### applications support growing

Although traditionally superminis have been sold as "barebones" hardware, tailored and programmed by users or systems houses for particular applications, vendors are tending to provide more sophisticated programming tools and special-purpose I/O equipment for such applications as aerospace simulators, oil drilling analysis, process control and business transaction-processing, according to the report. Will the current phenomenal growth in this market last forever? No. Soon, in-depth support of particular applications niches will become the deciding force in market leadership.

### major challenge from HP — not IBM

With almost 40% of the current market (in terms of the value of equipment installed), DEC is the leader in 32-bit superminis, with its VAXes. Runners-up are Perkin Elmer (22%), SEL/Gould (17%) and Prime (16%). IRD predicts an "important" new supermini, from H-P, which may be announced soon. The machine will be comparable in power to mid-range VAX equipment and configured as a desk-top. A head-on competitive machine from IBM is unlikely; an IBM supermini product would damage IBM's 32-bit commercial offerings in the 4331 and 434n series, with which superminis compete in some applications.

### DGC readies "Fountainhead" for introduction

Data General, which introduced its MB/8000 series of superminis last

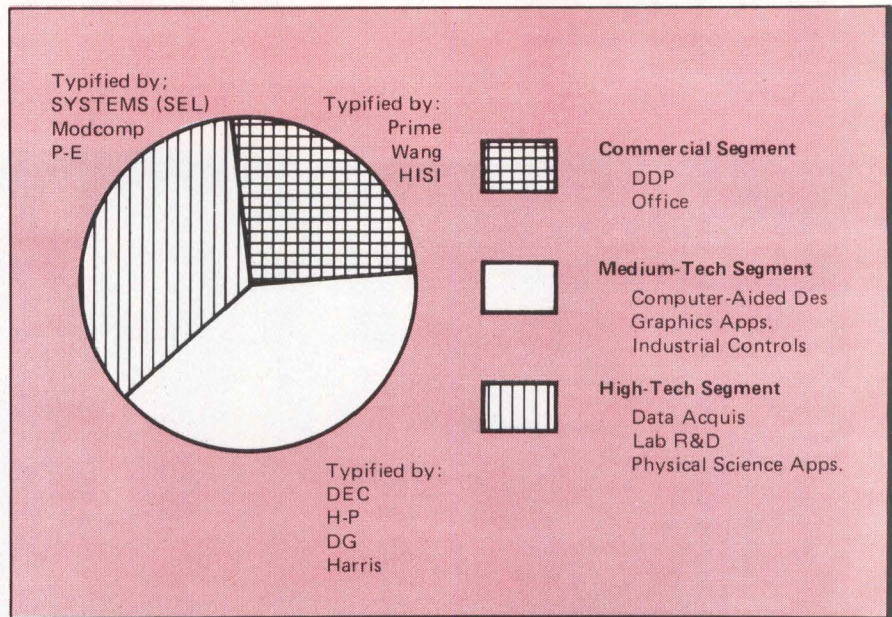


Figure 1. Superminicomputer Market Segmentation and Primary Positioning of Leading Suppliers

|  | KEY                      |  |            |
|--|--------------------------|--|------------|
|  | 1 - Strong               | 2 - Moderate                                 | 3 - Weak   |
|  | High-Tech<br>(Lab & R&D) | Medium-Tech<br>(Scientific<br>& Engineering) | Commercial |
| <b>32-Bit Superminis</b>                                     |                          |  |            |
| Apollo   | 3                        | 1  | 3          |
| BTI  | 3                        | 2  | 1          |
| DGC  | 2                        | 1  | 2          |
| DEC  | 1                        | 1  | 1          |
| Honeywell (HISI)   | 2                        | 2  | 1          |
| Perkin-Elmer   | 1                        | 1  | 2          |
| Prime  | 2                        | 2  | 1          |
| Systems  | 1                        | 2  | 3          |
| Wang   | 3                        | 3  | 1          |
| <b>Other-Word-Length<br/>High Performance<br/>Superminis</b> |                          |  |            |
| Harris   | 1                        | 1  | 2          |
| H-P  | 1                        | 1  | 2          |
| Modcomp  | 1                        | 1  | 3          |
| Tandem   | 3                        | 2  | 1          |

Figure 2. Comparative Market Strengths of Superminicomputer Manufacturers in 1981

year, is readying a new supermini for introduction to the market later in 1981 or in 1982, as reported earlier ("Minicomputers", December 1980 pp. 26-28, P. Snigier). The "Fountainhead Proc-

essor" is a key element in DGC's growth strategy. Linked with this product is the possible acquisition of one or more specialized systems vendors to provide DGC with "instant" applica-



tions expertise. DGC's abortive attempt to acquire Megatek, a computer graphics system manufacturer, is an example of a potential "short-cut" to obtaining computer-graphics software capability for DGC's supermini series.

### no competition from Japan? Unlikely.

Micro and minicomputer suppliers brace themselves for a "tremendous" influx of new products from Japan. But is there an immediate prospect of severe Japanese competition in the supermini segment? No. But why? The Japanese and European computer suppliers overlooked the potential of this market sector, in their eagerness to ship large numbers of small business computers and traditional EDP systems. Meanwhile, most U.S. vendors of superminis are "doing rather well" in overseas markets.

## Software Trends Spark Competition

Competition is intensifying among companies vying for control of vital software areas. The strengths of different software companies will establish their predominance in their respective market focuses over the next five years, relative to operating systems, languages utilities and specific market applications. Contention among several companies is the battle for dominance of 16-bit operating systems. Digital Research's CP/M operating system achieved the status of de facto standard for 8-bit  $\mu$ Cs. However, efforts to control operating systems at the 16-bit level as well are encountering formidable competition from UNIX and UNIX-like operating systems produced by companies such as Micro-Soft Inc., Bell Labs, Onyx, Cromemco and others. Standards of 16-bit operating systems will be determined within the next two years, according to Creative Strategies International of San Jose, CA, in a new report.

As software houses solidify into major marketing forces for hardware, their allegiances to certain computers and/or operating systems will largely determine the success of those computers. Trends in the  $\mu$ C industry are toward standardization more than in any other aspect of the data processing industry. Especially at the operating system level, incompatibilities will severely hinder developments. Only

those hardware manufacturers with very strong in-house software development can afford incompatible, proprietary operating systems. Software, and good documentation of that software, will control the sales of microcomputers. Hardware manufacturers that ignore this fact will not do well.

Most of the best software available today is from third-party software houses, and this trend will continue. With few exceptions, hardware manu-

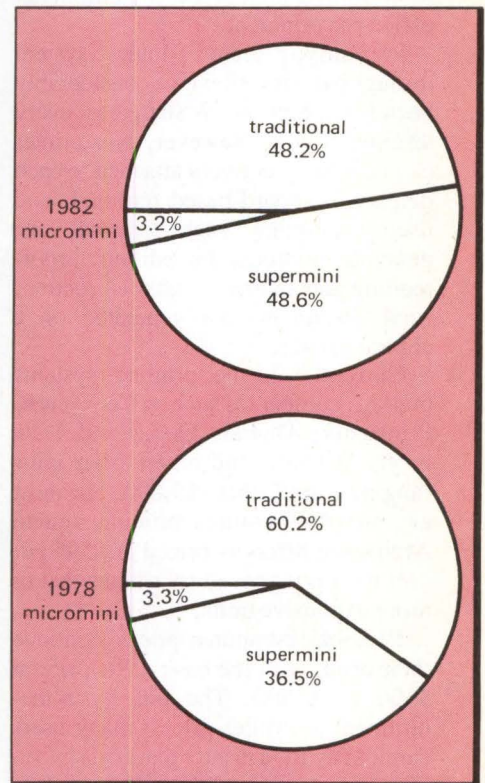
facturers have not moved to develop software in-house, but have acquired software from suppliers outside the manufacturers' environment.

The fast-changing technology of  $\mu$ C industry requires distribution across as large a base of systems as possible. There is an escalating rush among software houses to generate "Lathe" type software converters, which allow quick transfer and translation from one machine to another, within and without a similar operating system and  $\mu$ P.

## Minis Continue To Gain On Mainframes

The sophisticated end user has become the rule, not the exception. This, in turn, has fueled demand for greater user control and encouraging the trend towards DP decentralization. Even within the minicomputer industry, effects of changing user needs can be seen. Conventional minis will continue to be well-suited for automation control and advanced communications work, as well as laboratory analysis and "number crunching." On the other hand, microminis, sometimes called microcomputers, are becoming increasingly attractive as an alternative to conventional minis. These small, one-board systems are particularly cost effective for tasks such as control of machine tools where data handling requirements are modest.

Minis with more powerful processors are evolving in the other direction to become "superminis." While the prices of these computers are substantially higher than those of conventional minis, the greatly increased data handling capability and ease of programming will make superminis the fastest growing minicomputer category.



Share of minicomputer shipments by type 1978 and 1982, in pie-chart form, are by factory value of U.S. shipments.

## Printers: Key To Computer Growth

What the computer world needs is a low-cost printer to solve the current dilemma of peripheral cost exceeding many basic computers. While lower mini and  $\mu$ C prices have made computers accessible to broader business and personal applications, the peripheral costs, particularly printers, inhibit their full development.

The 20-, 40-, and 80-column printers, such as offered by Alphacom, and others, will grow rapidly in the low-end small business and personal computing

market, which will increase in the 1980-1985 window by over 23% a year, from today's \$1.2 billion, rising to \$3 billion.

Printers now range from thumbnail-sized calculator-based printers to the largest and most refined thermal and impact printers at all market levels.

### markets are changing

The 20-, 40-, and 80-column alphanumeric and graphics printers are attractive to business and professional



end users, because hard copy of data, graphs, charts and tables are increasingly becoming a standard requirement. Now, hobby, educational and home computer users also have a feasible printer option. Professional and business users, lacking alternatives, use printers costing \$1000 to \$3000 for all hard copy, including rough draft. The cost limits their number to one per business computer. With the low cost of newer 80-column printing systems, more than one printer can be connected to a shared-logic type system in an office environment.

Presently, shared logic system throughput is slowed considerably because one printer is shared by every terminal. Now, however, one printer can be cost-effectively attached to each display keyboard-based terminal, and users operating each terminal can generate printouts for editing, proof-reading and approval. After correction, final documents are generated on a central printer.

Currently in the printing systems market, companies such as Centronics, Printronix, Diablo, Qume and Data Products Corp. and others offer units ranging from \$900 to \$5,000. The most expensive 80-column printing system Alphacom offers is priced at \$595 per unit with print speed four times that of more expensive units.

Personal computer prices continue their drop, with the basic CPU price at \$500 to \$1500. The big fly-in-the-ointment is printer prices: many users cannot pay for a printer that costs two to four times the CPU! Big markets remain dormant. But, now the newer 20-, 40-, and 80-column printers, ranging from \$175 to \$595, provide many users hard copy capability at more-affordable prices.

### but, can they deliver?

The printer boom continues. Inexpensive, fast and reliable models are the fuel behind sales. Can suppliers deliver? Key to this growth is suppliers meeting volume demands inherent in an expanding, price-competitive market. Will traditional, computer-oriented companies geared to lower-volume manufacturing requirements keep pace with demand and price changes? Not unless they change.

Some firms are well-positioned to take advantage of this growing market. For example, Alphacom of San Jose

ensured its ability to deliver through an exclusive North American distribution agreement with Olivetti and manufacturing agreement with Rockwell, which invested over \$2 million in production facilities for Alphacom's Sprinter Series.

Quality, volume and engineering

support are keys to the printer field of the 1980s. Traditional companies specialize in limited-capability machines or market niches, making their products less flexible for the broader requirements of the OEM concerned with end users' immediate applications.

## Low-Cost Graphic Systems Aid OEM Designers

In a major expansion of CAD/CAM product lines, firms are introducing low-cost graphics workstations and software packages configured for use by OEMs.

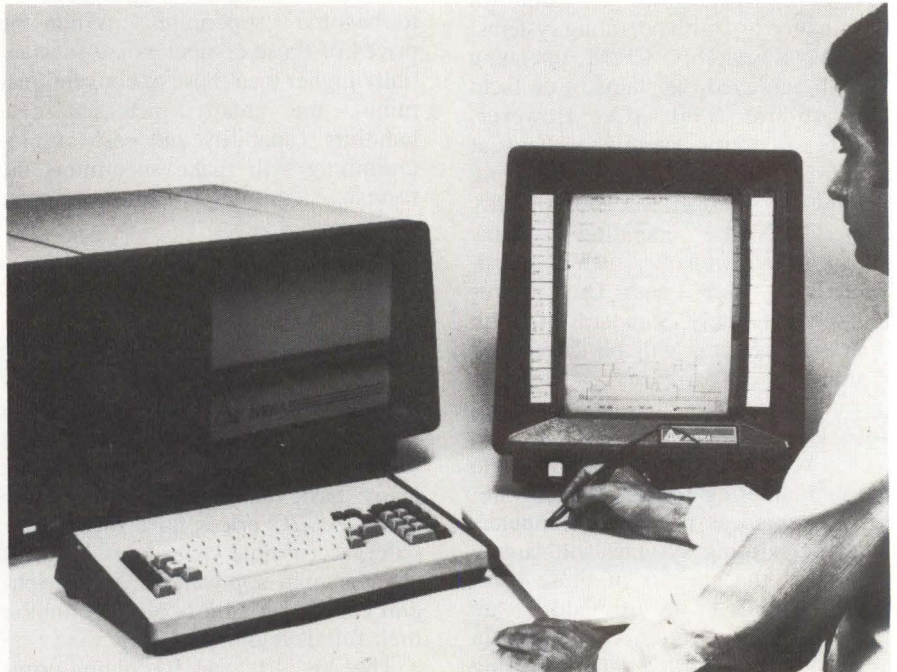
Avera of Scotts Valley, CA, has such a system. Its four workstations are built around a dual processor architecture based on Intel's 16-bit 8086 microprocessor and an OS with 200,000 lines of Pascal code. The four workstation configurations include the GS1100, including 2 diskette drives, 192-KB parity memory, dual processors, two RS-232C ports, keyboard and control electronics, B/W display and control electronics, data tablet and control, 64-KB bit map, supplies and enclosures. GS1120 is like GS1100 with one diskette drive and one 10-MB Winchester drive. The GS1200 is like GS1100, but with a 13" color display. GS1220 is like GS1200 with one diskette drive and one 10-MB Winchester drive.

### dual processor architecture

Key to the power of the workstations is a dual processor architecture with two 8086s sharing the command and graphics processing load, with the processor's arbitrating through a multitasking OS. One processor interprets commands; the other supports graphics. The main processor has 128 KB of RAM; the graphics processor, another 64-KB RAM plus a 64-KB bit map. Main storage RAM has parity checking, but the bit map does not. Memory (combined) can be expanded to a total of 1 MB.

### graphics input and software

A 564-by-832 pixel CRT display is oriented vertically, with a 9"-by-12" viewing area and 24 on-screen functions that respond to cursor control. The graphics area contains 512-by-512 pixels. The display unit also features a two-digit LED display for indicating



An Avera workstation user need not to know how to type or draw. This work station is configured so that users simply point a stylus at the proper command on the screen or draw a simple symbol on the drawing pad input.



self-diagnostic codes and speaker to acknowledge a command input.

Software, designed for ease of use, is organized into five command groups: control, editing, manipulation, status and viewing — an organization that eliminates the need to display all commands simultaneously. Once a command category is selected, commands within that group are displayed. The user strings together functions and demands syntax of a given command. Using the data tablet, he draws symbols representing commands.

### recursive data structure

Via the Pascal-based OS (common to all systems), a flexible recursive data structure is utilized. A recursive structure allows users to associate any graphics or text components in the data structure with other components to an arbitrary level of complexity by nesting. It forms hard associations; for example, a line can be associated with a symbol so that if the line is later moved, the symbol cannot be inadvertently left behind. Via an intermediate data structure for external communications, these systems are amenable to design partitioning and uploading to larger computers, including IBM mainframes.

## CAD Package Improves Engineering Productivity

Advanced CAD software package Medusa provides complete 2-D and 3-D design, drafting and documentation. Based on Prime Computer's general-purpose 32-bit computer systems, Medusa enables designers to customize their own design system, a capability unavailable with turnkey or software-only offerings.

The system is packaged with its own integrated workstation, available with color or B&W terminals. Workstations are configured for easy access to control elements and provide a high 1000-line resolution display to enhance operation and increase performance.

The 2-D entry-level model is used for layouts, schematics and detailing tasks in mechanical, electrical, structural and electronic applications. The advanced 3-D model is for designing a complex 3-D object and then producing an engineering drawing. The workstation has a 19" display, joystick for easy manipulation and control of cur-

sors, a data tablet, PT25 character-mode terminal and graphic controller.

Cost? Don't expect to buy one for your home computer lab. A typical entry-level Prime/Medusa system costs \$235K and includes one Prime 250 CPU, 768-MB memory, one 96-MB disk drive and two workstations with B&W terminals. Licensed software includes 3-D Medusa, Primos, Fortran, Midas and CPL. Medusa software can be licensed separately at \$30K and \$60K for the 2- and 3-D models, respectively.

## Computer Graphics Will Improve Sagging Managerial Productivity

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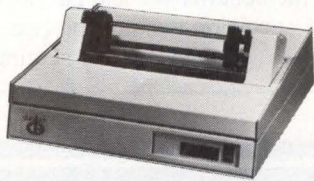
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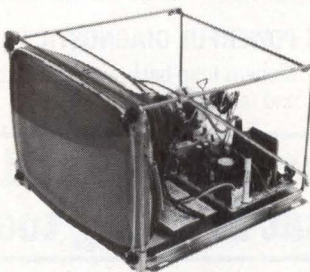
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## Technology Trends

scientific and engineering applications to combat this problem. A single glance can reveal in seconds subtle trends and relationships that can take hours to decipher from a table of numbers.

In a special OARS report, entitled "Graphics in the Office," IDC of Framingham, MA, forecasts a sharp rise in the overall use of computer graphics, averaging 35% growth per year through 1984. In dollars, this represents an increase in revenues from just over \$1 billion in 1979, to over \$4.5 billion in 1984. It certainly is no revelation that graphics — pie charts, bar graphics, etc. — are easier to comprehend than a table of numbers. Executives used graphics for presentation and analysis for years. What is new is the concept of generating graphics interactively without involving graphic arts to bring immediate answers to management's questions. An example of what can be done is the use of "what if" gaming techniques, which allow the manipulation of variables such as price, return on investment, etc.

CAD/CAM systems are the dominant force in the graphics market. While CAD/CAM systems are much more sophisticated and more expensive than business systems, it is actually the business applications market which will show the fastest growth: shipments of some \$1 billion are forecast by IDC for 1984. CAD/CAM systems may dominate the overall market dollarwise, but in terms of sheer numbers, the business graphics market will far surpass it in units shipped. In fact, business applications will soon rival CAD/CAM applications as the major driving force. Most of the technology is in place; all that is needed is to refine and tailor it to the specific needs of business.

Display devices accounted for a little over half of all graphics expenditures. Hard copy devices accounted for just over a third, while the remainder of the expenditures went for such other equipment as business/personal computers and photographic output devices.

Things will change rapidly, however, on the computer graphics scene over the next five years. Much of this change will be due to a sharp rise in the number of personal computers used for graphics. Additionally, as the technology improves, the price of low-cost, hard copy will begin to fall. These devices — dot matrix printers/plotters, color cameras, and ink jet printers, etc.

— will grow in numbers, though dollarwise shipments of these devices will drop to 22% of the total business graphics market by 1984. Furthermore, IDC is predicting that business/personal computers will account for 20% of the graphics market (by dollar value) in 1984. Display devices will dip slightly — to under half of total expenditures at that point, while photographic equipment will rise to approximately 8% of the market.

Display devices use three primary technologies: the direct view storage tube (DVST), raster refresh tubes, and random scan tubes. Each of these technologies has its own cost/performance trade offs. IDC views raster tubes (which operate much like a TV set) as the technology of choice for business purposes mainly due to high-quality color, good resolution, selective erasure, and the ability to display photographic images. The big drawback to raster scans right now is cost. The images of raster scan must be refreshed many times a second, and this requires the definition and storage in memory of every pixel (picture element), whether part of the image or not. Obviously, the memory and processing cost in this method are prohibitive, but as memory costs continue to drop it will become less of a factor.

The other methods of display mentioned also have their pros and cons. Direct view storage tubes, for example, don't need to be refreshed 30-60 times a second, and they offer high resolution at low cost. However, selective erasure is not possible in a DVST, and low light output is another factor to be considered. Random scan tubes offer selective erasure and higher resolution than raster refresh tubes, but only limited color. These displays have been employed mainly by the engineering/scientific community where resolution is very important and color less so.

Of the 180,000 shipments of display devices forecast in 1984 by IDC, 75% will be raster scan tubes. Additionally, approximately 90% of these will be color tubes, as compared to 63% for raster tubes shipped in 1979. Users will drive the graphics display market toward increasing use of color graphics for business applications.

With color displays soon to dominate the market, the demand for color hard copy will also increase dramatically. Color displays and color hard copy devices will grow hand in hand. If inexpensive, convenient hard copy output devices are slow in coming, we can expect this to have a dampening



effect on the color display market. By the same token, if color hard copy output becomes available quickly, then the color display market will be boosted.

What's in store for users regarding output devices? Quite a few things, including: • color cameras — useful for the preparation of slides, transparen-

cies, and color microfilm, • photo-composition devices — offering superior resolution previously available only to graphics designers, and • dot matrix printer/plotters — simple adaptations of alphanumeric matrix printers, which can not only produce shades of gray, but by striking over can also produce color.

## Remote Terminals

**JAPAN:** Matsushita is planning to bring CAD into the Japanese home. The principle is that a lady customer, shopping for dresses is filmed by video camera. The video film, together with size statistics, is stored by company. Whenever the shopper wants to buy a dress, she telephones the company, her film is recalled from data and displayed on TV. Dresses are then superimposed on image as though she were trying them on. Hopefully, she will select one that looks good on her. . . **BARBADOS:** A \$9 million plant (with more than 100 employees) for manufacturing resistors has opened on this Caribbean island. Backer is TRW of the US. The range of resistors is designed for a variety of electronic systems from basic telephone equipment to sophisticated space research. . . **LONDON:** Scientific Calculations has opened a London office. The company produces printed circuit designs and applications. . . **SOMALIA:** This country has become the 106th member of INTELSAT (International Telecommunications Satellite Organization.) INTELSAT operates the global satellite system that provides 2/3 of the world's international telecommunications services. . . **FRANCE:** British and French telecommunications officials have agreed to adopt a new technical standard for Viewdata by the mid-1980's. This will end the rivalry between Britain's Prestel and the French Antiope. A working method with Germany is also being developed. Japan has been waiting for such an agreement and should be among the first to produce new standard Viewdata terminals. Viewdata transmits such things as telephone directories service (500,000 directory terminals for France alone); electronic mail; stock market; news; information; etc. . . **IRELAND:** A high technology research center is being set up in Limer-

ick. It will concentrate on the application of electronic technology and the material sciences with particular emphasis on alternate energy sources. . . **ITALY:** The Italian Olivetti group is acquiring control of the Swiss company, Hermes Precisa, manufacturer of office equipment. . . **WEST GERMANY:** Production of West Germany's electronics industry rose 4.9% to \$44.5 billion in 1980. This increase occurred despite the recession. (1979, however, was a much better year.) . . **HAWAII:** The Fourth Annual Pacific Telecommunications Conference takes place Jan. 18-20, 1982, at the Ilikai Hotel, Honolulu. (Never too early to plan for such events.) Papers and exhibits invited. Contact Richard J. Barber, (Director), 1110 University Ave., Suite 303, Honolulu, HI 96826. . . **SINGAPORE:** A conference and exhibition for the quality control/quality assurance field in Southeast Asia has been scheduled for June 17-19, 1982 in Singapore. . . **HONG KONG:** A new firm has been launched to manufacture magnetic recording heads. The company is SAE Magnetics (H.K.) Ltd., a division of Stanford Applied Engineering Corp. of Santa Clara, CA. . . **SCOTLAND:** The worst recession in Great Britain since the 1930's has served as a stark contrast to the continuing growth and prosperity of the energy and electronics industries in Scotland. Scotland has been the home of several American firms for about half a century and has been attracting high-technology manufacturers for decades. The 1970s, however, has seen a strong burst of growth in the high technology areas, spurred by government financial incentives, a growing pool of skilled labor, research and development resources, and experienced executives willing to start new ventures.

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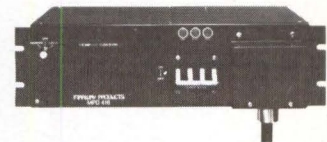
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The image shows several overlapping sheets of forms. The most prominent one is titled 'Unit Price Estimate Calculation Table'. It contains various tables and sections for data entry, including:

- Machine type** and **Material quality** sections.
- A table with columns for **Serial number**, **Dimensions**, **Weight**, **kg**, **Price**, and **Quantity**.
- A table with columns for **Subtotal**, **Type of equip. ment. source**, **Labor hours**, **mfg. cost**, and **Amount**.
- A table with columns for **Unit**, **Unit price**, and **Amount**.
- A **Subtotal** section with a **Final delivery price** calculation:  $(4) + (5) + 6$ .
- A **Final delivery price** section with a calculation:  $(4) + (5) + 6$ .

Other sheets visible include 'Planning Sheet 2-22' and 'Calculation Procedure for Unit Price Estimate'.

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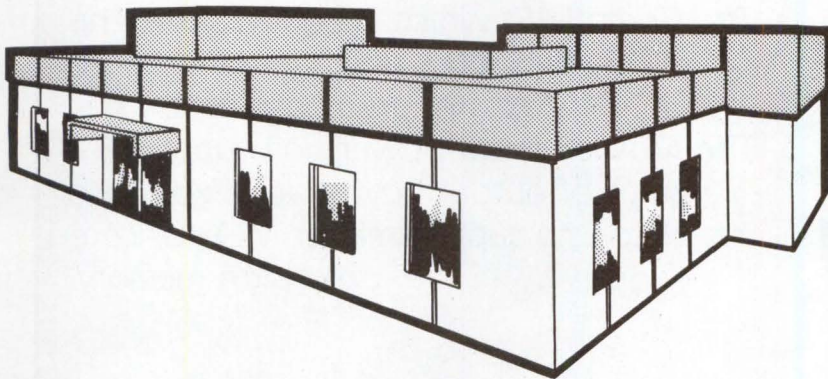
#### Analysis Manual

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- Punctual Delivery Check Sheet
- Operation Rate Survey Work Sampling Statistics Sheet
- Operation Rate Survey Work Sampling Sheet (1)
- Operation Rate Survey Work Sampling Sheet (2)
- Plant and Equipment Check Sheet



# Management in Japan

By Tatsukichi Yanagawa



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 $\bar{x}$ -R Control Chart Data Sheet (1)

$\bar{x}$ -R Control Chart Data Sheet (2)  
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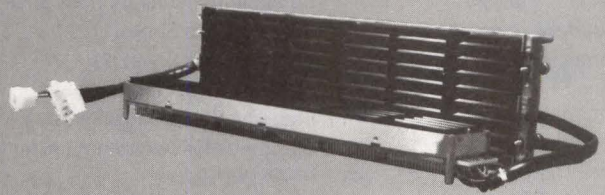
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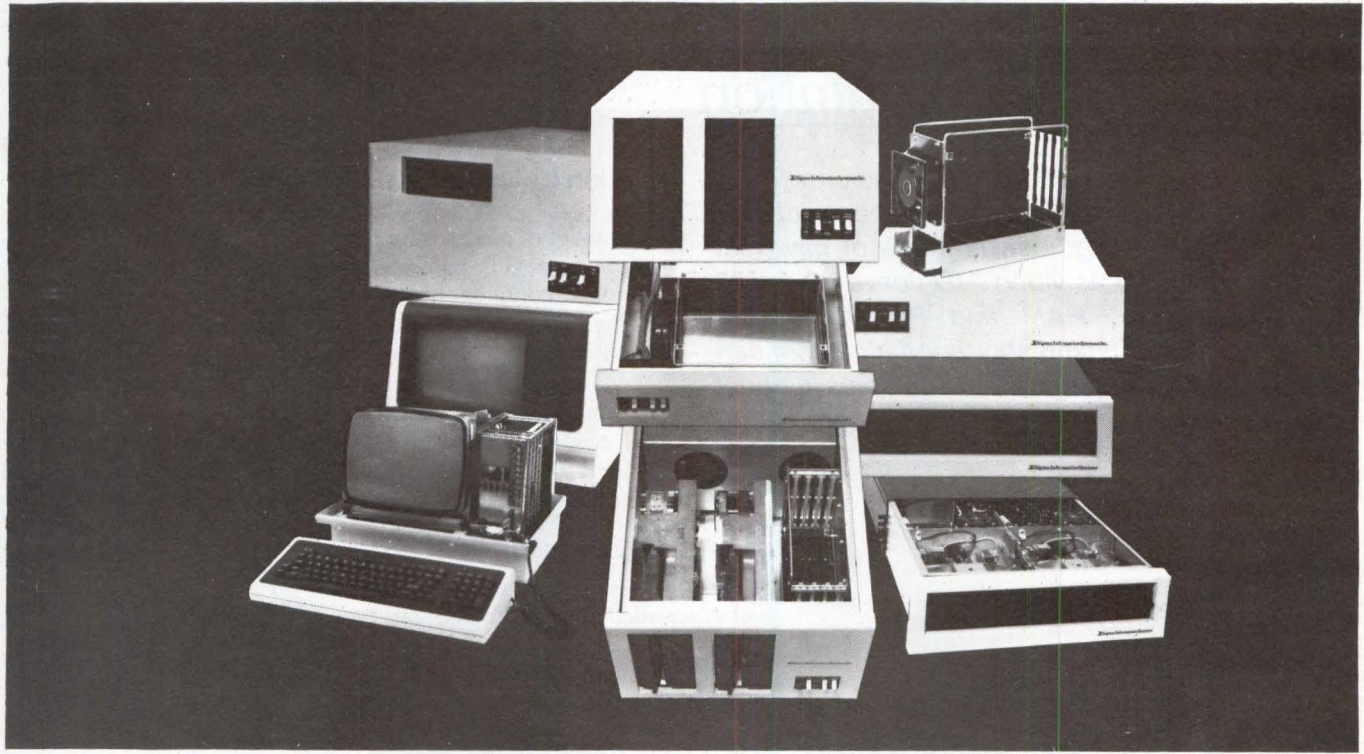
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# Shortened Algorithm

## speeds DFT computation

A shortened Discrete Fourier Transform (DFT) or SDFT algorithm was developed to achieve real time processing. Use is made of new fast components such as video A/D converter, multiplier/accumulator, RAM and PROM. A DFT processor based on the shortened algorithm can calculate power spectrum of 32 samples in about 300  $\mu$ s, giving a maximum sampling rate of 100 KHz.

by Dan Cohen and Avidgor Margalit

A number of methods for the realization of a digital real time DFT processor has been published in recent years. In the past, contemporary technology limitations on the speed of digital components, especially multipliers, prevented the realization of a satisfactory processor. The introduction of new components, such as the monolithic multiplier/accumulator family and video 30 ns-6 to 10 bit ADCs helped solve some major problems. We describe a new method which, with the aid of new components, permits realization of a satisfactory real time DFT processor.

### SDFT is fourfold faster

This shortened algorithm for DFT (SDFT) calculation method fills in the gap between a complicated fast FFT processing and a simple-but-relatively-slow direct DFT computation. Use of shortened DFT gives a four times faster processor in comparison with a direct DFT assuming the

Dan Cohen and Avidgor Margalit are from Haifa, Israel.

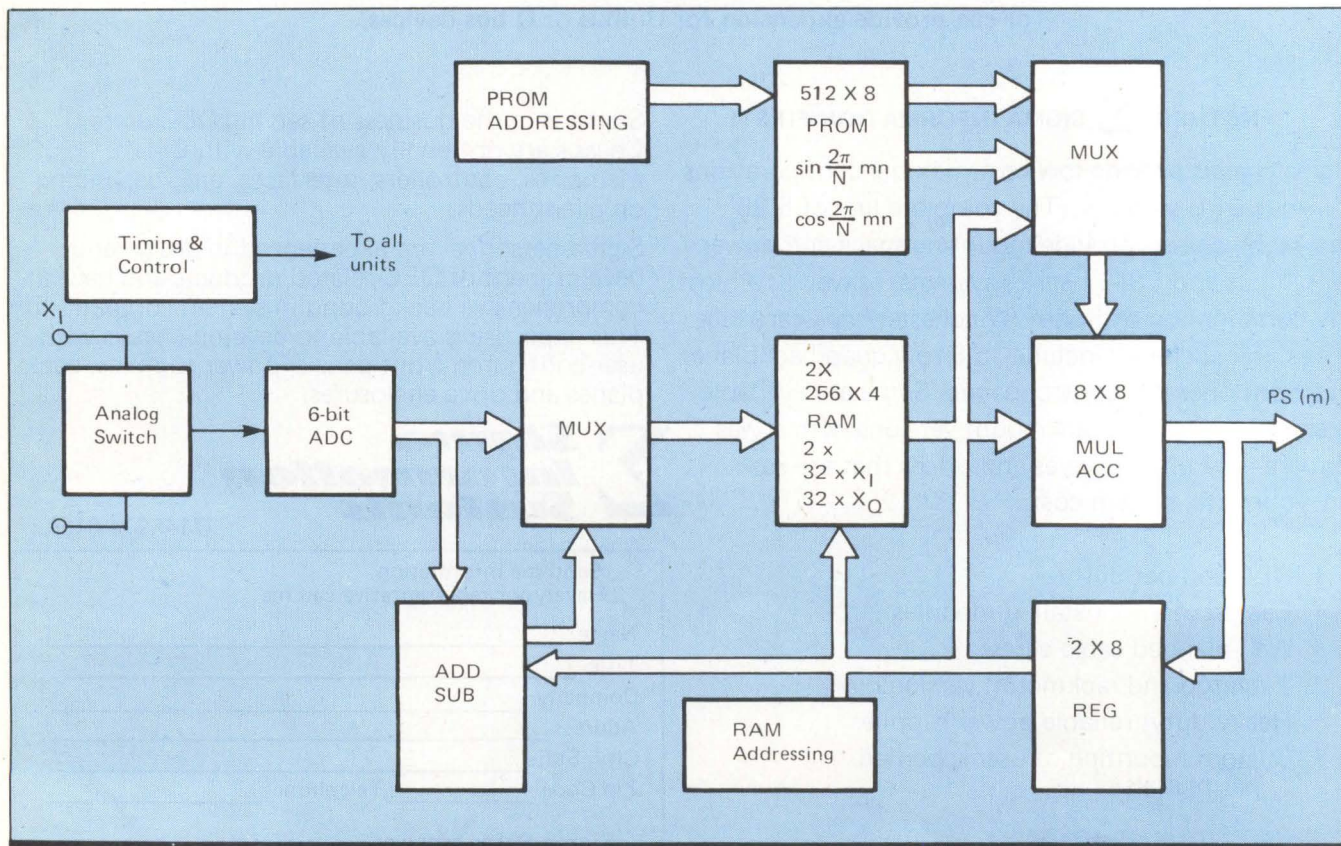


Figure 1: Shortened DFT serial processor (N=32)



same techniques of realization. Such a processor for 32 points was designed and built by the authors, fulfilling the expectations of a fast, low power, low volume and low price unit. A 5-W, one-board processor computes a 32-point DFT in less than 300  $\mu$ s (100 KHz sampling rate), for less than \$500 (qty. 100).

### direct DFT

The DFT is defined as

$$S(m) = (1/N) \sum_{n=0}^{N-1} X_n \exp [(-2\pi j/N) (m n)] \quad (1)$$

where "exp" signifies a base e (or natural) exponential;  $m, n = 0, 1, 2 \dots N-1$ ;  $x_n$  samples are taken at  $\Delta t$  intervals;  $x_n$  are real or complex sample values; and  $N$  is the total number of samples in an integration.

Direct DFT is calculated by solving Eq. 1 for each  $m$  separately. This is the simplest way to realize the processor, hence the name "direct." Despite its simplicity, the introduction of such a processor does cause difficulties in fast real-time systems.

The shortened DFT method eliminates these difficulties by reducing the number of complex multiplications ( $N^2/4$ ) by a factor of 4.

### shortened DFT or SDFT

As is well known, an FFT processor implies  $N \log_2 N$  multiplications, while direct DFT processing requires  $N^2$  multiplications ( $N$  is the processing block length). This number of multiplications can be reduced by partial realization of the FFT algorithm (theoretically it could be done until the complete FFT algorithm is achieved), according to the following equations:

$$\exp(-j2\pi m/N)(N/2+r) = (-1)^m \exp(-j2\pi mr/N) \quad (2)$$

$$S(m) = (1/N) \sum_{r=0}^{N/2-1} \{ X_r \exp(-j2\pi mr/N) + X(r+N/2) \exp[(-j2\pi/N) m(r+N/2)] \} \quad (3)$$

Substituting Eq. 2 into the second expression on the right-most side of Eq. 3 we obtain:

$$S(m) = (1/N) \sum_{r=0}^{N/2-1} \exp [(-j\pi mr/N) \{ x_r + (-1)^m x(r+N/2) \}] \quad (4)$$

Eq 4 shows a reduction of the number of multiplications in the frequency domain. That means  $N^2/2$  multiplications instead of  $N^2$  in the direct DFT. On the other hand this algorithm adds  $N$  additions/subtractions in the time domain, which results in addition of 1 bit to the input dynamic range.

An additional reduction of the computing time for real signals is achieved by using:

$$S(N-m) = S^*(m) \quad (5)$$

This indicates that the whole procedure is reduced to computation of the spectrum  $S(m)$  for  $m = N/2$ , and then computation of its conjugate  $S^*(m)$ . Thus,  $N^2/2$  multiplications for computation of  $S(m)$  and  $N/2$  additions for computation of  $S^*(m)$  will complete the procedure. When quadrature channels are used, each channel should be computed separately.

In summary, the shortened DFT algorithm will produce the spectrum after the following computations:

- $N^2/4$  multiplications,
- $N$  complex additions in the time domain and  $N/2$  real additions in the frequency domain.

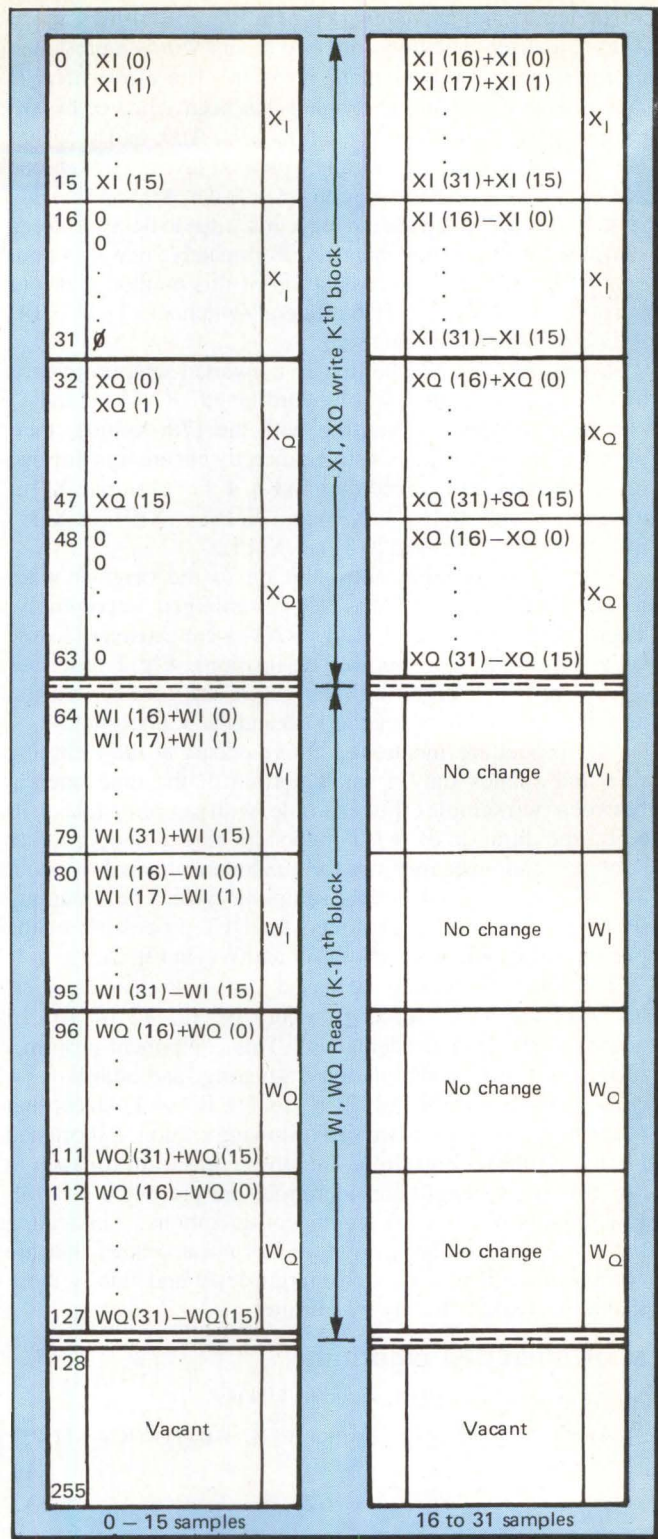


Figure 2: RAM organization (N=32)

### realization of shortened DFT

Realization of a direct DFT filter depends on desired specifications: sampling rate, block length, power dissipation, volume, price etc. The most convenient realization, the serial method, utilizes a multiplier/accumulator and satisfies most typical system requirements — except for the case of very high-sampling-rate systems. It is possible to overcome this shortcoming by paralleling two serial processors for a single channel or four serial processors for quadrature channels.

Fig 1 describes a serial realization of the shortened DFT method. Quadrature video signals  $X_I$  and  $X_Q$  are sampled by



an analog switch and converted by a single ultra-high-speed A/D converter, resulting into two binary words represented in fractional 2s complement notation. The classical A/D conversion of quadrature channels has been achieved by two parallel assemblies each containing S/H, A/D, and a register in series. Although the shortened method saves two S/H, one A/D and two registers, it requires a faster A/D and analog switch in order to reduce the inaccuracy due to delay between samples from the two channels. Fortunately, new components make possible the realization of this method. For our purpose we chose the 4066 bilateral switch and TDC 1014J A/D converter (6 bit, 30 nsec).

Assuming  $N = 32$ , the first 16 converted samples of each block are stored in a 8 bit word-length RAM (I and Q channels separately). Starting with the 17th sample, their binary equivalents are not stored directly but are transformed into new expressions according to Eq. 4. For example,  $X(16)$  transforms into  $X(16) + X(0)$  and  $X(16) - X(0)$ , or  $X(31)$  into  $X(31) + X(15)$  and  $X(31) - X(15)$ .

This transformation adds one bit to the original word length, so the RAM has to be enlarged accordingly. Therefore two 931422 TTL-Ts RAM were chosen (75-nsec access time, 250-mw power dissipation). Fig 2 describes RAM organization during the two phases, between the 1st and the 16th and between the 17th and the 32nd samples.

The procedure mentioned above occurs at the sampling rate and spends only a small portion of the time interval between two samples. For example, with sampling rate of 10 KHz, the duration of A/D conversion, read memory, add or subtract, and write memory for quadrature channels is about 400 nsec, or only 0.4% of the sampling cycle. The remaining 99.6% of the time is exploited for DFT processing of the preceding block of samples ( $W$  and  $W_Q$  in Fig 2).

The processing unit is based on an  $8 \times 8$  multiplier/accumulator TDC 1008J (it could be  $12 \times 12$  or  $16 \times 16$  according to specific demands). This component performs multiplications, accumulations, squaring, and additions ( $A + B = A \times 1 + B \times 1$ ;  $A - B = A \times 1 + B \times (-1)$ ) according to the algorithm described in a following section, "shortened DFT algorithm," resulting in a power spectrum for each  $m$  (A.11). Word length considerations are presented in a following section, "word length considerations," indicating the specific bits that are ignored as noise, others that are compared with a calculated margin level and finally those that are detected directly by a limiter.

### shortened DFT algorithm

Spectral line  $S(m)$  normalized to  $1/N$  is:

$$S(m) = \sum_{r=0}^{N/2-1} \left\{ \exp(-j2\pi mr/N) [X_r + (-1)^m X(r + N/2)] \right\} \quad \text{A1}$$

$$\text{if } Y_r = X_r + (-1)^m X(r + N/2) \quad \text{A2}$$

then quadrature channels are expressed as:

$$Y_r = Y_{Ir} + jY_{Qr} \quad \text{A3}$$

Combining Eq A1 with A3 and substituting the Euler expressions for the exponent we obtain:

$$S(m) = \sum_{r=0}^{N/2-1} Y_{Ir} \cos(2\pi mr/N) + \sum_{r=0}^{N/2-1} Y_{Qr} \sin(2\pi mr/N) + \sum_{r=0}^{N/2-1} Y_{Qr} \cos(2\pi mr/N) - \sum_{r=0}^{N/2-1} Y_{Ir} \sin(2\pi mr/N) \quad \text{A4}$$

$$\text{if: } a = \sum_{r=0}^{N/2-1} Y_{Ir} \cos(2\pi mr/N) \quad \text{A5}$$

$$b = \sum_{r=0}^{N/2-1} Y_{Ir} \sin(2\pi mr/N) \quad \text{A6}$$

$$c = \sum_{r=0}^{N/2-1} Y_{Qr} \cos(2\pi mr/N) \quad \text{A7}$$

$$d = \sum_{r=0}^{N/2-1} Y_{Qr} \sin(2\pi mr/N) \quad \text{A8}$$

$$\text{The real expression will be: } g = a + d \quad \text{A9}$$

$$\text{The imaginary one will be; } h = c - b \quad \text{A10}$$

The final result for the power spectrum will be:

$$PS(m) = g^2 + h^2 \quad \text{A11}$$

### word length consideration

The following explanation will be accompanied by a numerical example based on: number of DFT points per block (32), input dynamic range of quantized video signals (6 bits), noise level of white Gaussian noise ( $\sum \chi_n = 0$ );  $\sigma_{n=1}$  LSB and coefficient accuracy (for  $m = 32$ ) (5 bits).

According to the SDFT algorithm, quantized input signals are processed to obtain new 7-bit-long expressions. The result is a 12-bit word. Accumulator of 32 multiplications adds to the result 5 bits at the most. In order to avoid truncation, a 17 bit word is needed. Assuming the noise level of 1 LSB is accumulated according to  $N^{0.5}$  law, at the end of the process the noise level will reach the 9th bit out of the 17th result.

Calculations of  $g$ ,  $h$  (see the previous section), their squares and the  $PS(m)$ , are performed while ignoring 8 LSB (which are considered noise). Thus, if the processing unit is based on an  $8 \times 8$  multiplier accumulator, only bits 9 to 16 are considered for obtaining  $PS(m)$ . The 1 MSB indicates immediately existence of a signal for the proper  $m$ .

### calculation time

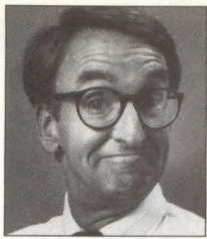
Calculation time of 32 points DFT processor based on the shortened algorithm is based on the following data:  $Q$  (quadrature) = 2, TSW (switch on) = 200 ns, TAD (A/D conversion) = 30 ns, TWR (write RAM) = 75 ns, TRR (read RAM) = 75 ns, TLS (LS-TTL operation) = 30 ns, TAP (read PROM) = 125 ns and TMA (multiply/accumulate) = 125 ns.

Duration of sampling, A/D conversion, additions and writing in RAM on 32 quadrature input signals:  $(N/2)(TSW + Q(TAD + TWR)) + (N/2)(TSW + Q(TAD + TRR + TLS + TWR)) = 16.5 \mu s$ . Multiplication/accumulation time of a complete block:  $4[(N/2)^2(TAP + TMA) + TLS] = 256 \mu s$ .  $PS(m)$  calculation time of 32 spectral lines:  $(2N/2)(2 \times 2 \times (TLS + TMA) + TLS + TMA) = 24.8 \mu s$ . Total calculation time is approximately 300  $\mu s$ ; and maximum sampling rate, 100 KHz. D

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- (2) S. Winograd, "On Computing the DFT", *Proc. nat. Acad. Sci., USA*, Vol. 73, Apr. 1976.
- (3) S. Winograd, "A new Method for computing DFT", *Proc. IEEE Int. Conf. Acoust., Speech, Signal Proc.*, 1977.
- (4) H.J. Nussbaumer, P. Quandale, "Fast Computation of DFT Using Polynomial Transforms", *IEEE Trans-on Acoust., Speech, Signal Proc.*, Vol. Asst 27, Apr. 1979.





Barney Stevenson just spent two years programming and de-bugging a process control system in assembly code.

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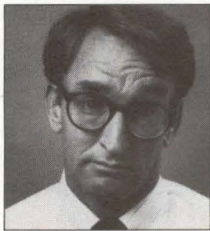
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# Microprogrammable Processor

## single-bit storage concept

**T**he single bit storage concept is adaptable and may be varied to meet systems requirements. Expanding bit storage is an efficient method, and permits a doubling of total data bits stored for each added bit of microcode. The ease of enable control circuitry modification, which changes the division between latches assignable to status bits only, (or to either status or flag bits,) permits rationalization of system requirements and design implementation.

by Alan W. Bentley

This design illustrates the principle of simultaneous and rapid processing. On a given microcode instruction, one flag status bit may be modified while several other bits may be referenced by different sectors of the microcode which are performing independent functions. Finally, latches differ from edgetriggered-storage devices as the latch-enable activates input gates, permitting track of D input during enable time.

At enable completion, the latch stores the last internally propagated input. Therefore, because the latch is enabled during the second half of the clock period, the latch input stabilization time is maximized to permit proper status storage. Specific instructions, however, may have long execution times.

Although instruction driven microprocessors fulfill the majority of processing applications, the high capability portion of the performance spectrum is dominated by microprogrammable processors. This follows from their architectural differences. An instruction driven microprocessor is a serial device with a fixed architecture and a given repertoire of instructions. Its performance is limited by the necessity of sequentially executing those instructions. Its operating modes are relatively inflexible and it is difficult to adapt either the instruction set or the architecture to increase performance. Conversely, the microprogrammable organization is more flexible. It is packaged as vertical slices

through a register array, arithmetic and logic unit, instruction decoding and execution logic and connecting paths.

Interconnecting slices establishes bit widths of the data word and processing unit. To support and control the processing unit, additional hardware is added and microcode instruction control is implemented. Processor performance is improved by increasing the number of tasks that may be performed simultaneously. This is achieved by expanding the support hardware and the microcode, obtaining a finer division of tasks and an increased capability to manipulate control and enable lines. Thus, the increased performance of a microprogrammable processor system is due to its organization which permits a number of tasks to be performed simultaneously.

### single bit storage concept

In microprogrammable processor design, microcode controlled storage for status and flag bits must be provided. An approach has been developed that uses both microcode and hardware efficiently, and is adaptable, so it may fulfill varying system requirements. An 8-bit multiplexer (LS151) and an 8-bit addressable latch (LS259) perform the data selection and storage functions, controlled by 4 bits of microcode. The lower three bits of microcode ( $2^0 - 2^2$ ) address both the multiplexer and the latch, the upper code bit,  $2^3$ , is used as a multiplexer strobe and when true, drives its output false. Also, the upper two code bits,  $2^2$  and  $2^3$ , when both true, suppress the latch enable. This divides the microcode word into three sectors;  $0_{16}$  through  $7_{16}$  stores the

*(text continued on page 33)*

Alan W. Bentley is from Cubic Corp, of the Defense Systems Div. in San Diego, CA.



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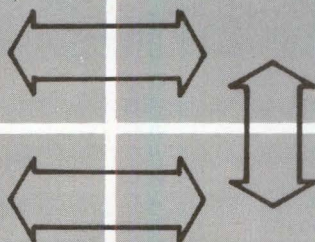
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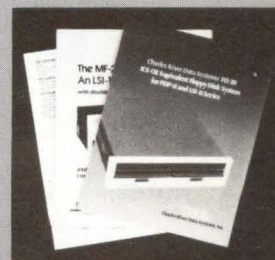
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# CRDS



| Usage Assignment | Multiplexer Input | Connection  | Output Latch   | Microcode Flag Set | Reset | Status Storage |
|------------------|-------------------|-------------|----------------|--------------------|-------|----------------|
| Flag 0           | D0                | VCC         | Q <sub>0</sub> | 0                  | 8     |                |
| Flag 1           | D1                | VCC         | Q <sub>1</sub> | 1                  | 9     |                |
| Flag 2           | D2                | VCC         | Q <sub>2</sub> | 2                  | A     |                |
| Status A         | D3                | Parameter A | Q <sub>3</sub> |                    |       | 3              |
| Status B         | D4                | Parameter B | Q <sub>4</sub> |                    |       | 4              |
| Status C         | D5                | Parameter C | Q <sub>5</sub> |                    |       | 5              |
| Status D         | D6                | Parameter D | Q <sub>6</sub> |                    |       | 6              |
| Status E         | D7                | Parameter E | Q <sub>7</sub> |                    |       | 7              |

**NOTES**

1. Microcode B<sub>16</sub> illegal — use unconditionally resets Q<sub>3</sub>, status a latch
2. Microcodes C<sub>16</sub> - F<sub>160</sub> surpass latch Enable input

**Table 1: Microcode and input assignment for typical 8 bit storage application.**

| Usage Assignment | Multiplexer Input | Connection  | Output Latch | Microcode Flag Set | Reset | Status Storage |
|------------------|-------------------|-------------|--------------|--------------------|-------|----------------|
| Flag 0           | D0                | VCC         | 0            | 0                  | 10    |                |
| Flag 1           | D1                | VCC         | 1            | 1                  | 11    |                |
| Flag 2           | D2                | VCC         | 2            | 2                  | 12    |                |
| Flag 3           | D3                | VCC         | 3            | 3                  | 13    |                |
| Flag 4           | D4                | VCC         | 4            | 4                  | 14    |                |
| Flag 5           | D5                | VCC         | 5            | 5                  | 15    |                |
| Status A         | D6                | Parameter A | 6            |                    |       | 6              |
| Status B         | D7                | Parameter B | 7            |                    |       | 7              |
| Status C         | D0                | Parameter C | 8            |                    |       | 20             |
| Status D         | D1                | Parameter D | 9            |                    |       | 21             |
| Status E         | D2                | Parameter E | 10           |                    |       | 22             |
| Status F         | D3                | Parameter F | 11           |                    |       | 23             |
| Status G         | D4                | Parameter G | 12           |                    |       | 24             |
| Status H         | D5                | Parameter H | 13           |                    |       | 25             |
| Status I         | D6                | Parameter I | 14           |                    |       | 26             |
| Status J         | D7                | Parameter J | 15           |                    |       | 27             |

**NOTE**

1. Microcode 16<sub>8</sub> + 17<sub>8</sub> illegal, use unconditionally resets if its 6 and 7 respectively
2. Microcodes 30<sub>8</sub> - 37<sub>8</sub> suppress latch Enable input

**Table 2: Microcode and input assignments for a 16 bit application with 6 status bits, that are handled by one multiplexer. For flag bits 0 through 7, the 2<sup>3</sup> bit is the octal latch D input, requiring that the flag bit set and reset microcode be reversed from those in Table 2.**

| Microcode                         | Enable Equations                                       | Use                         | Remarks  |
|-----------------------------------|--|-----------------------------|--|
| 00 <sub>8</sub> - 17 <sub>8</sub> | $\text{Clock} \cdot 2^5 \cdot 2^4$                     | Flag Only<br>Flag or Status | Set 10 <sub>8</sub> - 17 <sub>8</sub> , Reset 00 <sub>8</sub> - 07 <sub>8</sub><br>Multiplexer Input 00 <sub>8</sub> - 07 <sub>8</sub> , Low Input 10 <sub>8</sub> - 17 <sub>8</sub> |
| 20 <sub>8</sub> - 37 <sub>8</sub> | $\text{Clock} \cdot 2^5 \cdot 2^4$                     | Flag Only<br>Flag or Status | Set 30 <sub>8</sub> - 37 <sub>8</sub> , Reset 20 <sub>8</sub> - 27 <sub>8</sub><br>Multiplexer Input 20 - 27 <sub>8</sub> , Low Input 30 <sub>8</sub> - 37 <sub>8</sub>              |
| 40 <sub>8</sub> - 57 <sub>8</sub> | $\text{Clock} \cdot 2^5 \cdot 2^4$                     | Flag Only<br>Flag or Status | Set 50 <sub>8</sub> - 57 <sub>8</sub> , Reset 40 <sub>8</sub> - 47 <sub>8</sub><br>Multiplexer Input 40 <sub>8</sub> - 47 <sub>8</sub> , Low Input 50 <sub>8</sub> - 57 <sub>8</sub> |
| 60 <sub>8</sub> - 77 <sub>8</sub> | $\text{Clock} \cdot 2^5 \cdot 2^4$                     | Status Only                 | Multiplexer Input 60 <sub>8</sub> - 67 <sub>8</sub><br>Enable Supressed 70 <sub>8</sub> - 77 <sub>8</sub>  |
|                                   | $\text{Clock} \cdot 2^5 \cdot 2^4 \cdot 2^3 \cdot 2^2$ | Status or Flag              | Q <sub>0</sub> - Q <sub>3</sub> Status of Flag Use<br>Q <sub>4</sub> - Q <sub>7</sub> Status Use Only<br>Enable Supressed 74 <sub>8</sub> - 77 <sub>8</sub>                          |

**NOTES:**

1. Three latches may be assigned flag only or flag or status use, corresponding multiplexer only requires in later case.
2. If flag only, the latch D input is microcode 2<sup>3</sup> bit, if flag or status the same input is multiplexer Y output.
3. One latch normally assigned status use only, alternate enable equation and configuration shown if assigned to status or flag use

**Table 3: Expansion to 32 bits of storage. For each octal latch, shown is its enable equation and its microcode assignment.**



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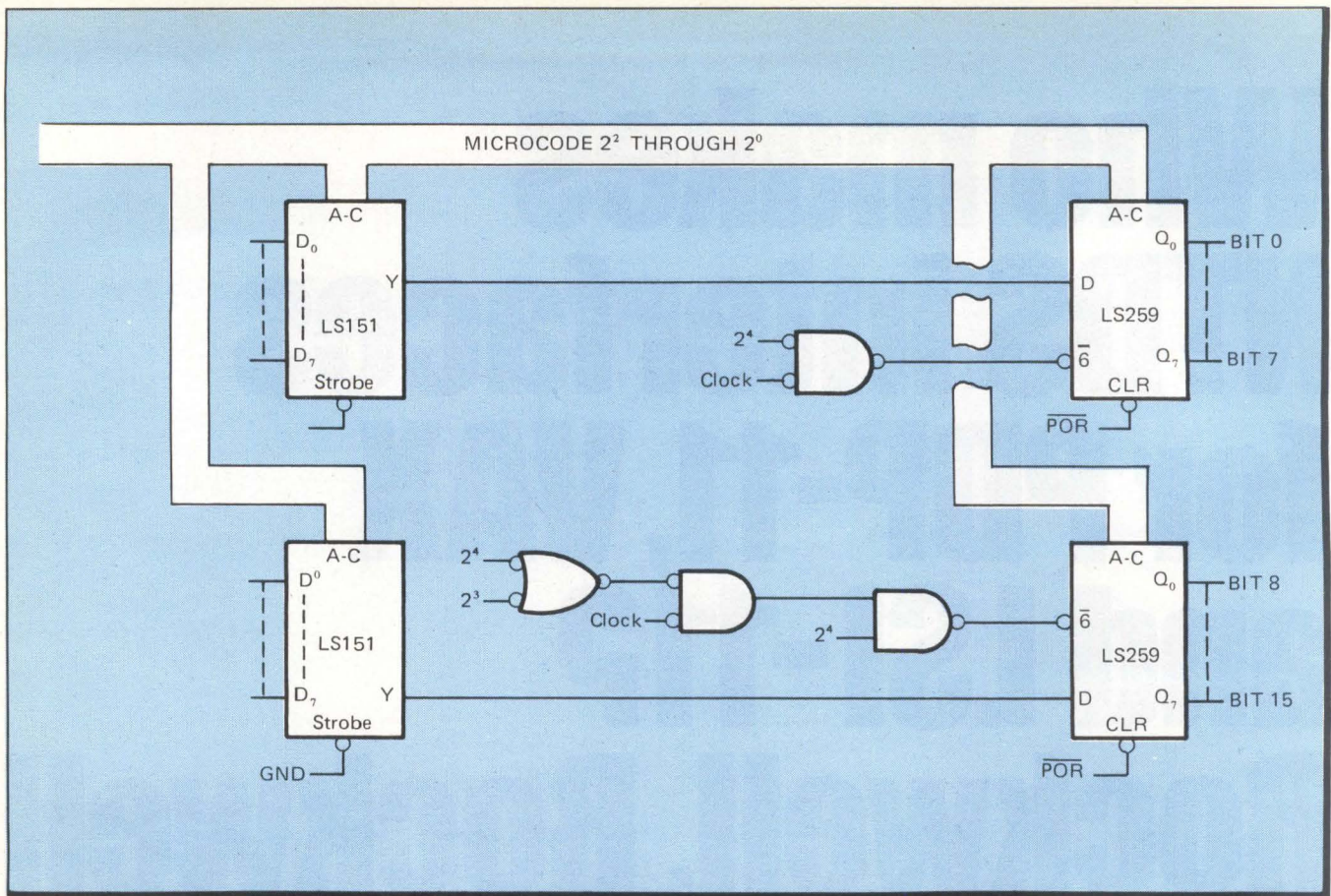
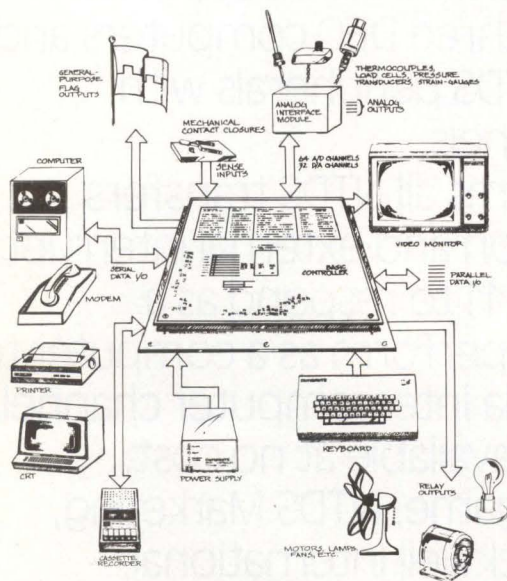


Figure 1: Sixteen bit storage with 8 or fewer status bits. Parameter selection performed by single multiplexer.

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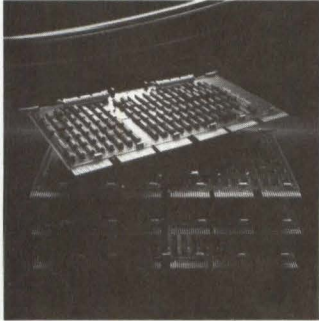
Circle 21 on Reader Inquiry Card



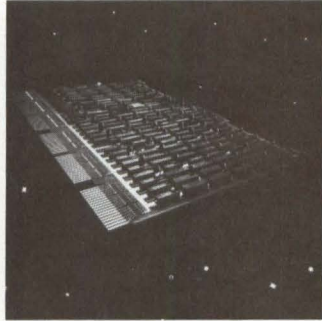
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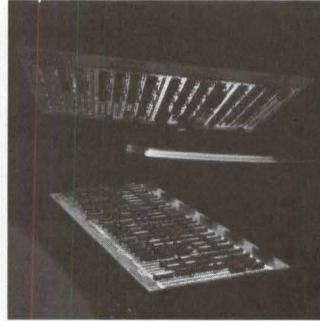
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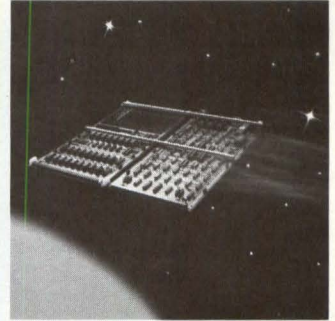
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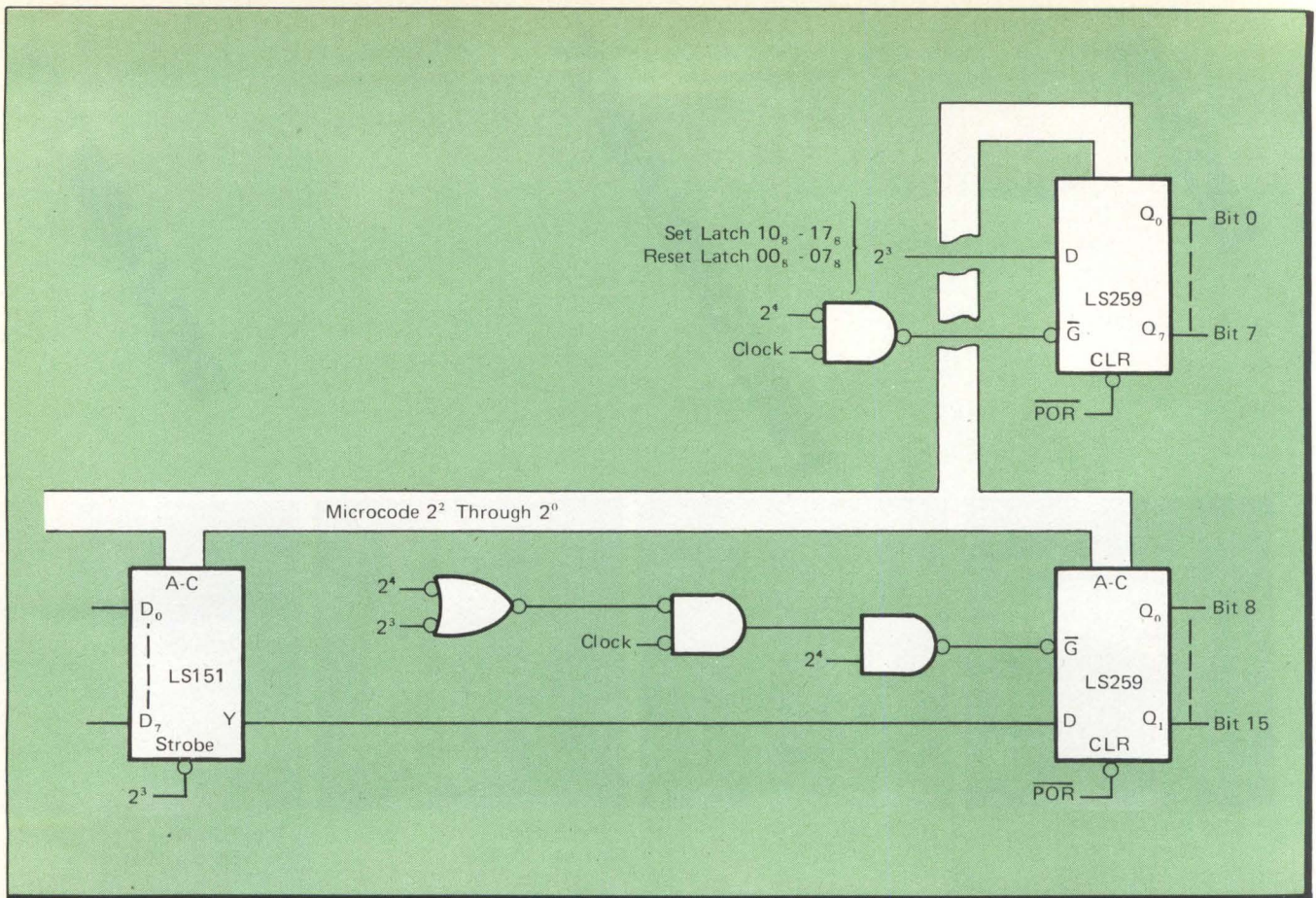


Figure 2: Sixteen bit storage handling more than 8 status bits. Two multiplexers are needed to provide adequate parameter selection.

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(text continued from page 26)

logic level of the addressed multiplexer input in the corresponding latch,  $8_{16}$  through  $B_{16}$  cause the multiplexer output to be false, resetting latches 0 through 3 respectively, and  $C_{16}$  through  $F_{16}$  suppresses the latch ENABLE command, leaving the latched outputs unchanged.

During systems operation, there are two categories of single bit information that must be stored for later use, they are the status and flag bits. Status bits are associated with specific parameters and store their values when programmed. Examples of such parameters are: sign bit, carry out bit and the result of a register equal zero test. Conversely, flag bits are not associated with specific parameters, rather they may be programmed set or reset, and system requirements determine their definition. Therefore, to store a status bit only one microcode is required, the parameter is routed from the corresponding multiplexer input and the coded latch stores the digital value. Flag bits require both a setting and resetting microcode, which are formed by code pairs differing by the  $2^3$  bit. If the  $2^3$  bit is false, the multiplexer input, tied to  $V_{CC}$ , sets the addressed latch. If it is true, the multiplexer strobe input causes the multiplexer output to be false, resetting the latch. Thus, if the multiplexer D1 input is tied to  $V_{CC}$ , microcoding  $1_{16}$  sets  $Q_1$  and  $9_{16}$  resets  $Q_1$ .

When assigning microcodes and multiplexer inputs, codes  $C_{16}$  through  $F_{16}$  suppress the latch ENABLE command. Codes  $4_{16}$  through  $7_{16}$  control latches  $Q_4$  through  $Q_7$  respectively and must be assigned as status bits. Codes  $0_{16}$  through  $3_{16}$  paired with  $8_{16}$  through  $B_{16}$  control  $Q_0$  through  $Q_3$  and may be assigned as either status or flag bits. Table 1 shows a typical application, that requires 3 flag and 5 status bits. Shown for each bit is its assignment, multiplexer input, controlling microcode and latch output. Typically, the required number of status bits exceeds the number of flag bits. The division of 4 status bits and 4 bits assignable to either the status or flag category is satisfactory. If not, by expanding the input gate of the ENABLE circuitry to include the  $2^1$  microcode bit, the microcodes that inhibit ENABLE are reduced to  $E_{16}$  and  $F_{16}$ . The latches assigned to status bit only are reduced to  $Q_6$  &  $Q_7$ . The remaining 6 latches may be assigned to either the status or flag category.

### storage expansion

The flexibility of this approach allows expansion, if additional bit storage is required. Generally, each bit added to the microcode doubles the capability of storing status or flag bits, and to implement this capability, multiplexers and octal latches are added in equal numbers. However, if a latch is used to store flag bits only, its corresponding multiplexer is not required, for with proper address assignments, a microcode bit can supply the D input to the flag latches.

For expansion to 16 bits of storage with more than 8 status bits required, the hardware configuration is shown in **Figure 1** with the input connections and coding shown for a typical assignment in **Table 2**. If 8 or fewer status bits are required, the reduced hardware configuration of **Figure 2** may be used. Three variations of the ENABLE equation are shown; with the enable inhibit gate progressively expanded, to reduce both the microcode combinations that are inhibited and the number of latches committed to status bit use only. Thus, the implemented latches are divided between the two categories by adjusting the ENABLE equation.

Controlling four octal latches with a 6 bit microcode illustrates the principle of expansion. Table 3 shows each latch's specific design information, and alternate configurations that permit design optimization. D

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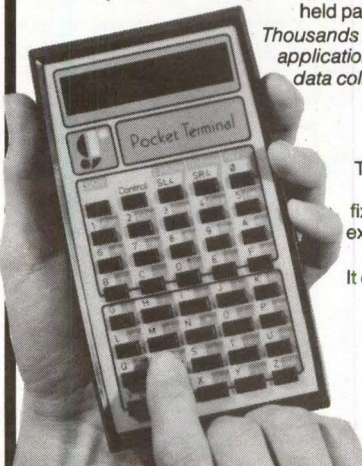
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# GCR Increases

## data recording rates and reliability

**G**roup-coded recording (GCR) of data onto magnetic tape has been around for a number of years. IBM first announced it in 1973. Even though GCR increased data recording rates and reliability, most manufacturers originally stayed out of the GCR race. They felt that improved tape rate and reliability would prove unnecessary, because other storage media (such as disk) might push tape aside. They were wrong: the GCR tape market, \$3.5 billion four years ago, should reach three times that in 1981-82. Today, over 70% of large computer systems installed in the U.S. utilize GCR-equipped tape subsystems.

Why this dramatic growth? The reason: tape remains the least expensive medium for data storage — approximately one-tenth the cost of disk. It is the only legal electronic means of archiving data, and is the most interchangeable medium.

Designing faster tape drives did not appear to be a solution for improving tape-subsystem performance, because electromechanical limitations make speeds above 250 ips impractical. The alternative (putting more data on the same amount of tape by increasing flux density) seemed more practical. However, increased density called for improved methods for detecting and correcting errors in the data.

by Mike Newton

Non-return to zero (NRZI) recording, the earliest method, writes 800 bits of information per inch of tape. Magnetically, NRZI relies on a flux change in the oxide coating of the tape to indicate a '1' bit of information, while the absence of a flux change signifies a '0'. Because NRZI requires one flux change for one bit of information, the format provides 100% recording efficiency. Unfortunately, mechanical skew considerations limit NRZI density to the 800 bpi range, and the format cannot correct errors.

Phase encoding (PE), which uses a self-clocking approach, was next developed to overcome the deficiencies of NRZI. Like NRZI, PE records nine tracks on the tape. However, it records the '1' and '0' bits via a flux change — the difference between the two bits depends on direction of flux change. PE suffers from the drawback of needing at least one flux change per bit. Two like bits in succession require a second flux change at the boundary between the cell bits. This flux allows write current to return to a state from which it can write a flux change in the same direction as flux change of the preceding bit of information. Thus, PE can require as many as two flux changes per bit of information that give it a recording efficiency of 50%.

At least one flux change occurs per bit cell in PE. The technique benefits from the fact that each of the nine tracks can have its own clocked detection circuit. This circuit will have a variable-frequency clock running in a phase-locked loop with data on the track. With a clocking circuit monitoring each track, added hardware can sense flux

Mike Newton is from Storage Technology Corp.

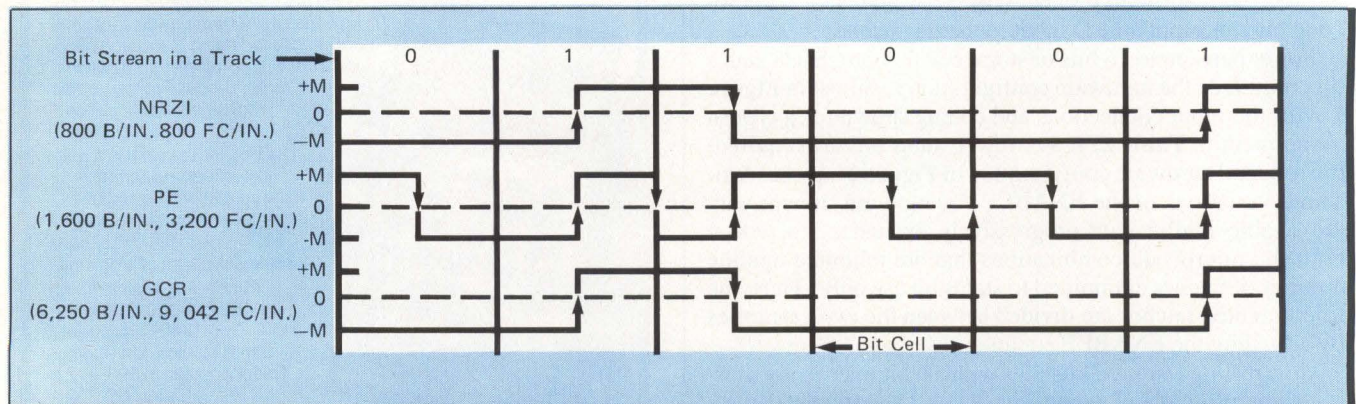


Figure 1: Flux change patterns shows that NRZI recording uses a flux change for a logic 1 and no flux change for a 0; PE recording uses a flux change for 1s and 0s; GCR, like PE, uses a flux change for the binary numbers, the data is coded before recording.



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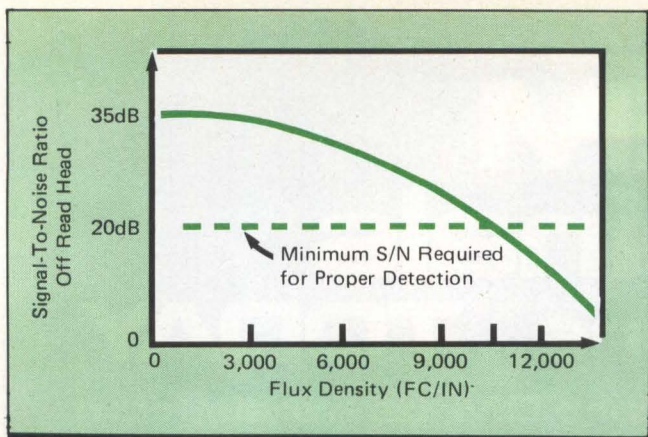


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**Figure 2: Signal-to-noise ratio at the read head depends upon the closeness of the flux change on the tape. GCR, which operates at a flux density of 9000 flux changes/inch (fc/in.), provides an S/N above the minimum needed for reliable information.**

change amplitude and position within each bit cell. Detection of either of these two conditions occurring outside normal parameters indicates erroneous data within a specific track. Byte-by-byte parity checking can further pinpoint the incorrect bit or bits within that track and correct errors on the fly. However, in any given data record, only single-track error correction is possible via these safeguards.

Since the independent clock of each of the nine tracks virtually frees PE from skewing problems experienced with NRZI, it allows PE recording at 1600-bpi density. It is possible to use PE at higher densities, but the increased frequency of flux changes begins to cause an unacceptable signal-to-noise ratio. Also, dual-track error correction — not provided for by PE — becomes important at higher densities.

### what is GCR?

Very simply, GCR is a recording format that takes advantage of the efficiency of NRZI while implementing the clocking procedures of PE. Aided by a sophisticated approach to error correction, GCR has resulted in a 6250-bpi recording density, plus a dual-track error detection and correction capability. The 6250 density was selected, because 6250 bpi processed at 200 ips equals 1.25 Mbytes/sec., which is a data rate compatible with many of today's high-performance computer channels.

### how does it work?

Like its predecessors, GCR records on nine tracks. Basically, it uses the NRZI convention: a flux change represents a '1' bit of information, while the absence of a flux change indicates a '0' bit. However, it requires a modification. Originally, a NRZI recorder utilized no clocking system, and it could write a string of '0' bits, represented by a series of bit cells with no flux change. Incorporating a clocking system into the GCR approach eliminated this capability, since periodic flux transitions are necessary to ensure the synchronization of the clocks on the nine tracks. Essentially, GCR can write no more than two '0' bits consecutively.

This is where the term "group-coded" comes in. Before the GCR system records the information, it collects the data in an eight-byte buffer. The tape controller adds seven data bytes and an eighth byte for error checking and correcting information. This function produces an eight-byte data group. Although the information comes in broadside (byte-serial) from the CPU, it is coded bit-serially in subgroups of four bytes.

For clarity, let's number the bits in each byte, #1 through

#9. The translator receives data bits four at a time, and converts the four #1 bits into a five-bit code character, the four #2 bits into a five-bit code character, and so on down through the four #9 bits. The resulting nine five-bit characters are then recorded onto tape. Thus, each eight-byte data group is recorded as a ten-byte storage group. For retrieval, the process is reversed. The four-to-five translation scheme was devised to provide a five-bit storage subgroup that, for each four-bit data subgroup, contains no more than two consecutive '0' bits and no more than one '0' bit on either end. This scheme insures that no recorded track will ever contain more than two consecutive bit cells without a flux transition.

### error detection and correction

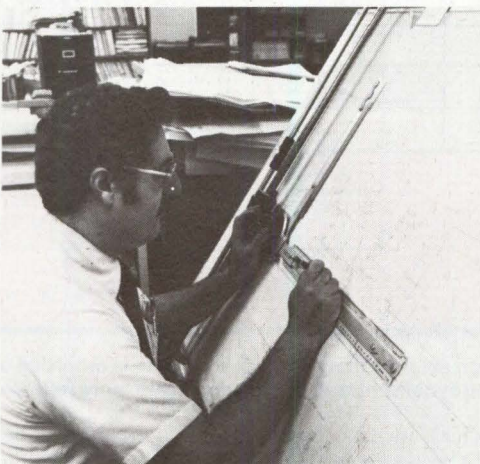
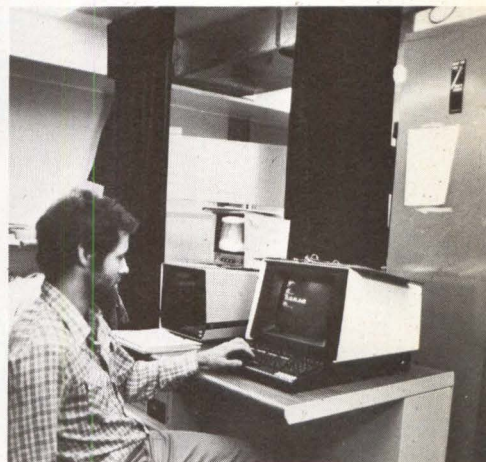
PE error-correction system provides single-track error correction. The more extensive GCR approach utilizes a system of cyclic codes recorded with the data. GCR uses the same hardware as PE — amplitude sensing (noting the fluctuations in flux-change amplitude) and phase error (checking the exactness of the flux location within the bit cell) — to give the system its multiple-bit error-correction ability.

The error-checking and correcting (ECC) byte of information (attached to the data subgroup in the buffer prior to encoding) is generated by a polynomial as described in ANSI spec  $\times 3.54$ ). This polynomial is based on the 56 bits of information that make up the data group. Thus, a direct mathematical relationship exists between construction of the ECC byte and all data from which it is generated. When the data is read back, control hardware reworks the polynomial generation and checks the resulting error-correction byte against the ECC byte originally written. If a discrepancy occurs, it can be used to calculate exact position of the erroneous bit or bits within the data group. Although this technique can correct only single-bit errors, amplitude sensing and phase error checking can correct multiple-bit errors.

| 4-Bit Data Value | 5-Bit Recording Value |
|------------------|-----------------------|
| 0000             | 11001                 |
| 0001             | 11011                 |
| 0010             | 10010                 |
| 0011             | 10011                 |
| 0100             | 11101                 |
| 0101             | 11010                 |
| 0110             | 10110                 |
| 0111             | 10111                 |
| 1000             | 11010                 |
| 1001             | 01001                 |
| 1010             | 01010                 |
| 1011             | 01011                 |
| 1100             | 11110                 |
| 1101             | 01101                 |
| 1110             | 01110                 |
| 1111             | 01111                 |

**Figure 3: Group coding starts with the data entering the controller from the CPU in byte-serial order. The data bytes are stacked in the controller buffer. An error-correcting code (ECC) byte is generated by, and added to, every 7 data bytes to make an 8-byte data group. The translator converts the data into storage code. This process is bit-serial in which each 4-bit data subgroup is assigned a 5-bit storage code. See Figure 4 for a more detailed explanation.**





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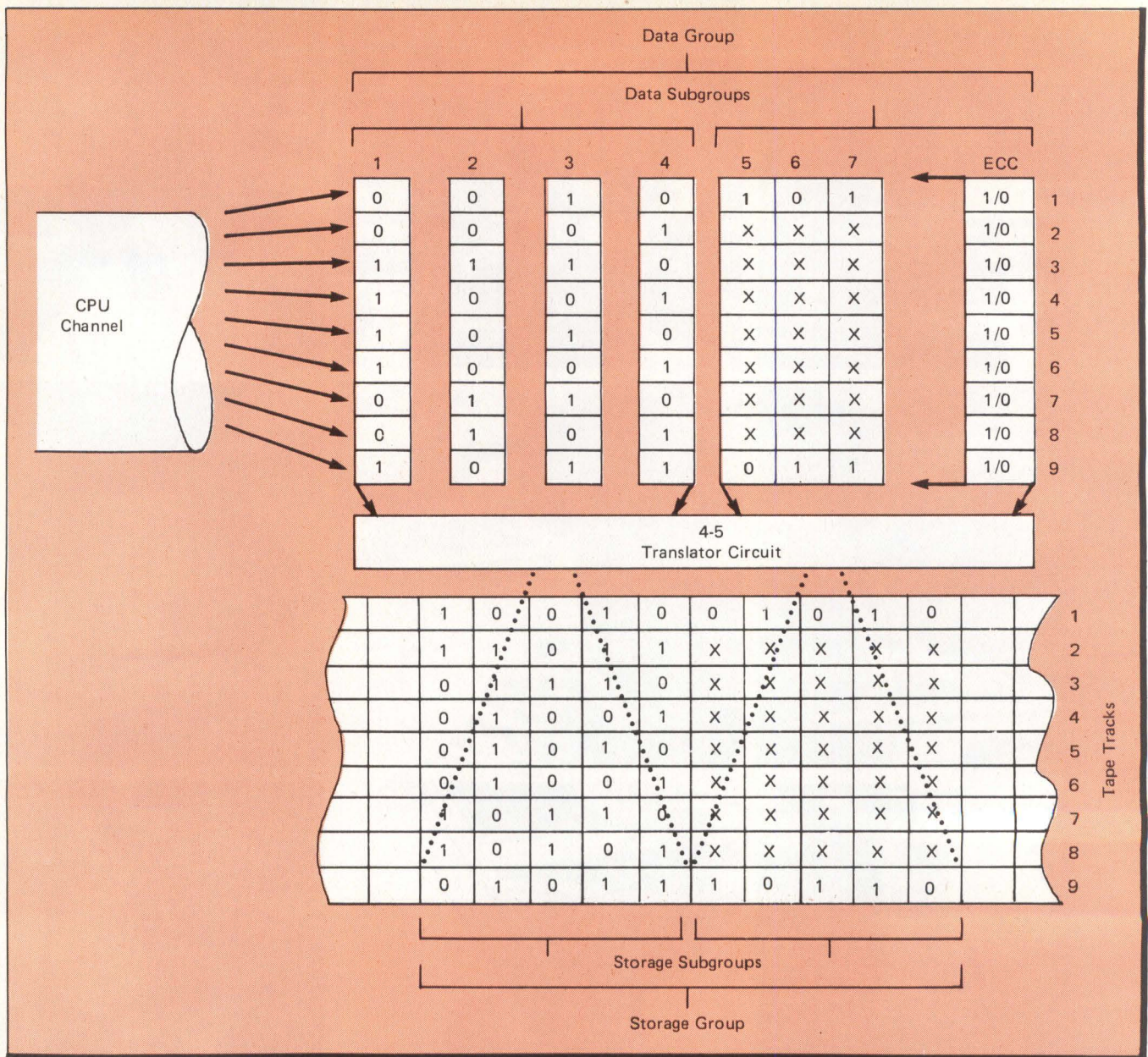


Figure 4: The four-to-five GCR translation scheme insures that, when data is recorded on the tape, no more than two successive zeros appear on any track. This scheme makes synchronization of the read head more reliable.

Two additional error check characters, incorporated into each storage record, supplement the GCR error detection and correction systems. A polynomial, defined by ANSI specs, generates the AuxCRC (auxiliary cyclic redundancy character). A different polynomial, based on all the data, plus the pad bytes (inserted after the residual customer data bytes to fill out the last storage group) and the AuxCRC itself

generates. The AuxCRC and the CRC are generated in a manner similar to the ECC, and provide a final check to insure the integrity of the data after it is read. These characters do not locate or correct errors, but simply indicate that an error or errors exist. Whenever that happens, the computer is automatically alerted to switch to retry procedures.

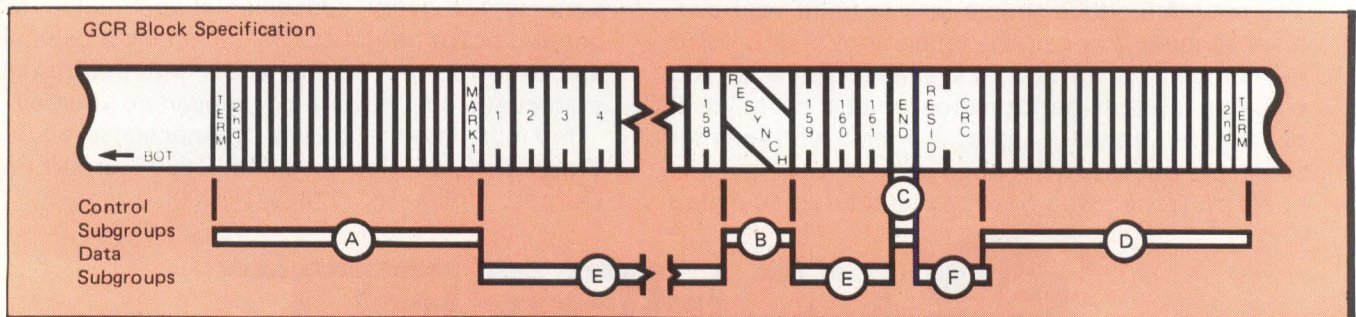


Figure 5: GCR group consists of preamble (A), resync burst (B), end mark (C), postamble (D), storage groups (E), and residual and GCR groups. (F).



## resynchronization

Amplitude sensing, used with GCR to allow multiple-bit, double-track error correction, works the same way with GCR as it does with PE recording. When an erroneous bit is sensed, the dead-track register causes faulty track shut down. This action could create a real problem in GCR, since long data blocks are desirable to optimize the advantages of GCR's increased density and to avoid devoting too much tape space to interblock gaps. It is obviously unsatisfactory for one or perhaps two tracks to shut down for the duration of a record of that length. Consequently, the GCR format provides an opportunity to reset the dead-track register. It also resynchronizes the read detection circuits during recording by writing a resync burst in all tracks after every 158 data groups, provided that at least one more data group remains to be written. The resync burst consists of a Mark 1 subgroup, ten '1'-bit bytes, and a Mark 2 subgroup. The burst is unique and automatically triggers resynchronization of the nine read detection circuits. Because error probability relates directly to record length, and since resynchronization occurs after every 1,106 data bytes, the inclusion of this precaution reduces the probability of an uncorrectable error in an 8000-byte data block by a factor of almost seven.

## the GCR data block

So far, we've discussed data groups, AuxCRCs, CRCs and resync bursts. Next we will discuss the other components that make up a GCR data block and their assembly on tape.

**The Preamble.** Just as PE does, the GCR record begins with a block of information designed to alert the amplitude sensors of the beginning of a block, and to synchronize the read-detection clock for each tape track. The preamble consists of a term subgroup and a secondary subgroup. These subgroups announce the beginning of a data block, followed by 14 subgroups made up entirely of '1' bits which allow the read-detection circuits to synchronize. A Mark 1 subgroup ends the preamble.

**Storage Groups.** Groups of coded data are then written on the tape. Each group consists of 10 bytes. When decoded, the 10 storage bytes are reconverted back into seven bytes of data and the ECC byte.

**Resync Burst.** After each 158 storage groups (data), a written resynch burst resets the dead-tracking circuits and brings the read-detection circuits back into sync.

**End Mark.** When the system has finished writing all the storage groups (data), it writes End Mark on all tracks.

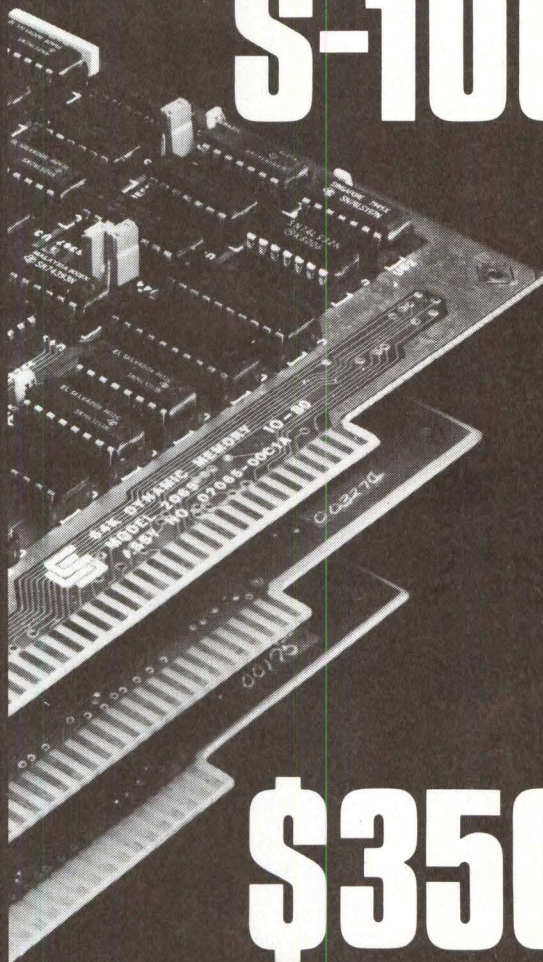
**Residual Group.** Each group contains (prior to coding) eight bytes of information (7 data + ECC). Therefore, if after the system has coded and written all data groups, fewer than seven bytes of customer data remain, they are written into the residual group. The system then fills the group up with pad bytes of zeros, plus an AuxCRC byte and an ECC byte.

**CRC Data Group.** Next, the system writes a CRC group containing the CRC bytes and the residual count byte. The count byte describes the number of actual data bytes vs. pad bytes in the preceding residual group. Five or 6 CRC bytes (all identical) plus an ECC byte make up the CRC group prior to conversion by coding into a 10-byte storage group.

**The Postamble.** A mirror image of the preamble, the postamble which finishes the record contains a Mark 2 subgroup (the reverse of a Mark 1), 14 subgroups made up entirely of '1' bits, a secondary character and a term character.

We've seen how GCR provides nearly error-free storage of information at low cost. Keep these fundamentals in mind when selecting tape storage subsystems. **D**

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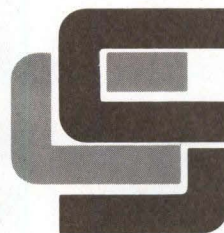


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The prices listed are only representative and may not represent the highest or lowest prices available. In general, prices for processors tend to represent smallest configurations with minimum memory. Where a system price only is available, this is noted with "(sys)." For peripherals, generally the controller is not included in the price. These prices represent typical United States prices and may vary in other countries. Unless otherwise noted, all prices are representative single-unit prices.

Next month's issue will complement this issue by providing a computer compatible directory. This month's DEC directory and next month's computer compatible directory are the first of their kind. Make sure to save them, they will be valuable for future reference in the upcoming year.

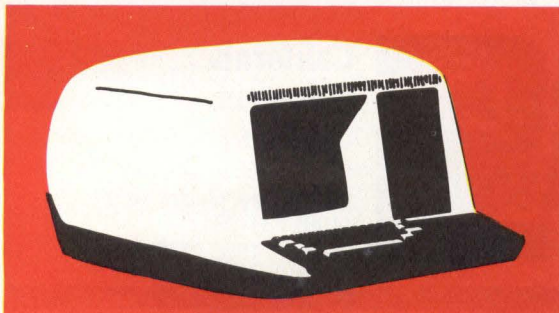
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## minicomputers

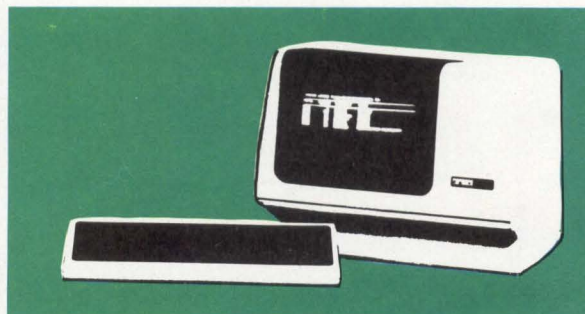
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## super-minicomputers

**VAX-11/750. Entry-level super-minicomputer.** Wordlength — 32 bits. Maximum memory 2 MB. Uses ECC MOS memory. Can employ UNIBUS and MASSBUS. 4 KB cache memory standard. **\$89,900 (sys).**

**VAX-11/780. Top-of-the-line superminicomputer.** Wordlength — 32 bits. Maximum memory 8 MB (except for multiport configurations where an additional 4 MB can be used). Can employ UNIBUS and MASSBUS. Floating-point processor is available as option. **\$128,000.**

## mainframes

**DECsystem-1090 Mainframe.** Wordlength — 36 bits. Maximum memory 18 MB. Uses core memory. 2-Kword cache memory standard. **\$639,800.**

**DECsystem-1091 Mainframe.** Wordlength — 36 bits. Maximum memory 13.5 MB. Uses MOS memory. 2 K word cache memory standard. **\$476,000.**

**DECSYSTEM-2020 Entry-level mainframe.** Wordlength — 36 bits. Maximum memory 2.3 MB. Uses MOS memory. 512-word cache memory standard. **\$168,500.**

**DECSYSTEM-2040 Mainframe.** Wordlength — 36 bits. Maximum memory 9 MB. Uses MOS memory. **\$357,100.**

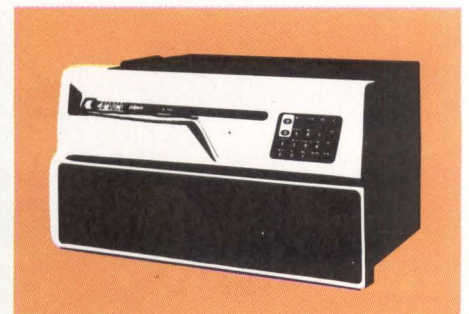
## Storage Peripherals

### disks

**RX01 Front-loading Diskette.** Capacity per drive: 0.25 Mb. Drives per controller: 2. Average access time: 180 ms (seek) 8.3 ms (latency). Peak transfer rate 62 Kb/sec. Uses floppy technology. Processors supported: PDP-8/A, DECstation, LSI-11/2, LSI-11/23, PDP-11/03, PDP-11/23, PDP-11/24, PDP-11/34A, PDP-11/44, PDP-11/70, VAX-11/780. **\$3,600.**

**RX02 Front-loading Diskette.** Capacity per drive: 0.5 Mb. Drives per controller: 2. Average access time: 180 ms (seek) 8.3 ms (latency). Peak transfer rate 62 Kb/sec. Uses floppy technology. Processors supported: PDP-8/A, DECstation, LSI-11/2, LSI-11/23, PDP-11/03, PDP-11/23, PDP-11/24, PDP-11/34A, PDP-11/44, PDP-11/70, VAX-11/750, VAX-11/780. **\$4,150.**

**RL01 Top-loading cartridge.** Capacity per drive: 5.2 Mb. Drives per controller: 4. Average access time: 55 ms (seek) 12.5 ms (latency). Peak transfer rate 512 Kb/sec. Uses 3330 technology. Processors supported: PDP-8/A, LSI-11/2, LSI-11/23, PDP-11/03, PDP-11/23, PDP-11/24, PDP-





# COMPAT '81

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Please read carefully. Fill in form completely. Use envelope if enclosing remittances. Deadline for returning pre-registration August 1, 1981. Later registration must be done at Registration Desk at the Exposition.

I. For which of the CPU's listed below do you plan to purchase computer compatible products and/or services?

- Data General                     Hewlett-Packard                     Intel                     Perkin Elmer  
 Digital Equipment Corp.                     IBM                     Motorola                     Other \_\_\_\_\_

II. For the CPU's you have checked, what types of plug compatible products do you specify or purchase?

A. Computers/Controllers

- Programmable Controllers  
 Single Board Computers/Chips

B. Data Terminals

- Alphanumeric Display Terminals  
 Graphic Terminals  
 Programmable/Intelligent Terminals

C. Memory

- Add-in and Add-on Memory Systems  
 Bubble Memory Systems  
 Semiconductor Memory (RAM/ROM, etc.)

D. Mass Storage/Drives

- Disk Pack/Removable Cartridge  
 Fixed Disk/Large  
 Floppy Disk  
 Magnetic Tape

Tape Cassette/Cartridge

- Winchester Drives

E. Printers/Plotters

- CRT Display Copiers/Printers  
 Line Printers  
 Plotters  
 Serial Printers  
 Teleprinters

F. Input/Output Units

- COM Equipment  
 Digitizer/Light Pens  
 Facsimile Equipment  
 Magnetic Card Equipment  
 Optical Input Units  
 Voice Response Equipment  
 Other, please explain \_\_\_\_\_

G. Controllers/Interfaces

- Communications Interfaces/Adapters  
 Data Acquisition and Control Modules/Subsystems  
 Intelligent Interface Modules/Subsystems  
 Peripheral Controllers/Formatters

H. Communications

- Communications Multiplexers  
 Concentrators/Message Switching Systems  
 Data Transmission Equipment  
 Modems/Data Links

J. Software/Firmware

- Applications  
 Communications  
 Development Aids for Microcomputers/Minis  
 Languages  
 Operating Systems

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NAME 

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11/34A, PDP-11/44, PDP-11/70,  
VAX-11/780. **\$4,700.**

**RL02 Top-loading cartridge.**

Capacity per drive: 10.4 Mb. Drives per controller: 4. Average access time: 55 ms (seek) 12.5 ms (latency). Peak transfer rate 512 Kb/sec. Uses 3330 technology. Processors supported: PDP-8/A, LSI-11/2, LSI-11/23, PDP-11/03, PDP-11/23, PDP-11/24, PDP-11/34A, PDP-11/44, PDP-11/70, VAX-11/750, VAX-11/780. **\$5,600.**

**RK07 Free-standing top-loading cartridge.**

Capacity per drive: 28 Mb. Drives per controller: 8. Average access time: 36.5 ms (seek) 12.5 ms (latency). Peak transfer rate 538 Kb/sec. Uses 3330-11 technology. Has dual access option. Processors supported: PDP-11/24, PDP-11/34A, PDP-11/44, PDP-11/70, VAX-11/750, VAX-11/780. **\$12,000.**

**RM02 Free-standing disk pack.**

Capacity per drive: 67 Mb. Drives per controller: 8. Average access time: 30 ms (seek) 12.5 (latency). Peak transfer rate: 1200 Kb/sec. Uses 3330-11+ technology. Has dual-access option. Processors supported: PDP-11/24, PDP-11/34A, PDP-11/44. **\$19,300.**

**RM03 Free-standing disk pack.**

Capacity per drive: 67 Mb. Drives per controller: 8. Average access time: 30 ms (seek) 8.3 (latency). Peak transfer rate: 1200 Kb/sec. Uses 3330-11+ technology. Has dual-access option. Processors supported: PDP-11/70, VAX-11/750, VAX-11/780, DEC-SYSTEM-20. **\$20,300.**

**RM80 Free-standing fixed medium.**

Capacity per drive: 124 Mb. Drives per controller: 8. Average access time: 25 ms (seek) 8.3 ms (latency). Peak transfer rate: 1200 Kb/sec. Uses 3350 technology. Has

dual-access option. Processors supported: VAX-11/750, VAX-11/780. **\$19,000.**

**RP06. Free-standing disk pack.**

Capacity per drive: 176 Mb. Drives per controller: 8. Average access time: 30 ms (seek) 8.3 ms (latency). Peak transfer rate: 806 Kb/sec. Uses 3330-11 technology. Has dual-access option. Processors supported: PDP-11/34A, PDP-11/44, PDP-11/70, VAX-11/780, DECSYSTEM-20, DECsystem-1090 and -1091. **\$34,000.**

**RM05 Free-standing disk pack.**

Capacity per drive: 256 Mb. Drives per controller: 8. Average access time: 30 ms (seek) 8.3 (latency). Peak transfer rate: 1200 Kb/sec. Uses 3330-11+ technology. Has dual-access option. Processors supported: PDP-11/70, VAX-11/780. **\$34,000.**

**RP07. Free-standing fixed medium.**

Capacity per drive: 512 Mb. Drives per controller: 8. Average access time: 23 ms (seek) 8.3 (latency). Peak transfer rate: 1300 Kb/sec (under TOPS-10 or TOPS-20); 2160 Kb/sec with interleaved vectoring. Uses 3370 technology. Has dual-access option. Processors supported: VAX-11/780, DEC-SYSTEM-2040, -2050, and -2080, DECsystem-1090 and -1091. **\$38,000.**

**RP20. Free-standing fixed medium.**

Capacity per drive: 929 Mb (967 Mb under TOPS-10 and TOPS-20). Drives per controller: 8. Average access time: 25 ms (seek) 8.3 (latency). Peak transfer rate: 1200 Kb/sec. Uses 3370 technology. Has dual-access option. Processors supported: DEC-SYSTEM-2040, -2050, and -2080, DECsystem-1090 and -1091. **\$49,000.**

## tape storage

**TU58 Drive for preformatted 1/4-inch tape cartridge.**

Capacity of tape unit: .25 Mb. Drives per controller: 2. Tracks: 2. Recording density: 800 bits/in. R/W speed 30 in/sec. Peak transfer rate: 38,400 baud. Rewind speed: 60 in/sec. Can be rack-mounted, in table-top chassis, or as build-in component. Processors supported: LSI-11/2, LSI-11/23, PDP-11/03, PDP-11/23, PDP-11/34A, PDP-11/44, PDP-11/70, VAX-11/750. **\$750.**

**TS11 Drive for 1/2-inch tape in reels up to 10.5".**

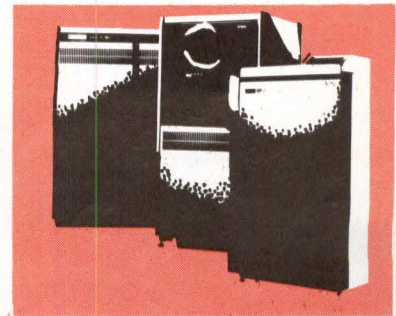
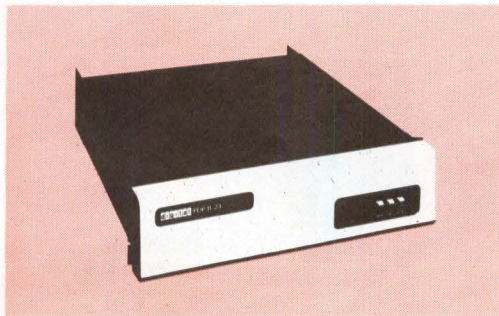
Capacity of tape unit: 31 Mb. Drives per controller: 1. Tracks: 9. Recording density: 1600 bits/in. R/W speed: 45 in/sec. Peak transfer rate: 72 Kb/sec. Rewind speed: 150 in/sec. Buffering: tension arm. Tape threading: manual. Rack-mount or free-standing unit. Processors supported: PDP-11/24, PDP-11/34A, PDP-11/44, PDP-11/70, VAX-11/750, VAX-11/780. **\$13,800.**

**TE16 Drive for 1/2-inch tape in reels up to 10.5".**

Capacity of tape unit: 31 Mb. Drives per controller: 8. Tracks: 9. Recording density: 800 or 1600 bits/in. Read/write speed: 45 in/sec. Peak transfer rate: 72 Kb/sec. Rewind speed: 150 in/sec. Buffering: vacuum. Tape threading: manual. Free-standing unit. Processors supported: PDP-11/34A, PDP-11/44, PDP-11/70, VAX-11/780. **\$15,000.**

**TU77 Drive for 1/2-inch tape in reels up to 10.5".**

Capacity of tape unit 31 Mb. Drives per controller: 4. Tracks: 9. Recording density: 800 or 1600 bits/in. R/W speed: 125 in/sec. Peak transfer rate: 200 Kb/sec. Rewind speed: 440 in/sec. Buffering: vacuum. Tape threading: automatic. Free-stand-





ing unit. Processors supported: PDP-11/44, PDP-11/70, VAX-11/750, VAX-11/780, DECSYSTEM-20, DECsystem-1090 and -1091. **\$23,100.**

**TU78 Drive for 1/2-inch tape in reels up to 10.5".** Capacity of tape unit 145 Mb. Drives per controller: 4. Tracks: 9. Recording density: 1600 or 6250 bits/in. R/W speed: 125 in/sec. Peak transfer rate: 781 Kb/sec. Rewind speed: 440 in/sec. Buffering: vacuum. Tape threading: automatic. Free-standing unit. Processors supported: VAX-11/780. **\$25,500.**

**TU72 Drive for 1/2-inch tape in reels up to 10.5".** Capacity of tape unit 145 Mb. Drives per controller: 8. Tracks: 9. Recording density: 1600 or 6250 bits/in. R/W speed: 125 in/sec. Peak transfer rate: 781 Kb/sec. Rewind speed: 500 in/sec. Buffering: vacuum. Tape threading: automatic. Free-standing. Processors supported: DECSYSTEM-20, DECsystem-1090 and -1091. **\$35,300.**

## Terminals and Printers

### terminals

**LA34-DA Hardcopy terminal.** Uses dot-matrix (9 × 7). Character set: 96 ASCII. Maximum printing speed: 300 baud. Paper type: roll. Buffer capacity: 128 characters. **\$1,450.**

**LA34-AA Hardcopy terminal.** Uses dot-matrix (9 × 7). Character set: 96 ASCII. Maximum printing speed: 300

baud. Paper type: roll. Buffer capacity: 160 characters. Forms handling standard. Extended Logic (XL) option available. **\$1,600.**

**LA34-RA Receive-only hardcopy terminal.** Uses dot-matrix (9 × 7) for alphanumeric characters. Character set: 96 ASCII. Also has graphics-output printing from raster-screen video terminal. Maximum printing speed: 300 baud. Paper type: pin-feed. **\$1,550.**

**LA34-VA Receive-only hardcopy terminal.** Uses dot-matrix (9 × 7) for alphanumeric characters. Character set: 96 ASCII. Also has graphics-output printing from raster-screen video terminal. Maximum printing speed: 300 baud. Paper type: roll feed. **\$1,650.**

**LA34-WA Receive-only hardcopy terminal.** Uses dot-matrix (9 × 7) for alphanumeric characters. Character set: 96 ASCII. Also has graphics-output printing from raster-screen video terminal. Maximum printing speed: 300 baud. OEM version sold without paper option. **\$1,700.**

**LA38-GA Hardcopy terminal.** Uses dot-matrix (9 × 7). Character set: 96 ASCII. Has auxiliary numeric keypad. Maximum printing speed: 300 baud. Paper type: pin feed. Buffer capacity: 160 characters. **\$1,750.**

**LA38-HA Hardcopy terminal.** Uses dot-matrix (9 × 7). Character set: 96 ASCII. Has auxiliary numeric keypad. Maximum printing speed: 300 baud. Paper type: pin feed. Buffer capacity: 160 characters. Has pedestal stand. **\$1,850.**

**LA38-AA Hardcopy terminal.** Uses dot-matrix (9 × 7). Character set: 96 ASCII. Has auxiliary numeric keypad.

Maximum printing speed: 300 baud. Paper type: pin feed. Buffer capacity: 160 characters. Forms handling standard. Extended logic (XL) option available. **\$1,750.**

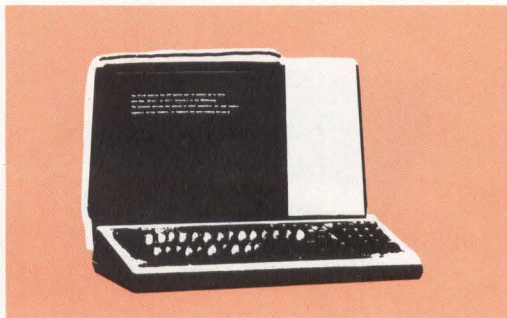
**LA120-AA Hardcopy terminal.** Uses dot matrix (7 × 7). Character set: 96 ASCII. Bidirectional printing. Maximum printing speed: 1200 baud. Buffer capacity: 4 K character max. **\$2,750.**

**LA120-RA Receive-only hardcopy terminal.** Uses dot matrix (7 × 7). Character set: 96 ASCII. Bidirectional printing. Maximum printing speed 1200 baud. Buffer capacity 1 K character. **\$2,700.**

**VT100 Video terminal.** Character set: 96 ASCII. Maximum communication rate: 19,200 baud. User-selectable functions such as reverse video, choice of 80- and 132-column lines, jump or smooth bidirectional scrolling, double-width or -size characters, and split screen scrolling. Video in and video out. Movable keyboard. **\$2,150.**

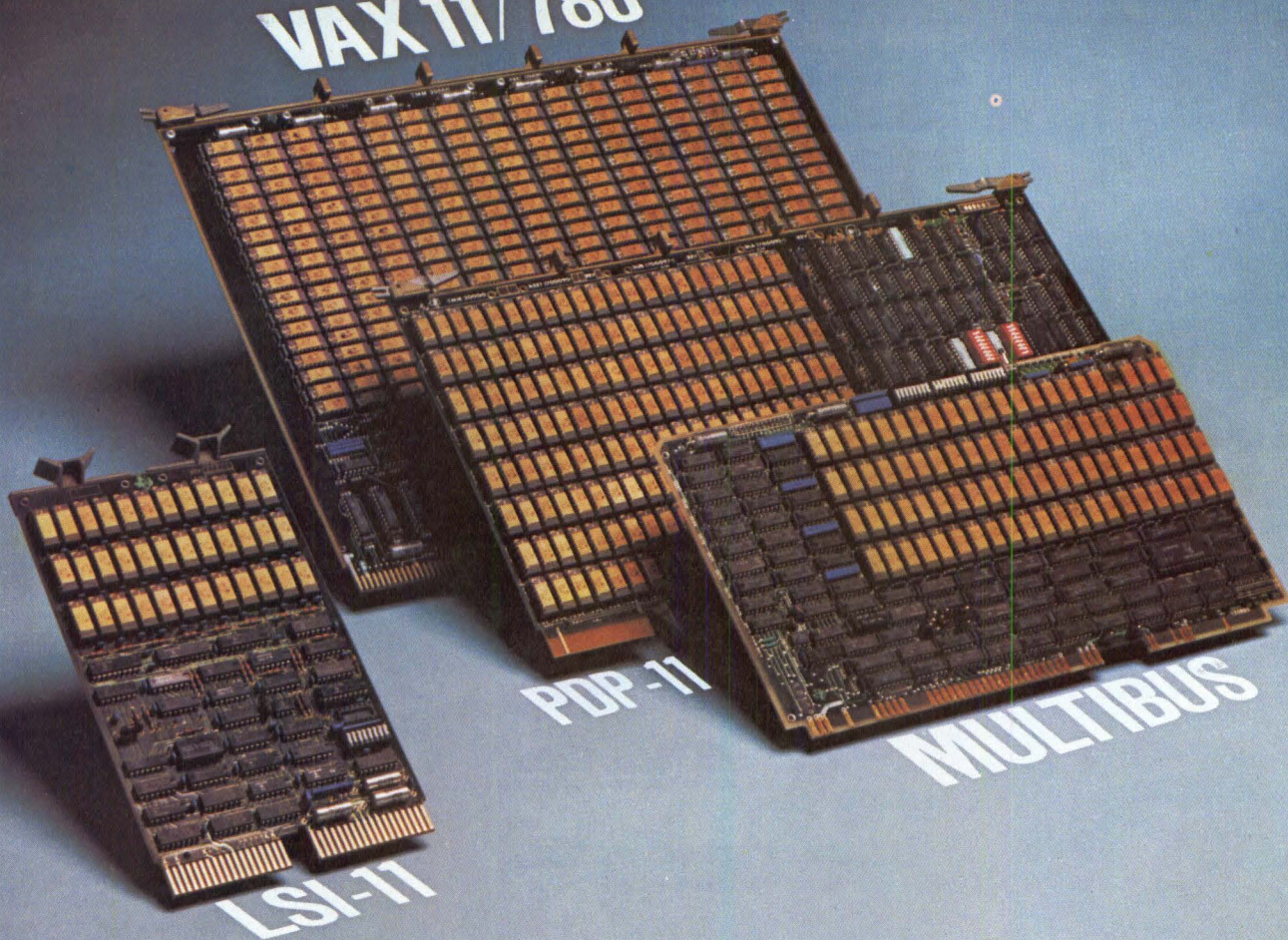
**VT100T Video terminal with emission shielding.** Character set: 96 ASCII. Maximum communication rate: 19,200 baud. User-selectable functions such as reverse video, choice of 80- and 132-column lines, jump or smooth bidirectional scrolling, double-width or -size characters, and split screen scrolling. Video in and video out. Movable keyboard. **\$7,100.**

**VT103 Video terminal with provisions for addition of LSI-11/2 or LSI-11/23.** Character set: 96 ASCII. Maximum communication rate: 19,200 baud. User-selectable functions such as reverse video, choice of 80- and 132-column lines, jump or smooth bidirectional scrolling, double-width or -size characters, and split screen scrolling.





VAX 11/780



## TI leadership. In 64K DRAM technology. In Memory Systems.

Whatever bus you're using — VAX<sup>†</sup>, PDP-11<sup>†</sup>, LSI-11<sup>†</sup>, or even Multibus<sup>‡</sup> — TI can supply add-in memory system boards with dynamic RAMs from our own high-performance 64K series.

When you specify TI's high-density, low-power boards, you save rack space. So you have more room for I/O — or whatever else you need. And, the low-power consumption of TI 64K DRAMs, compared to the old-fashioned 16Ks, cuts temperature levels and increases reliability. The reduction in memory package count by as much as four boosts reliability even more.

System reliability will be higher, too. Thanks to error correction/detection available on many TI memory boards. Using our own bipolar EDAC chip helps cut component count and system temperature, as well as improving basic system reliability. The EDAC chip replaces

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### Low cost

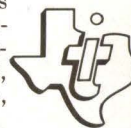
Representative pricing\* for TI memory boards is as follows: \$1600 for TMM10000-04 (192KB); \$3800 for TMM20000-02 (256KB); \$9000 for TMM30000-01 (1MB); \$1845 for TMM40010-07 (64KB).

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| TI MEMORY BOARDS — CURRENT AVAILABILITY |                       |             |      |      |      |      |      |    |
|---|-----------------------|-------------|------|------|------|------|------|----|
| System                                  | TI Series             | BYTES/BOARD |      |      |      |      |      |    |
|   |                       | 64K         | 128K | 192K | 256K | 512K | 768K | 1M |
| LSI-11 <sup>†</sup>                     | TMM10000 <sup>1</sup> |             | X    | X    | X    |      |      |    |
| PDP-11 <sup>†</sup>                     | TMM20000 <sup>2</sup> |             | X    | X    | X    | X    |      | X  |
| VAX <sup>†</sup>                        | TMM30000              |             |      |      |      | X    | X    | X  |
| Multibus <sup>‡</sup>                   | TMM40010 <sup>2</sup> | X           | X    |      | X    | X    |      |    |

<sup>1</sup> Parity optional    <sup>2</sup> EDAC standard

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Circle 3 on Reader Inquiry Card

<sup>†</sup>Trademark Digital Equipment Corp.  
<sup>‡</sup>Trademark Intel Corp.  
\*U.S. Single-unit price, subject to change without notice.



Video in and video out. Movable keyboard. **\$3,200.**

**VT105 Scientific/laboratory video terminal.** Character set: 96 ASCII. Limited graphics capabilities (charts and histograms). Maximum communication rate: 19,200 baud. User-selectable functions such as reverse video, choice of 80- and 132-column lines, jump or smooth bidirectional scrolling, double-width or -size characters, and split screen scrolling. Video in and video out. Movable keyboard. **\$3,100.**

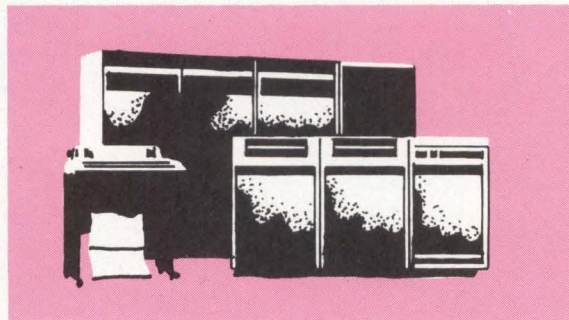
**VT173 Video terminal for typesetting computer systems.** Uses LSI-11/2. Special typesetting keyboard (105 keys in reporter version; 123 keys in classified-advertisement version). Has 32-Kb internal memory. Maximum communication rate: 19,200 baud. User-selectable functions such as multiple text creation and editing areas. Movable keyboard. **\$5,195.**

**VS11 Engineering video terminal for PDP-11 and VAX-11 computers.** Raster-scan unit available with either monochrome or full color presentation. Character set: 96 ASCII. Has

joystick for cursor positioning. Image memory to  $512 \times 526 \times 4$  noninterlaced. Image range: 16 colors or 16 shades of gray. **\$6,480.**

**VSV11 Engineering video terminal for LSI-11 and PDP-11/03, PDP-11/23.** Raster-scan unit available with either monochrome or full color presentation. Character set: 96 ASCII. Has joystick for cursor positioning. Image memory to  $512 \times 526 \times 4$  noninterlaced. Image range: 16 colors or 16 shades of gray. **\$5,730.**

**VK100 Keyboard subsystem.**  $\mu$ P-based unit for connection to video display (monitor). Has graphics, alphanumerics. Can be used with color or monochrome monitors. Has 8 colors or 8 levels of gray in picture presentations. Has graphics output port for use with LA34-VA terminal. Has internal (ROM-based) BASIC. Has interface for use with (user supplied) graphics tablet. **\$4,200.**

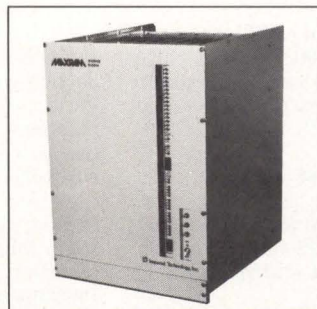


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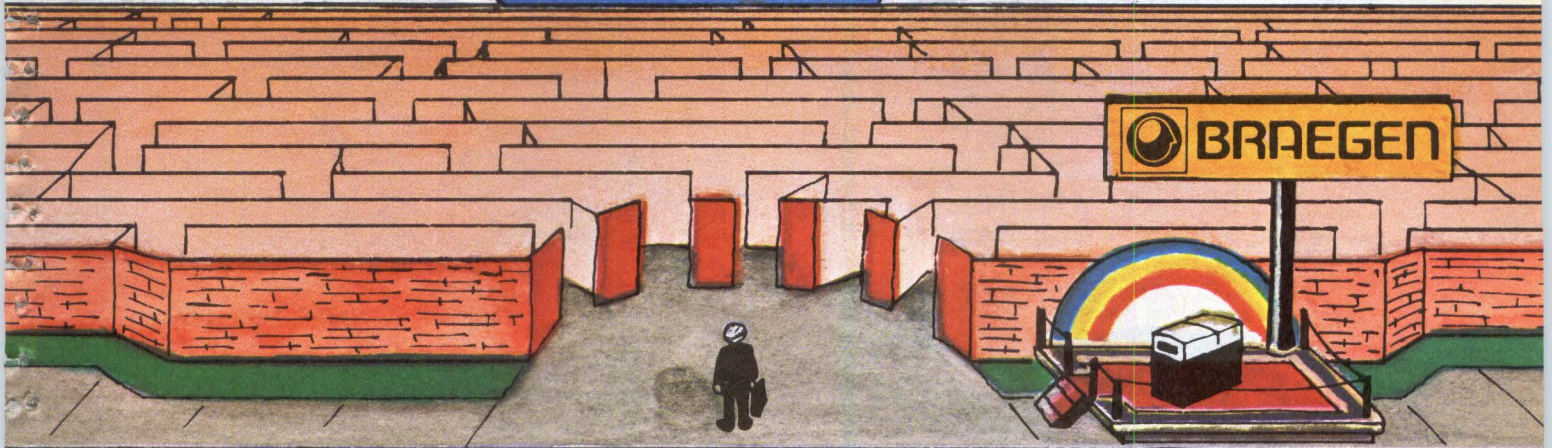
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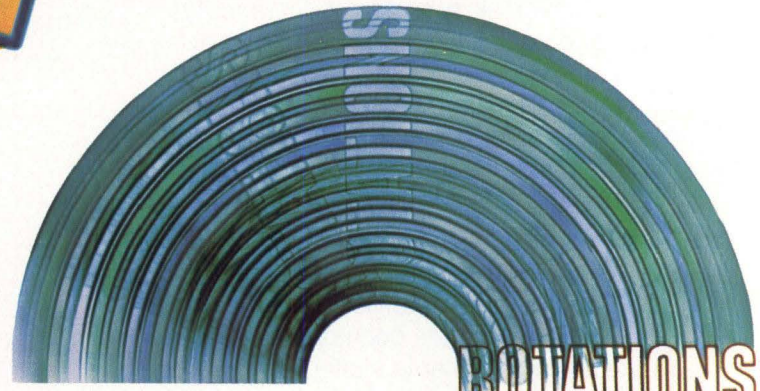
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**LP11-BA Band printer.** Output speed: 285 or 204 lines per minute. Character set: 64 or 96. Paper feed; pin feed. uses horizontal-font printing. For computers with UNIBUS. **\$8,950.**

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**LPV11-BA Band printer.** Output speed: 285 or 204 lpm. Character set: 64 or 96. Paper feed; pin feed. Uses horizontal-font printing. For computers with LSI-11 bus. **\$8,950.**

**LP11-C Impact line printer.** Output speed: 900 lpm. Character set: 64. Paper feed; pin feed. For UNIBUS PDP-11s. **\$27,800.**

**LP11-D Impact line printer.** Output speed: 660 lpm. Character set: 96. Paper feed: pin feed. For UNIBUS PDP-11s. **\$29,700.**

**LP11-V Impact line printer.** Output speed: 300 lines per minute. Character set: 64. paper feed; pin feed. For LSI-11 bus PDP-11s. **\$16,400.**

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**LP11-Z Impact line printer.** Output speed: 436 lpm. Character set: 96. Paper feed: pin feed. For UNIBUS PDP-11s. **\$21,900.**

**LP20-B Impact line printer.** Output speed: 240 lpm. Character set: 96. Paper feed: pin feed. For DECSYS-TEM-20 computer systems. **\$18,700.**

**LP20-D Impact line printer.** Output speed: 660 lpm. Character set: 96. Paper feed: pin feed. For DECSYS-TEM-20 computer systems. **\$37,900.**

**LP100-B Impact line printer.** Output speed: 1200 lpm. Character set: 64 or 96. Paper feed: pin feed. For DECsystem-10 computer systems. **\$63,100.**

**LP100-H Impact line printer.** Output speed: 660 lpm. Character set: 96. Paper feed: pin feed. For DECSYS-TEM-20 computer systems. **\$45,400.**

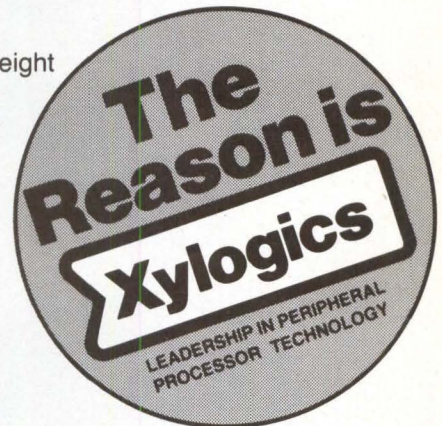
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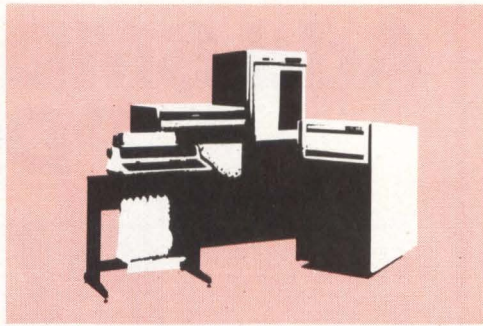
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#### QUADRASYNC/B™ (4-LINE DL11 REPLACEMENT/EIA)

**INSTALLS IN:** All PDP-11's; 4-lines per SPC slot at one unit load to Unibus. **DATA RATES:** 7 independently selectable baud rates for each of 4 channels (150-9600). **ELECTRICAL:** EIA standard RS232C (Modem control not supported). **VECTOR/ADDRESS SELECTION:** Vector and address values to be set on boundaries of 00s or 40s. 16 continuous word address for Vector or Address.

#### QUADRASYNC/C™ (4-LINE DL11 REPLACEMENT/CL)

**INSTALLS IN:** All PDP-11's; 4-lines per SPC slot at one unit load to Unibus. **DATA RATES:** 7 independently selectable baud rates for each of 4 channels (150-9600). **ELECTRICAL:** 20MA current loop (Send + Receive). **VECTOR/ADDRESS SELECTION:** Vector and address values to be set on boundaries of 00s or 40s. 16 continuous word address for Vector or Address.

#### QUADRASYNC/E™ (4-LINE DL11-E REPLACEMENT)

**INSTALLS IN:** All PDP-11's; 4-lines per SPC slot at one unit load to Unibus. **DATA RATES:** 7 independently selectable baud rates for each of 4 channels (150-9600). **ELECTRICAL:** EIA standard RS232C - with modem control. **VECTOR/ADDRESS SELECTION:** 16 continuous word address for Vector or Address - starting values selected on any boundary.

#### QUADRACALL™ (4-LINE DN11 REPLACEMENT)

**INSTALLS IN:** All PDP-11's; 4-lines per SPC slot at one unit load to Unibus. **PERFORMANCE:** Interfaces up to 4 Bell 801 ACU's with Unibus enabling any PDP-11 to dial any DDD network number to establish data link. **INPUT/OUTPUT:** 5-input signals from ACU are handled by EIA RS232 receivers. 6-output signals are transmitted using EIA RS232 drivers. **VECTOR/ADDRESS SELECTION:** Allows selection of device address and vector by use of pencil switches.

#### ABLE DV/16 (16-LINE DV11 REPLACEMENT)

**INSTALLS IN:** All PDP-11's; in less than one half the space of DV11. **DATA RATES:** 16-line throughput of up to 30,000 char/sec (19.2K baud full duplex for each line) total. **PROCESSING ADVANTAGE:** Word transfers (in lieu of byte DMA) permit user to operate within one half the DV11 bandwidth for data transfers. **OPERATING ADVANTAGE:** User may mix sync and async lines in combinations of 4 or 8 lines with modem control and full system software compatibility with all DV11 performance features.

#### ABLE DZ/16 (16-LINE DZ11-E REPLACEMENT)

**INSTALLS IN:** All PDP-11's in any standard hex-width SPC slot; takes half the space at half the bus loading imposed by the DZ11-E. **DATA RATES:** All 15 standard DZ11 baud rates (50-9600). **IMPLEMENTATION ADVANTAGES:** On-board pencil switches allow address and vector selection flexibility without the need for jumpers. Data format is program-selectable for each channel.

### MEMORY PRODUCTS

#### SCAT/45™ (ADD-IN FASTBUS MEMORY)

**INSTALLS IN:** PDP-11/45, -11/50 and -11/55. **EXPANDS IN:** 32K word increments/board. One-half of the available Fastbus space will accept full 124K word complement. **ADDRESSES ON:** Any 4096 word boundary across entire 124K word range. User has full memory complement at 330 nsec cycle-time memory instead of 32K word limitation imposed by the computer manufacturer.

#### CACHE/45™ (CACHE BUFFER MEMORY)

**INSTALLS IN:** PDP-11/45, -11/50 and -11/55. **CAPACITY:** 2048 byte (1K word). **ENHANCEMENT FACTOR:** Run time reductions to 50% (100% speed improvement) are achievable. **CACHE PARITY:** Automatically goes off-line in event of any data error. **RANGE SELECTION:** User may optimize hit ratio by upper/lower limit switch settings. **SPECIAL FEATURE:** Cache/45 can be enabled via software or console switches.

#### CACHE/434™ (4K WORD CACHE MEMORY)

**INSTALLS IN:** PDP-11/34 and -11/34A without using any additional backplane space! **CAPACITY:** 8192 byte (4K word). **ENHANCEMENT FACTOR:** Run time reductions to 40% (70% speed improvement) are achievable. **CACHE PARITY:** Automatically goes off-line in event of any data or address error. **RANGE SELECTION:** User may optimize hit ratio by upper/lower limit switch settings. Cache action monitor indicates hit rate.

#### CACHE/440™ (4K WORD CACHE MEMORY)

**INSTALLS IN:** PDP-11/35 and -11/40 without using any additional backplane space! **CAPACITY:** 8192 byte (4K word). **ENHANCEMENT FACTOR:** Run time reductions to 40% (70% speed improvement) are achievable. **CACHE PARITY:** Automatically goes off-line in event of any data or address error. **RANGE SELECTION:** User may optimize hit ratio by upper/lower limit switch settings. Cache action monitor indicates hit rate.

#### EMULOADER™ (ODT/BOOTSTRAP LOADER REPLACEMENT)

**INSTALLS IN:** PDP-11/05, -11/10, -11/35, -11/40, -11/45, -11/50 and -11/55. **MECHANICAL:** Dual width card replaces standard Unibus termination; requires no additional backplane space. **OPERATING ADVANTAGE:** Provides fixed console emulator (ODT) and bootstrap loaders for DL11, PC11, RF11, RK06, RK11, RP04/05/06, RP11, RS03/04, RX11, TC-11, TM11 and TU16. **SPECIAL FEATURE:** Performs memory diagnostic each time a boot operation is done from ODT.

### GENERAL PURPOSE PRODUCTS

#### QNIVERTER™

(Q-BUS TO UNIBUS CONVERTER OR UNIBUS TO Q-BUS CONVERTER)

**INSTALLS IN:** LSI-11, LSI-11/23, PDP-11/03 and PDP-11/23 via quad-width card. **APPLICATIONS:** Allows Unibus-compatible controllers and memories to be used with LSI computer systems, or LSI-based peripherals to be used with PDP-11 computer systems. **FEATURES:** Supports features of LSI-11/23 including the full 128K address capability.

#### REBUS™

(BUS REPEATER - DB11 REPLACEMENT)

**INSTALLS IN:** All PDP-11's; without using any additional backplane space. **MECHANICAL:** One dual-width card plugs into the same pair of connectors as the Unibus extension cable which is then plugged into the REBUS connectors. **COMPATIBILITY:** Allows for 18 additional bus loads and 50 foot bus extension. Requires no software changes. Bus cycle time unaffected for devices on CPU side of REBUS - increased by 250 nsec max. for devices on outboard side.

#### DUAL I/O™ (GENERAL INTERFACE-DR11-C REPLACEMENT)

**INSTALLS IN:** All PDP-11's; in any SPC slot via quad-width card. **APPLICATION:** Dual I/O is equivalent to two (2) DR11-C's and provides the logic for program-controlled parallel transfer of 16-bit data between two (2) external user devices and a Unibus system. **OPERATING ADVANTAGE:** Provides user the hardware/software equal to a dual DR11-C in one-half the space and one-half the bus loading of DR11-C's.

#### INTERLINK/UNI (DR11-B AND 1/2 DA11-B REPLACEMENT)

**INSTALLS IN:** All PDP-11's in any SPC slot via hex-width card. **APPLICATIONS:** Provides full DR11-B (DMA INTERFACE) and one side of DA11-B (UNIBUS LINK) capability on a single card. **OPERATING ADVANTAGES:** Requires only one hex-width card in each computer to effect link vs. full four-slot system unit per computer. Exhibits one bus load. Directly software transparent as a DR11-B replacement or when expanded to DA11-B equivalency.

#### BUSLINK/UNI, LSI OR U TO Q (CPU TO CPU LINK; UNIBUS TO UNIBUS, UNIBUS TO Q-BUS OR Q-BUS TO Q-BUS)

**INSTALLS IN:** All PDP-11's and/or LSI-11's via pairs of hex-width, hex/quad-width, or quad-width cards and supplied cables. **APPLICATION:** Provides full DA11-B (Unibus or Q-bus link) compatibility on single cards. BUSLINK operates at DA11-B transfer rates over distances of up to 50 feet. **OPERATING ADVANTAGE:** Requires only one card per CPU to effect link at minimal bus loading vs. full system unit per computer.

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# DEC Compatible Products Continue Upward Growth

*also, how not to get caught in your own trap*

**T**he early days of DEC compatibility saw financially shaky companies often offering products that later proved to be unreliable. From that unpromising beginning has emerged a generally healthy, dynamic industry, most of whose offerings begin with unqualified reliability. But there are still some pitfalls in this comparatively new supply source. This article will hopefully guide you safely past those consumer traps. Best tip: know your supplier!

by Paul Snigier

DEC compatible products continue their inroads, taking more market share, and improving from previous days of poor boards and poorer service. DEC compatibility has gained respectability. Unlike the earlier days of DEC compatibility, which was set off by the introduction of the PDP-11, respectability has come to the field. Many of the manufacturers of DEC compatible products are relatively long-term survivors in this field. They have survived the shakeout and lean years, and have grown into well-staffed, well-fielded outfits that can design, manufacture and support their DEC compatible products for years to come. Others, frequently cottage shop outfits started by college students and others, lacked the staying power or motivation to adequately service their products. More than one product was made with substandard parts, assembled in a cellar, with solder bridges and ICs inserted backwards. These products were foisted off onto unsuspecting OEMs. If the boards or products didn't work — which all too often became frequent enough to create monumental design and production headaches — then the only thing that was more aggravating was the promised field service from the DEC compatible manufacturer which wasn't all that had been promised. Times have changed.

Large semiconductor makers, such as National Semiconductor, which provided some material used in this article, and others like Mostek and TI, are actively pursuing this market. Obviously, they have a decided edge over other add-in/add-on memory makers when volume is the driving force. We wish to thank System Industries, Imperial Technology, and other manufacturers for providing us with technical material and answering our questions.

## vendor selection

If the product you're specifying is something you can service and is simple enough, or commonly-used and easily serviceable by other field techs, then vendor selection may assume less significance than if the products are more complex or less well-known.

*Paul Snigier is the Editor of Digital Design magazine.*

In investigating, insist on answers; your job and your firm are on the line — not theirs. Check the reputation of the firms you investigate by calling several. But, with myriad firms and new startups dotting this field, it's impossible to evaluate reputations, much less keep track of them. While compiling our August Computer Compatible (COMPAT) Directory issue — which will be distributed at our COMPAT show next month — we discovered firms not listed anywhere else by any other source of information. To check on them, you might start by using next month's directory issue. Ask colleagues within your department and company. While visiting shows, make contacts and ask them. Phone contacts for recommendations and what bad or good experiences they've had. If they work in a non-competing field, they may be glad to talk, hoping you'll reciprocate sometime. Find out what your competitors prefer — and what firms they avoid.

Get customer references from the firm. Contact them and determine their level of sophistication and breadth of experience. Each contact may provide you with two or three additional leads, giving you a good idea of how that firm conducts its business from the customer's viewpoint. This may not be what the firm tells you.

You have the right to ask for proof that the firm has staying power and commitment to that product line. Obtain a written financial report. Get bank references. Interpret growth patterns. That is, interpret them in terms of what's going on with other firms in that same sector of the DEC compatible market. If many have gone belly-up in the past three years that marketed this product and committed their main marketing effort to this product line, then it's very likely that this firm will more likely than not also end up on credit-hold with suppliers and be unable to correct the problems. Or, a firm may grow too rapidly, with sales skyrocketing, and wind up in receivership with cash flow problems. Slowed deliveries (and the related worsening field support) will hurt your firm's reputation.

You should check training; your people must be trained on the product you'll buy. Is it at the end user's site? At yours? Or at the maker's site? It's a good idea to have some independence in having your own service capability in case something happens to your supplier's field service. It's also a plus in selling your customers, and makes a good advertising



and sales pitch. See if you can negotiate manufacturing rights to the product that you purchase. It's just one more safety net in case the manufacturer goes under or decides to get out of this product line, or put it on the back burner.

### documentation: key to quality

Poor firms provide poor documentation; good firms, usually good to excellent documentation. Insufficient information about, say, a controller, could mean the difference between a disaster and a maintainable product. If the product is unsophisticated, then a basic instruction list, theory of operation and schematics might be satisfactory. Perhaps it leaves something to be desired, but it's something you and your designers and field techs can live with. Such a documentation is "adequate," although annoying and tedious to interpret.

For more sophisticated equipment, documentation becomes critical. Check the manuals and documentation to maintain, field repair and even build your own one day. Does the manufacturer provide on-going support for his documentation, providing decent retrofits and upgrades?

Failure to provide adequate documentation at this stage in the development of the DEC compatible marketplace is inexcusable; it is an indication of the lack of concern that this manufacturer feels towards his customers. It may be a sign of things that are waiting in store for you if you deal with him. Poor documentation is rarely a sign of incompetence: it's usually due to lack of concern or a tight-fisted company that's overlooking its EEs. When a design project is behind, guess what gets put off until later? Finally, at the end of the design cycle, there is a sudden rush to put together some documentation — anything — just to meet the commitment. Programmers, and to a greater degree, designers, are judged primarily on the code they generate and the circuits they design and package — not mainly on the quality of documentation. Project leaders are usually not judged primarily on the quality

of the documentation. And they know it. So, documentation gets the short end of the stick. Make sure you're not the victim. Demand quality documentation.

Your own documentation to the end user will also be written in part from the documentation you receive. In the case of military systems, a market that is targeted to grow in the eighties, poor documentation can prove your undoing. With more functionally illiterate students coming from public schools and entering the military, and with the exodus of skilled and technically-trained men from the military to industry, the armed forces must train an increasing number of recruits rapidly. Unfortunately, the quality of the recruits, in terms of their reading comprehension, is declining. With increasing classroom size and lack of meaningful punishment, and school discipline problems at epidemic proportions, there is no chance of any real improvement in reading comprehension within the eighties. The alternative, aside from simpler and less sophisticated military systems, is the generation of simpler documentation and training materials from OEMs. Tedious documentation will only make it harder for you to write decent documentation for military systems. Demand good documentation. If the firm has mediocre documentation, even if you don't specify that product, let them know how you feel. A few complaints to their president will get some changes.

### DEC-compatible makers cite plusses

Add-in memory from non-DEC sources offers the following advantages: (1) Products cost thousands of dollars less than non DEC, yet offer many additional features. (2) 97% of the time, you get delivery within, say, 20, days. DEC guarantees delivery within 6-9 months. (3) Products offer extras. An add-in memory may give you an ON/OFF switch that DEC doesn't. In such a case, on-site reconfiguration/trouble  
(continued on page 58)

| Vendor Selection Criteria       | Vendor And Product Selection Criteria |                          |                          |                          |
|---------------------------------|---------------------------------------|--------------------------|--------------------------|--------------------------|
|                                 | critical                              | important                | moderate                 | unimportant              |
| • Financial stability           | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| • product commitment            | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| • field service                 | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| • training                      | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| • manufacturers' rights         | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| • reputation                    | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| • other                         | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| <b>Product considerations</b>   |                                       |                          |                          |                          |
| • cost                          | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| • delivery                      | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| • extras                        | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| • warranty                      | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| • reliability                   | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| • installation costs            | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| • field service                 | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| • flexibility                   | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| • other                         | <input type="checkbox"/>              | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| <b>Sources</b>                  |                                       |                          |                          |                          |
|                                 | completed?                            | date                     |                          |                          |
| • DEC Directory (this issue)    | <input type="checkbox"/>              | _____                    |                          |                          |
| • COMPAT Directory (next month) | <input type="checkbox"/>              | _____                    |                          |                          |
| • colleagues' experiences       | <input type="checkbox"/>              | _____                    |                          |                          |
| • customer references           | <input type="checkbox"/>              | _____                    |                          |                          |
| • examine vendor list           | <input type="checkbox"/>              | _____                    |                          |                          |
| • trade press articles          | <input type="checkbox"/>              | _____                    |                          |                          |
| • market reports                | <input type="checkbox"/>              | _____                    |                          |                          |
| • visits to vendors             | <input type="checkbox"/>              | _____                    |                          |                          |
| • examine vendors' records      | <input type="checkbox"/>              | _____                    |                          |                          |

Figure 1: Develop an evaluation sheet and use one per product. The above evaluation criteria worksheet is only an example; yours will include more criteria tailored to your specific applications.



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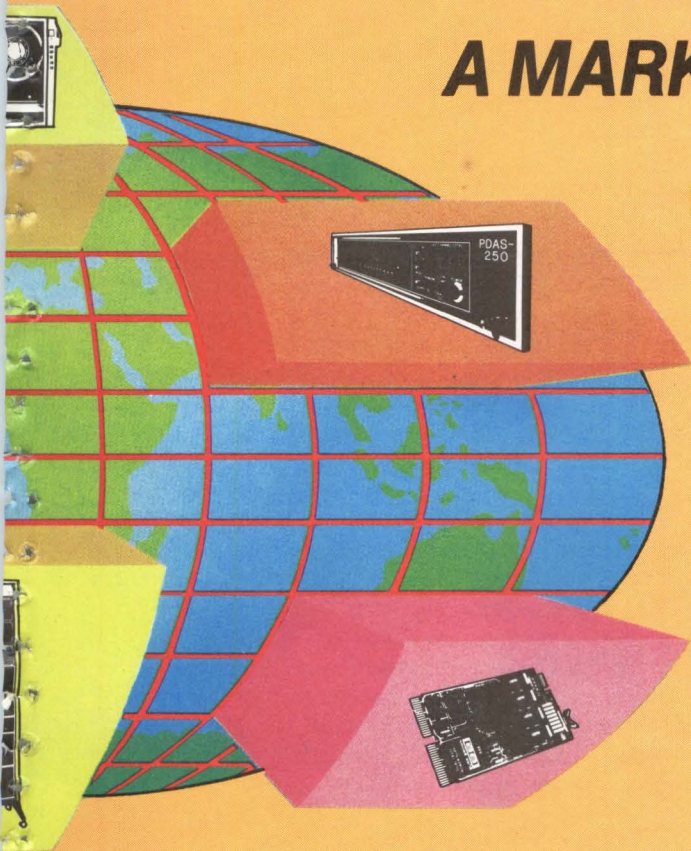




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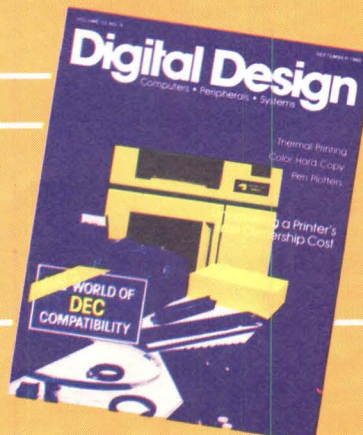
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## design considerations

- Reliability: MTBF, MTTR
- Compatibility with industry std. form, fit and function
- Serviceability
- Ability to meet industry std. environmental specs

## business considerations

- Financial stability
- Who is the supplier's parent company?
- Price/performance
- Production capacity
- Vendor source availability for components, especially heads
- Design approval, warranty, spares, brand recognition
- Customer support
- Capability and commitment for future development

**Figure 2: Selecting DEC-Compatible products will involve a number of criteria, shown above, that fall into the design or business category.**

(continued from page 55)

shooting is enhanced via an on-line/off-line switch to allow you to easily remove the card from the system without physically extracting it from the memory backplane. Where battery backup is employed, memory retains data while on-line or off-line. (4) More makers now give you a good warranty deal, unlike the past fly-by-night boards made from questionable parts. Sometimes they worked; if not, too bad. Service was a bear. Times have changed; DEC compatibility has gained respectability. (5) Check MTBFs, MTTRs and how the data was obtained. If all components are preconditioned to A+ status, and if, say, over 98% of all boards are entirely free from defects, consider yourself lucky. Few approach this reliability. (6) Consider low installation cost. Lower installation cost means it's easy to install and easier to maintain. (7) Is it backed by a big semi or other giant? If it's an industry leader in the design and testing of systems, fine; but sometimes you'll pay extra for this.

To illustrate the above points, let's use the following cases.

### disk storage for large minis

A "Compat" maker's disk storage can bring out the best in your DEC minicomputers, whether they be VAX-11/780, PDP-11/70 or any of the Unibus machines. When your system can't afford downtime — for example, during electronic funds transfer — it can secure database on-line, expand performance and allow for myriad configuration options necessary in such time-critical applications as printing, graphics, and transaction processing. It can substantially increase storage capacity with superior price/performance, while reliability insures a low ownership cost. The basic emulation capability would let you configure it as an RPOX or RMOX disk system; you free yourself from the CPU manufacturer's system constraints, and achieve 100% software transparency with existing disk drives.

Manufacturers' system features include the following, or are features you should look for: (1) Field-proven reliability, serviced with many installations, spanning years of field experience. Beware of novices. (2) Individually-tailored service plans insuring low cost of ownership. (3) Provides

more storage per spindle than RPOX and RMOX drives. (4) Requires hardware or software changes? Better that it doesn't. (5) Multiple CPU option that allows accessibility to database for up to, say, four different DEC minis. (6) Dual-channel drive capability that permits greater throughput, redundant system configurations. (7) Easy expansion via hardware modularity and software transparency. These aren't the only criteria, by a long shot, and they may not suit your needs, but they're guidelines.

### flexibility counts

Is the system built around an emulating controller? It can offer maximum flexibility in database storage systems. As storage needs grow, you then add on drives. Add one controller and a single SBI interface (emulator) to the VAX-11/780, for example, and link up to, say, eight 675-megabyte drives in a daisychain configuration, as one DEC-compatible maker puts it, thus providing up to 4,800 megabytes of on-line storage. This avoids software or hardware changes to the present system. As you configure the system, select from different disk drives. Different firms select different drives, which will vary, because of their in-house reliability. The systems expand flexibility options with configurations. Besides daisy chaining drives, you configure them radially. Or, if you need more than one CPU to share the same database, you use the controller's multiple CPU option to increase throughput by interfacing several DEC CPUs — say, VAX 11/780's, PDP-11/34's or PDP-11/70's — in any combination.

### reliability improves security

Maximize security and integrity of the database by using multiple CPU and dual-channel drives in environments where downtime is intolerable.

As an example, one manufacturer uses a configuration that transforms a single-CPU/controller system to a dual, redundant configuration consisting of two controllers and up to four drives. Two, three or four CPUs can interface with the two controllers, all sharing a common database. The quadruple connections and complete redundancies assure continuous on-line operation, increased throughput, and maximum system performance, without changing applications software or degrading response time.

Other cases can be investigated, but specifying reliability boils down to a few selection criteria.

What about overall dependability of system hardware? Is the system field-proven in thousands of installations? Do they span a broad range of applications? And do one or more resemble your own? Are these systems ones that have rendered years of reliable trouble-free service to hundreds of customers? *Caveat emptor*. Investigate.

### is system support a mirage

Do they back up the system's reliability with reliable service and support during factory system integration, at time of installation and afterwards on an ongoing contract basis tailored to your needs? Go to the plant for an on-site visit. Talk to their service people. Are they specially trained, topnotch engineers and managers? Or front men who merely hold your hand until a competent tech is available? Do they work out of a worldwide network of service centers offering total repair capability and fast turnaround?

Continuing requirements of maintaining data storage systems count. Is there fast, effective service? If you're located within a 50-mile radius of a large metropolitan area, do you get a 4-hour response service? Is it 24 hours a day, 7 days/



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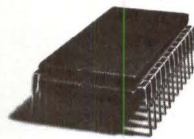


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week? Or do you need a faster, on-site contract? This is appropriate where several systems are centrally located. How many service plans, which can be customized to meet your specific needs, do exist? Or is response time less critical? Then, an 8-, 12-, 16- and 24-hour service "window" (on a normal workday basis) is better.

### peripheral controller

To waste chassis space on peripheral controllers that only interface a single device type to UNIBUS is a one-to-one approach, driving Unibus system costs up and reliability down. A hex-wide peripheral controller that simultaneously handles several RM02/RM03 80 MB disk drives, several TU10½" tape drives and 8-MB of semiconductor disk from just a single slot offers big plusses.

Such a one-board approach, which will grow in popularity, enables one board to do the work of three or more — with no degradation — thus saving in other ways. Immediate savings come from elimination of two comparably-priced controller boards. Down the line, upgrade flexibility permits expanding configuration less expensively: you don't (necessarily) need to buy additional boards or larger chassis.

This cuts spares inventory costs in the factory. It increases system reliability because of fewer ICs. Such cost-benefits mean rebalancing system operational costs, bringing price of I/O processing back in line costs of instruction processing and memory.

### fixed-head disk replacement

You will look for maximum throughput, reliability and transparency when examining alternatives or replacements for fixed-head disks used with DEC computers. A reliable,

solid state memory can feature a built-in controller which attaches to the Unibus on, say, DEC's PDP-11 series. Let's look at one example. The memory would respond through the controller in the same manner as RJS03 and RJS04 fixed-head disks. It should be faster and more reliable than disk storage (otherwise, why specify it?). As for modular flexibility, the memory storage is packaged in pluggable modules of 524K bytes (262, 144 words by 18 bits). Each 19" chassis accepts up to eight modules.

The chassis would accept a pluggable controller unit and a pluggable power supply module. Modules would be interconnected by means of a printed wire backplane; a rack-mount chassis would offer built-in forced-air cooling, thus making it self-contained.

As for chassis storage expansion, a second chassis, containing eight storage modules, could be interconnected so that 8.388 megabytes are available through one controller. Parity would be generated and checked for all data transfers; errors would be flagged. What about the pluggable feature of storage modules? Field expansion is easier, obviously, since maintenance is simplified by modular construction.

This storage system would offer total transparency to all operating software and diagnostics (because of a built-in controller). Each unit would feature two Unibus port interfaces: the first, for control and data; the second, for data only, with data transmission switched between ports under program control.

Are hardware or software changes required in the computer system to utilize the performance and reliability which the product offers? If so, investigate. If users may incorporate software patches for even greater performance, it's a decided plus. D

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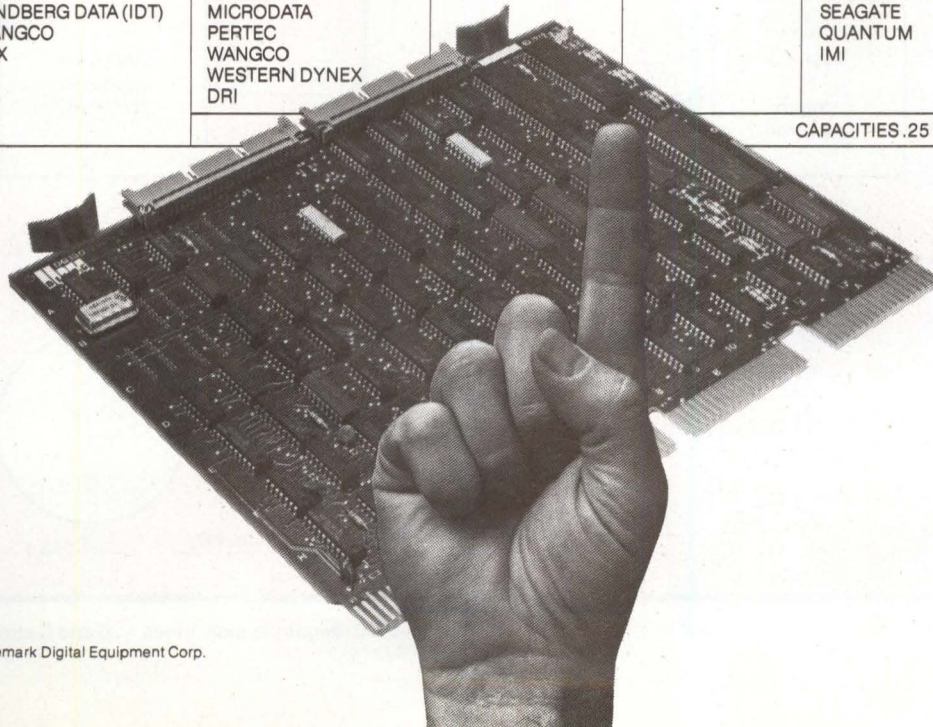
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| 1/2" REEL-TO-REEL STD. & STREAMER  | 2315/5440/RK05 CARTRIDGE CLASS   | CMD CARTRIDGE MODULE  | SMD STORAGE MODULE   | WINCHESTER 5 1/4", 8" OR 14"   | 1/4" TAPE CARTRIDGE                | FLOPPY DISC DRIVE   |
| AMPEX<br>CIPHER<br>CONTROL DATA<br>DIGI-DATA<br>KENNEDY<br>MICRODATA<br>PERTEC<br>TANDBERG DATA (IDT)<br>WANGCO<br>TDX | AMPEX<br>CAELUS<br>CENTURY DATA<br>CONTROL DATA<br>DEC<br>DIABLO<br>IOMEC<br>MICRODATA<br>PERTEC<br>WANGCO<br>WESTERN DYNEX<br>DRI | AMPEX<br>CONTROL DATA | AMPEX<br>CENTURY DATA<br>CONTROL DATA<br>BALL COMPUTER<br>MITSUBISHI | BASF<br>CONTROL DATA<br>FUJITSU<br>KENNEDY<br>MEMOREX<br>PRIAM<br>SHUGART<br>SEAGATE<br>QUANTUM<br>IMI | DEI<br>KENNEDY<br>PEREX<br>QUANTEX | BASF<br>DECITEK<br>MICROPOLIS<br>PERTEC<br>REMEX<br>SHUGART |
| CAPACITIES .25 TO 300 MB   |  |                       |  |  |                                    |   |



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# Bit Slice Design

**F**inal bit-slice emulation provides important user benefits. The most basic is reduction in IC chip count that allows a card reduction from 24 to one. This size shrinkage uses less mainframe or expansion chassis backplane space, less power and lowers system and operating costs. It inherently increases system reliability and lowers maintenance costs. The second major benefit is technological, allowing potentially higher data throughput than the original, improved DMA operation, increased data buffering, and ability to modify firmware executed by the  $\mu P$  to meet custom user needs. Interfacing up to four 80- to 300-MB disks to a standard Unibus backplane at low cost, Storm-02 is software and disk media compatible with the RJM02 subsystem.

by **Hildon Gold and Robert Deisher**

For the past several years now, the  $\mu P$  has displaced functions formerly performed by hard-wired logic. These new designs are yielding circuit functions of lower cost, smaller size, lower power consumption, increased reliability and easier maintainability. Such was the case with our own design team. We were able to develop a single-board controller capable of interfacing multiple, 80-megabyte storage module drives with DEC PDP 11s.

An alternative to the RJM02 mass storage system, the Storm-02 Controller provides interfacing for four drives. Each drive offers 80- to 300-megabyte unformatted storage for the PDP-11/04 through the PDP-11/60 Computer Systems. The Storm-02 was designed to emulate DEC's RJM02, including the RM-02 disk drive and RH-11 adapter. Unlike the DEC system that required up to 24 cards plus an expansion chassis to provide an interface for mass storage drives, the new design accomplished the same functions on a single board (**Figure 2**). What's more, when a Storm-02 and companion mass storage modules are selected instead of the DEC System, cost savings are considerable. For the first 80-

*Hildon Gold is Senior Hardware Engineer and Robert Deisher is International Marketing Manager (Europe and Mid East) for AED, 440 Potrero Ave., Sunnyvale, CA 94086.*

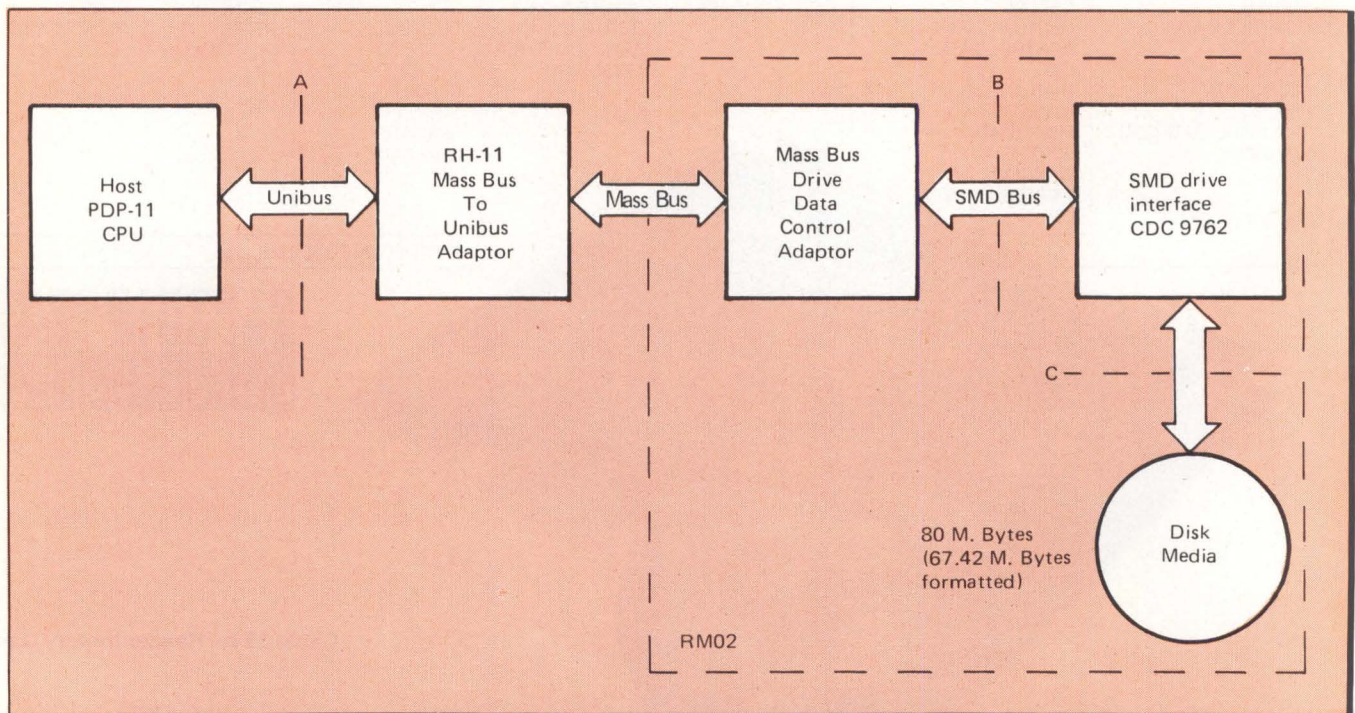


Figure 1: DEC implementation of the interface containing an RH-11 and RM02 interface to an 80 megabyte disk. Lines A, B and C show the major division points.



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*enables a single controller card to mate  
multiple storage disks to a DEC bus*

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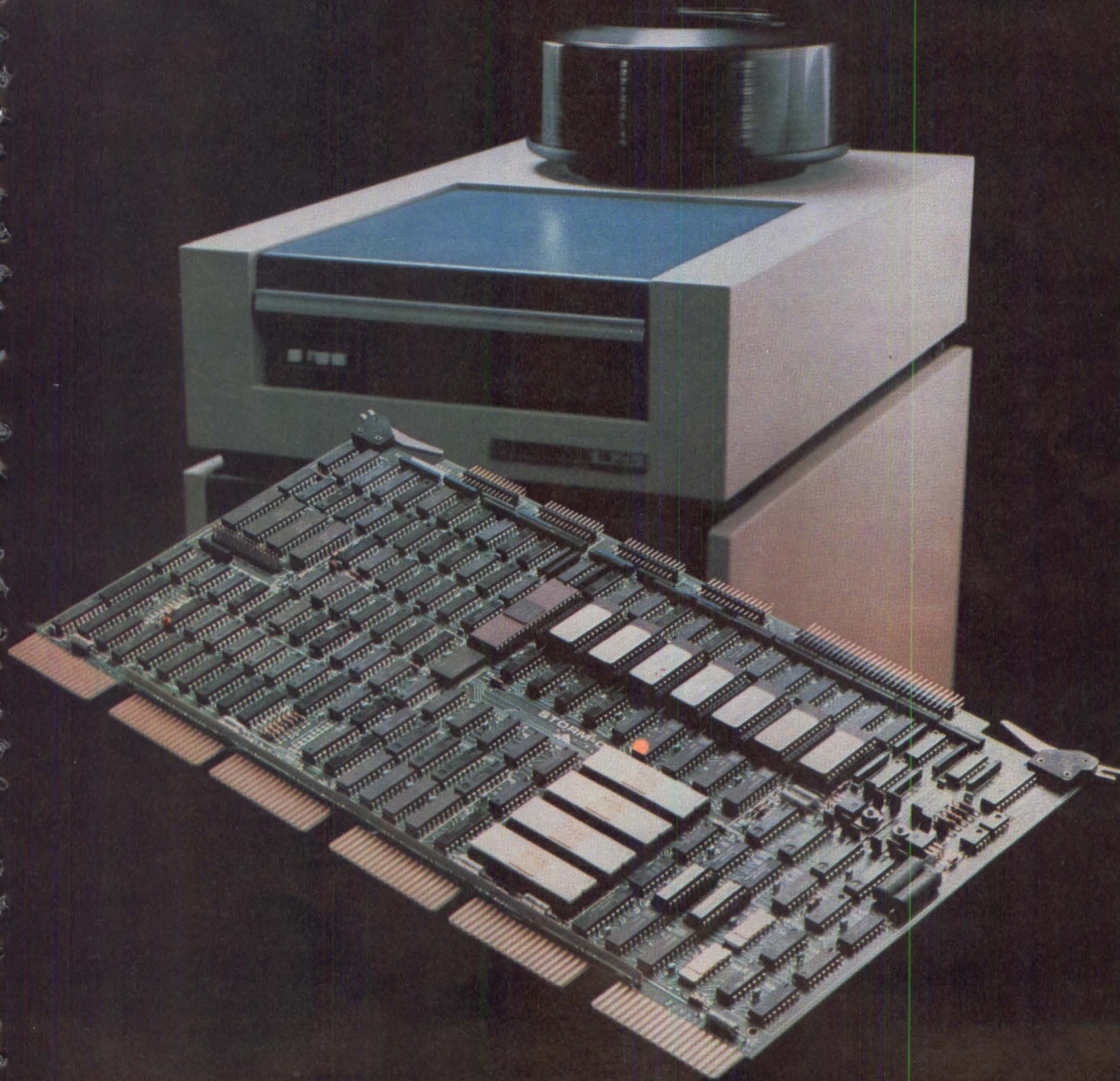


Figure 2: Single-board controller interfaces multiple, 80-Mbytes storage module drives with DEC PDP-11s.



megabytes (67 megabytes formatted), the cost of the configured storage system is 35% below the cost of the equivalent DEC system. Savings upon expansion to three additional 80-megabyte drives, for a total of 269 megabytes formatted, is considerably more.

Configured as a single Hex card, Storm-02 plugs directly into a standard SPC slot and, in combination with the drive, emulates DEC's RJM02 providing both software and media compatibility. The new Controller fully emulates DEC's RM02 disk system and is Unibus-compatible. It is also software-transparent to PDP-11 operating systems. What's more, Storm-02 provides media interchangeability with the RM02 since disk pack formatting is the same.

In designing Storm-02, we wanted to meet the capabilities of high data-transfer-rate, mass-storage drives while avoiding interference with other DMA hardware communications activities on the Unibus. When a DEC-based mass storage system is employed, data throughput is limited. Disk drives are limited to those with rotational speeds of 2400 rpm. In such cases data transfer suffers since it is limited to a rate of 800 kilobytes-per-second.

However, Storm-02 is capable of handling data interchange with drives running at 3600 rpm and, accordingly, a transfer rate of 1.2 megabytes per second. In doing so, the Controller allows utilization of mass storage drives having a higher data transfer rate without adversely impacting other Unibus DMA activity.

Another benefit is the ability to modify system firmware to meet the needs of other applications. This benefit will be obtained through a new product (soon to be released) allowing for any mix of 80 megabyte or 300 megabyte drives from one to four, with a single card. Other varied and specialized applications are possible by altering the card firmware.

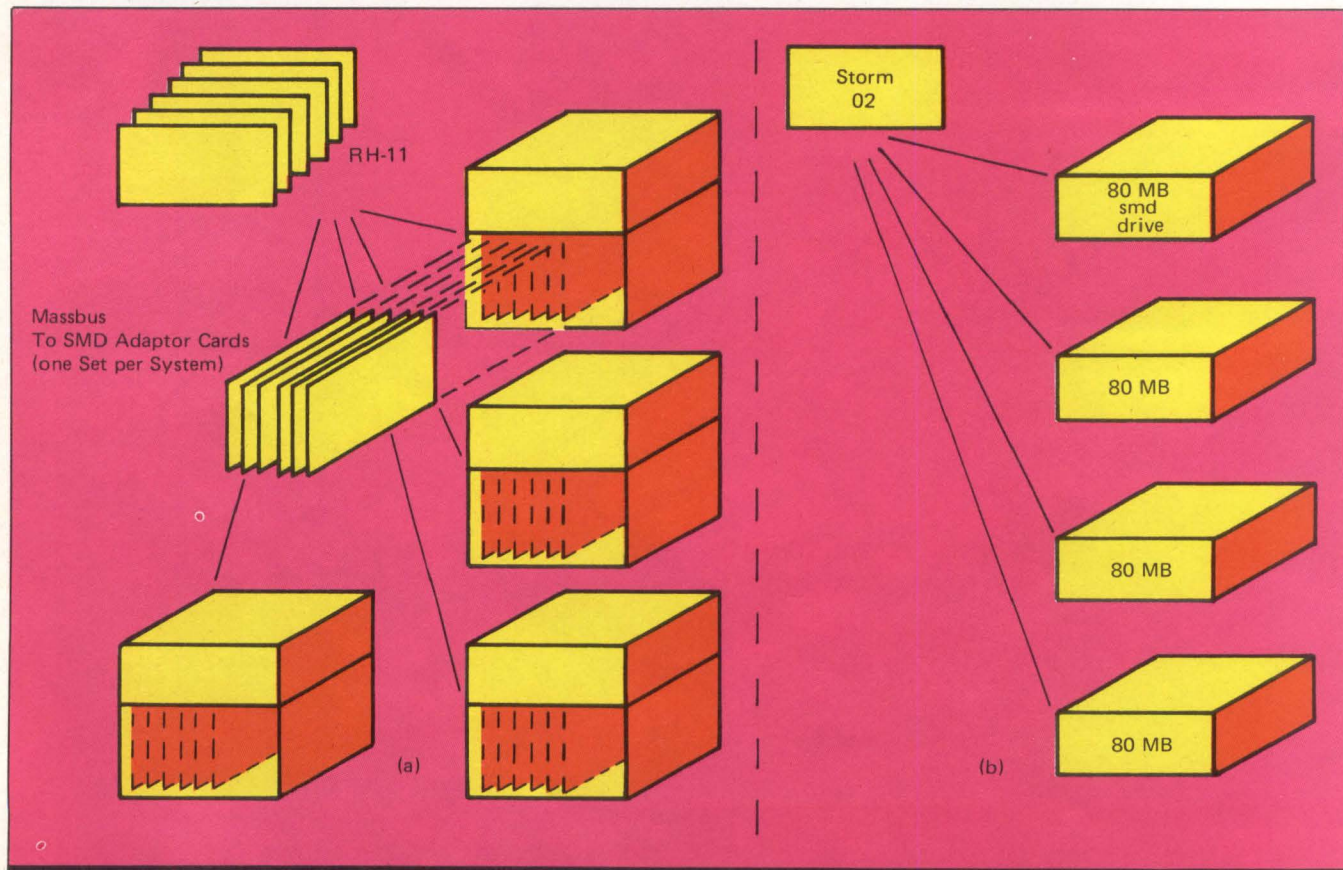
## the original system

A DEC CPU interface to a single drive is illustrated in **Figure 1**. The System consists as shown, of an RH-11 Massbus-to-Unibus adapter and an RM-02 subsystem. The latter contains the Massbus-to-SMD interface and the SMD drive interface (CDC 9762 unit) with the drive and media.

RH-11 contains the DMS (Direct Memory Access) controller and the programmed input/output function. It also provides the hardware interface between the CPU bus (Unibus) and an intermediate bus known as the Massbus. Other features include interrupt support, ability to perform a 'write check' of the data from the CPU memory and the peripheral, elastic buffering of data for the DMA transfer and special control and status registers. The elastic buffer in the original system allows for limited buffering up to 66 words (about one quarter of a sector). This hardware is contained on a complement of 6 to 7 Hex cards as illustrated in **Figure 3a**. Normally the cards are housed in the CPU mainframe, or in a separate expansion chassis.

Each RM-02 requires a 6- to 8-card Massbus-to-SMD interface adapter. As shown in Fig. 3a, a set of such cards is contained in each disk subsystem. The balance of the RM-02 subsystem contains the disk hardware, the power supply, drive and the media.

The actual system configuration selected for hardware implementation is shown in **Figure 4**. Storm-02 supports up to four 300-megabyte SMD drives. It allows for storage capacity of 80- to 300-megabytes by merely selecting or adding the drives and interconnection cables. This complete system configuration is contained in the single hex card (**Figure 2**). It replaces all cards (**Figure 3a**) ranging from 12 to 24, depending on the number of SMDs employed.



**Figure 3:** The original DEC System requires 12 to 36 Cards (as shown in a) to support up to four 80-megabyte drives. AED's STORM-02 Controller supports the same number of drives with a single card as shown in (b).

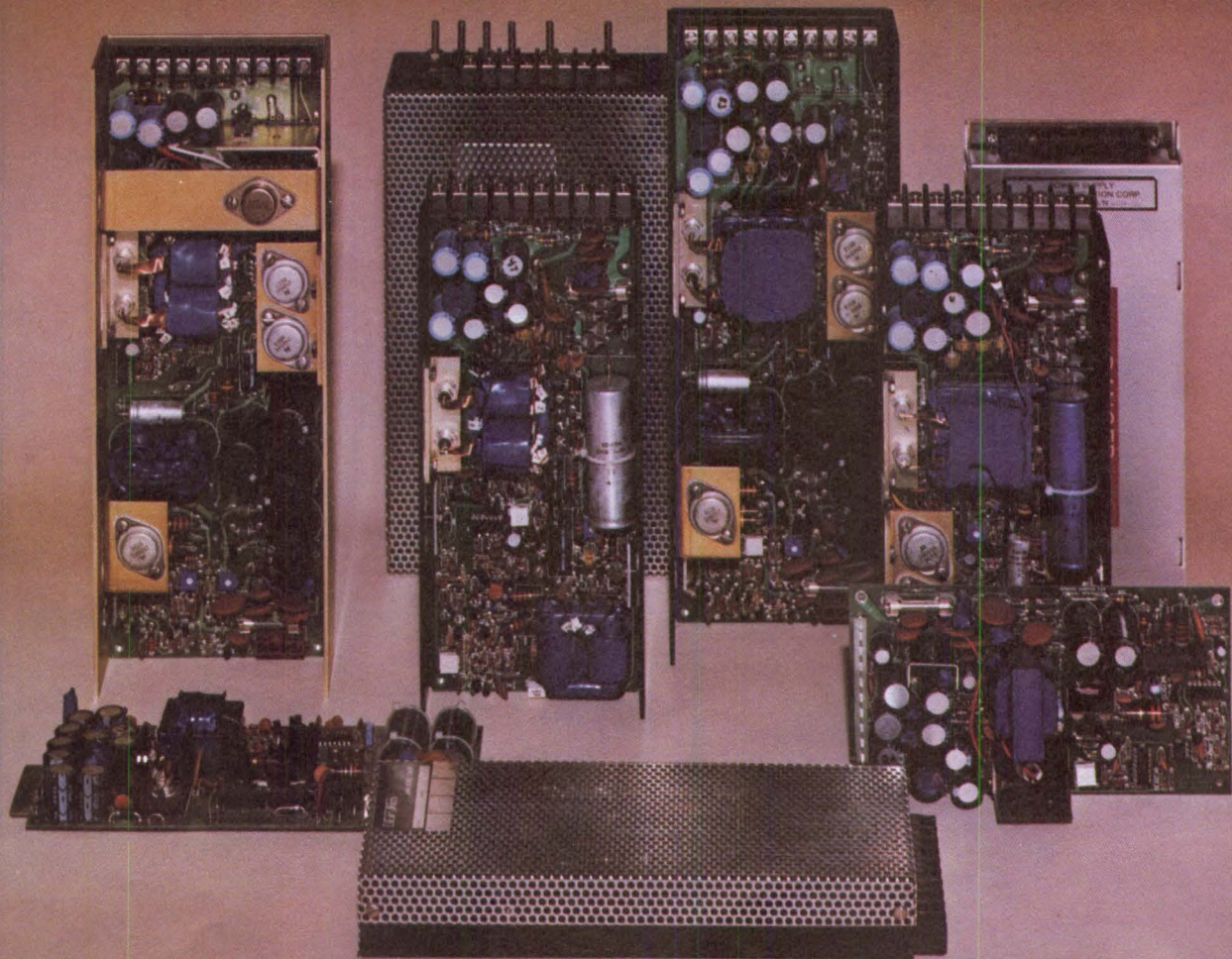


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## achieving transparency

To accomplish user transparency, the Storm-02 card had to function as in the original system. It was necessary for the hardware to electrically interface the Unibus. Also, the firmware had to cause the card to respond identically to the software commands of the RH-11/RM02 subsystem. Furthermore, the media and its pack formatting had to be the same as the original. Only then could the computer systems user proceed as if an RJM02 disk system were actually installed on the Unibus.

The software commands to which the card must respond include recognizing the positioning, data transfer, and housekeeping commands listed in **Table 1**. The Controller also had to provide the twenty-two, 16-bit Command/Status registers, the DMA buffering and the generation of the CRC (Cyclic Redundant Code) and ECC characters that are added to the sector header and data records, respectively. There had to be provisions to verify the CRC and ECC during a read and to generate the ECC syndrome. Finally, additional hardware was necessary to handle the SMD interface for one to four

### Positioning (no data transfer)

- SEEK
- RECALIBRATE (Return to zero cylinder)
- $\pm$ OFFSET
- RETURN TO CENTERLINE
- SEARCH (SEEK and find header)

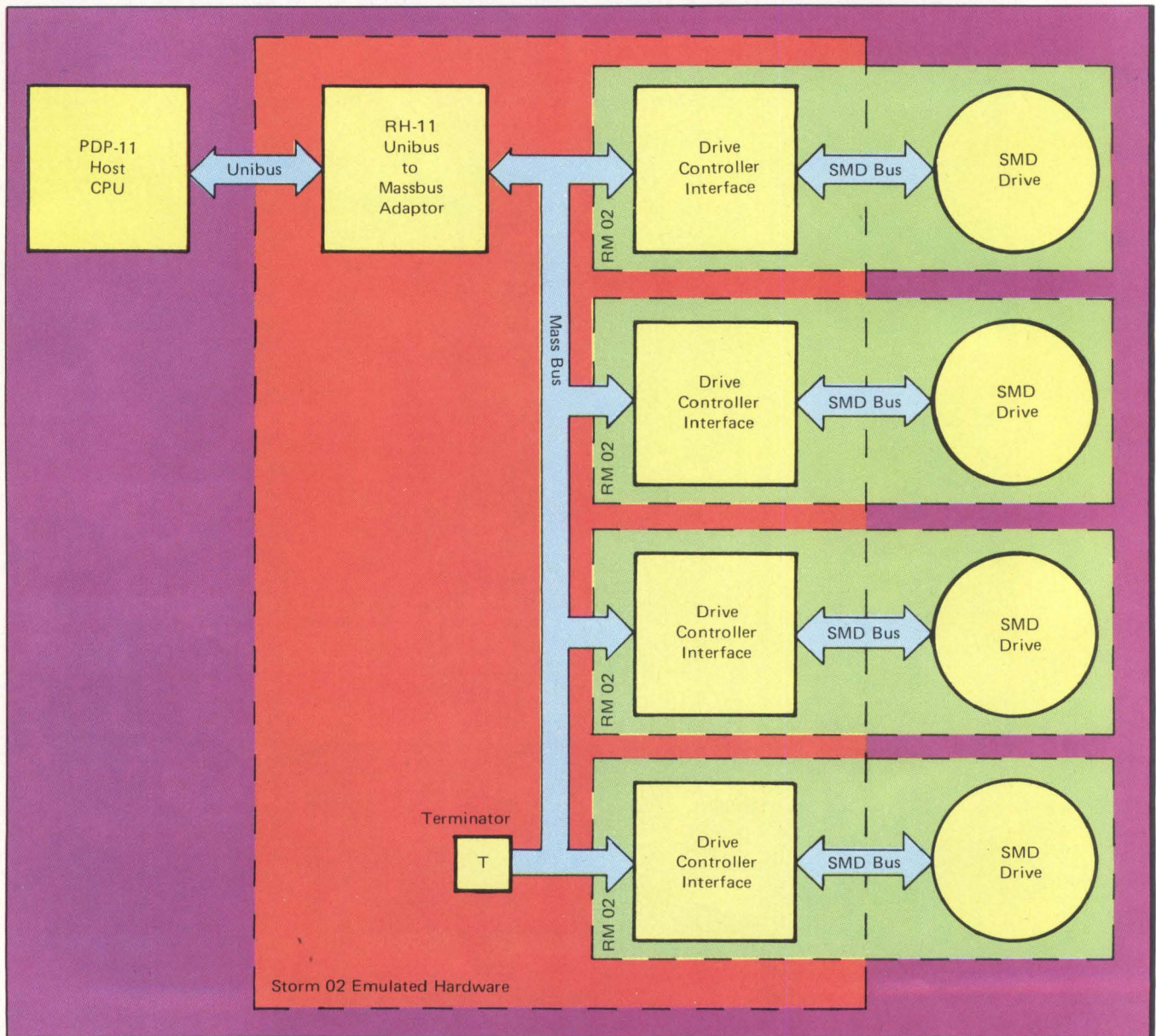
### Data Transfer Commands (DMA)

- Write header and data ("FORMAT")
- Write data only
- Write check header and data ("FORMAT VERIFY")
- Write check data only
- Read header and data
- Read data

### Housekeeping (Status Setting or Error Clearing)

- NO OP
- DRIVE CLEAR
- RELEASE (Dual Access Command)
- Read in PRESET
- Disk pack acknowledge

**Table 1: 16 Software commands that are recognized by the emulated card (identical to the RJM02 commands).**



**Figure 4: A DEC four drive configuration showing the Unibus interfaced to four disks. This configuration was selected by AED for emulation on a single HEX card, the STORM 02.**



# adac... Everything for LSI-11 data acquisition and control.

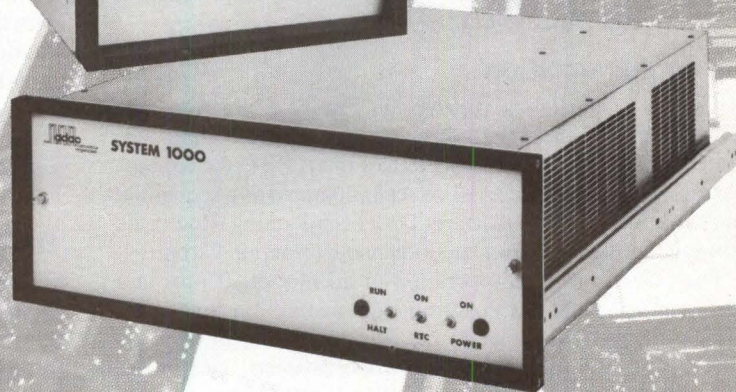
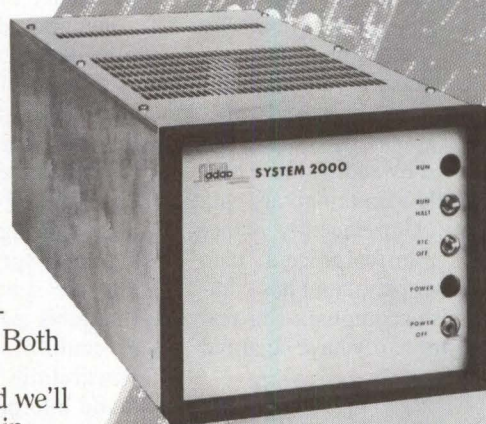
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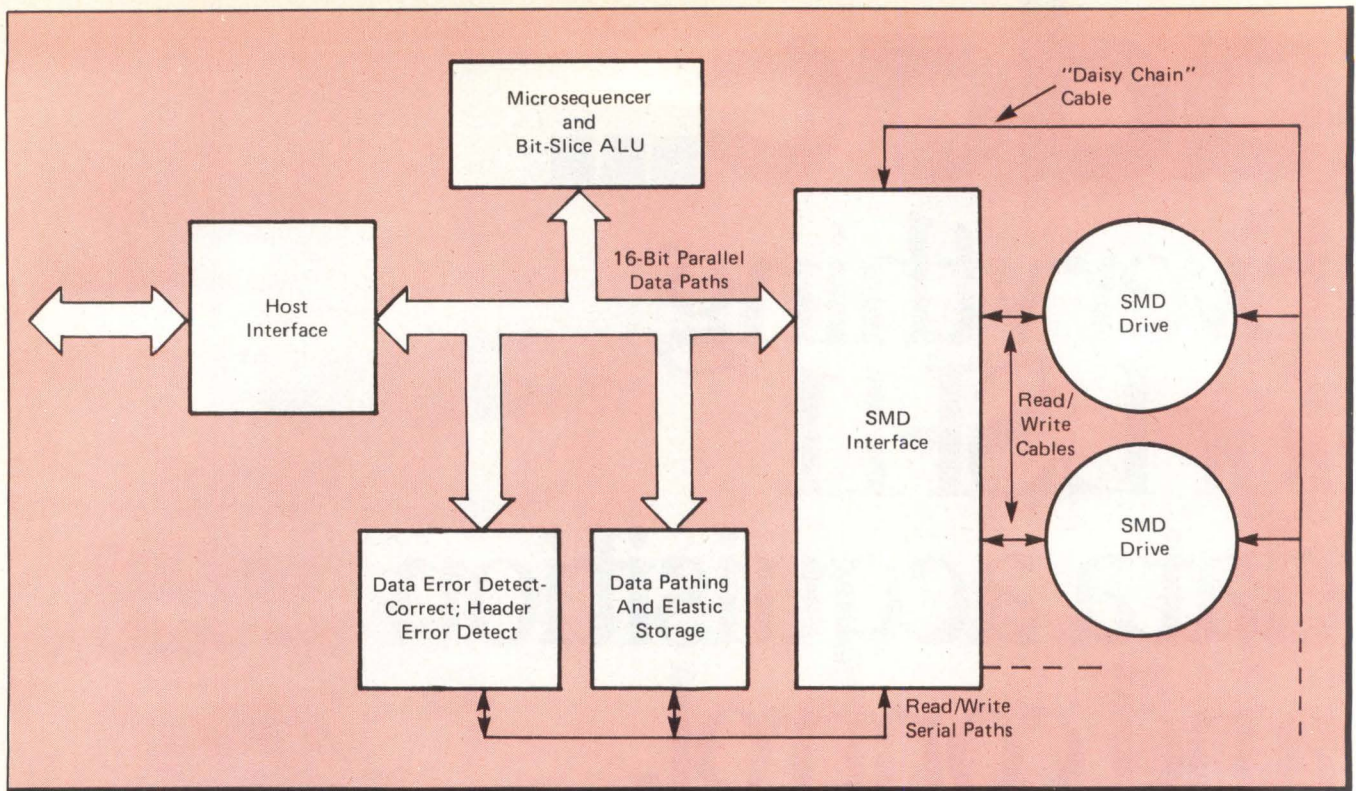


Figure 5: A system block diagram of the Bit-Slice emulation of the AED design.

drives. These consist of a common daisy-chained, parallel-drive control cable as well as the individual R/W cables. The R/W cables convey the serial read and write data along with the read, write and servo clocks and a few miscellaneous parallel control signals required for the interface.

If these criteria could be realized, the system would provide a product that is transparent to the user at both software and hardware levels.

Storm-02 emulates the interface between the DEC PDP-11 Unibus and the disk subsystem peripheral. All appropriate system software commands, test diagnostics and magnetic disk media are interchangeable with the original. The new design also allowed for a higher data transfer rate and optimizes the total system throughput from disk and other peripherals on the bus.

This optimization was accomplished by adding more buffering and additional intelligence to allow for temporary data storage within the controller card. Consequently, other peripherals can stop the long disk transfer process, then resume the data transfer when the other peripheral has completed its data transfer. All of this is accomplished in real time without loss of data that would ordinarily have occurred in the original DEC system.

### the implementation

Identified in the block diagram in Figure 5 are five subsystems implemented in the single Storm-02 Hex board controller. This subsystem includes Host Interface to the Unibus; a Microsequencer and Bit Slice ALU operated as a sequential machine; SMD Drive Interface; Disk Data-Pathing and Elastic Storage; and Data Error Detection and Correction Circuits.

The  $\mu P$  controls the operation of all blocks. It runs at a 200-ns microcycle rate enabling eight instructions to be executed with each 16-bit word that is transferred to or from the SMD. The  $\mu P$  memory is 2048 words deep, each word 56-bits wide. This memory is called the "Control Store." The processor ALU is 16 bits wide (size of the standard data

word which it must process). The Bit-Slice Elements chosen for the system are the 2900 bipolar series that include the 2901 Bit Slice ALU and 2910 microprogram sequencer chip.

The  $\mu P$  operates in classical "pipeline" fashion. That is, the control word for the next operation is brought out of memory while the function fetched from the last operation is acted upon by the  $\mu P$ . In addition, the very wide word enables sequencer, ALU, and Source and Destination Addresses to be acted upon in parallel. This results in an unusually high controller throughput speed compared to a conventional 8- or 16-Bit machine which is otherwise impeded by vertical architecture and sequential operations.

This 56-bit word is shown in Figure 6. The 11-bit address enters the control store from the 2910 sequencer. The several fields of the word are the microsequencer instruction field (10 bits), the ALU instruction field (18 bits), the immediate data field (16 bits) and the miscellaneous control field (12 bits). During each micro-instruction cycle, the entire word is available for use in the control sequences and as commands that are sent to each of the other five blocks. The actual functions performed by the  $\mu P$  are command sequencing (execution), decision-making and bookkeeping. These responsibilities can be summarized as follows: software command interpretation, sequencing SMD's (select drive, position heads, etc.), comparison of disk sector with the desired one, switching and routing of data in the data pathing block, data comparison for write verify, overall system timing, communications of status to host Interface, and error handling and recovery.

### the interfaces

The Host Interface (Figure 5) provides communications between Host CPU and Disk Controller and also implements Unibus Protocol. It contains the 22 Command/Status registers. The Host PDP-11 has full priority over these registers. The Host Interface provides the user programmable I/O addressing, interrupt priority and interrupt vector as provided



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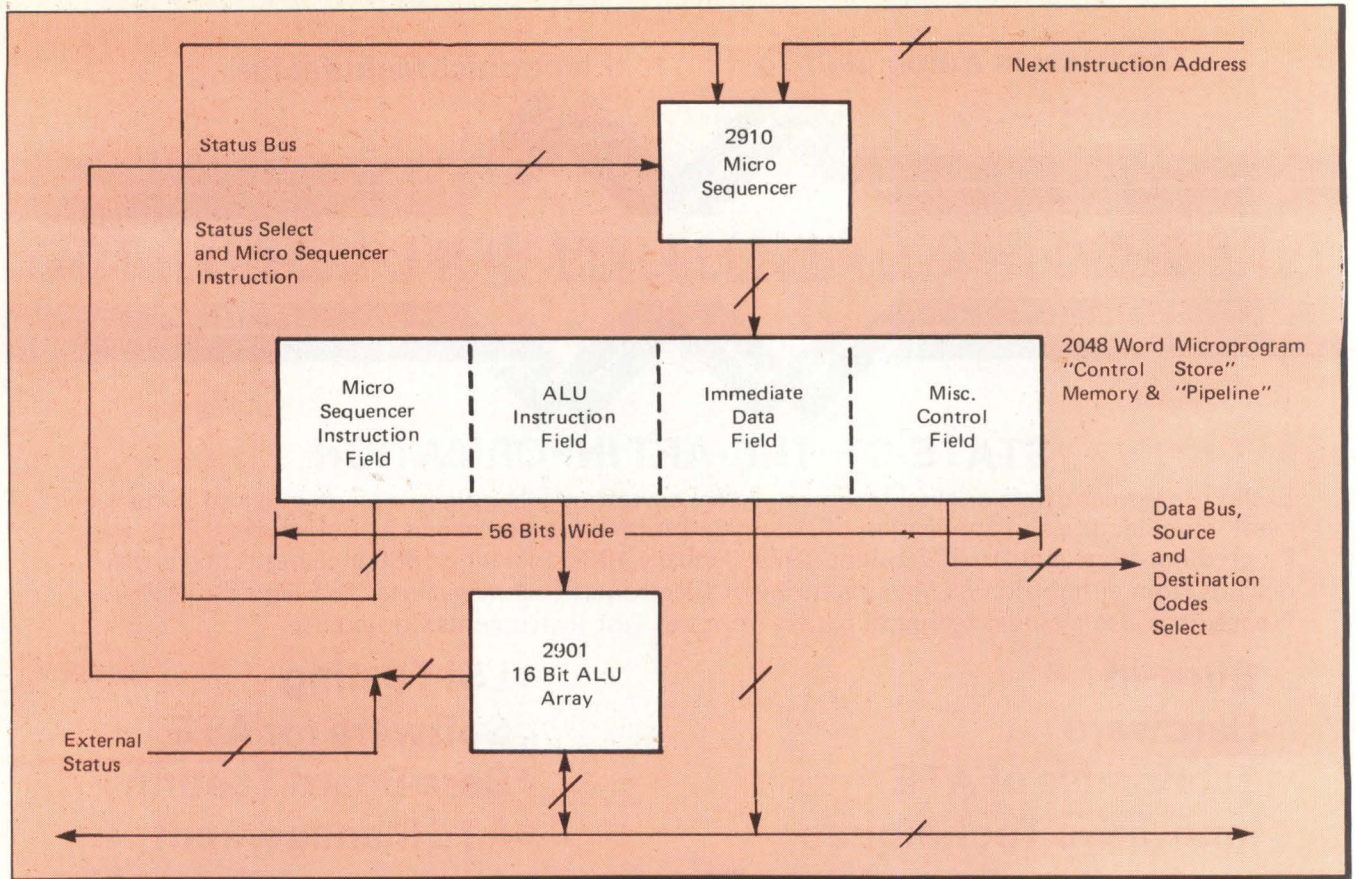


Figure 6: The 56 Bit word used for the State Sequential Bit-Slice Machine and how it ties into the system. The firmware contains up to 2048 such words that are executed in pipeline fashion.

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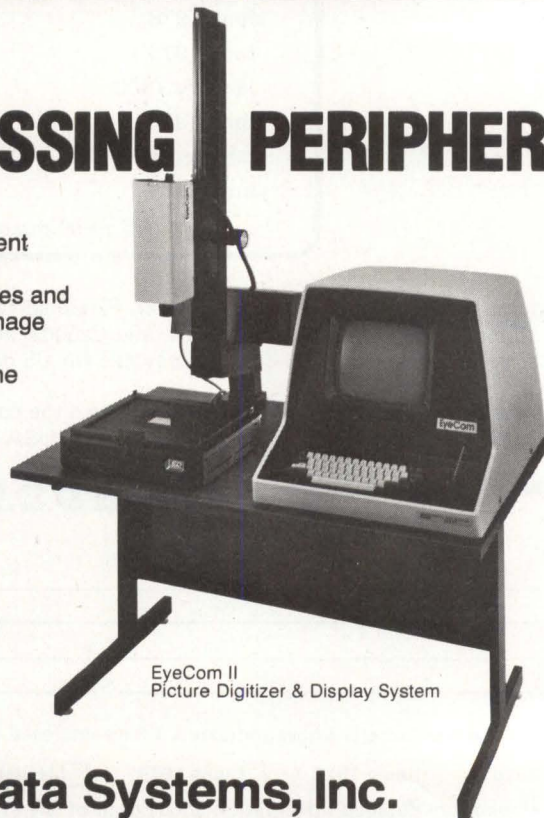
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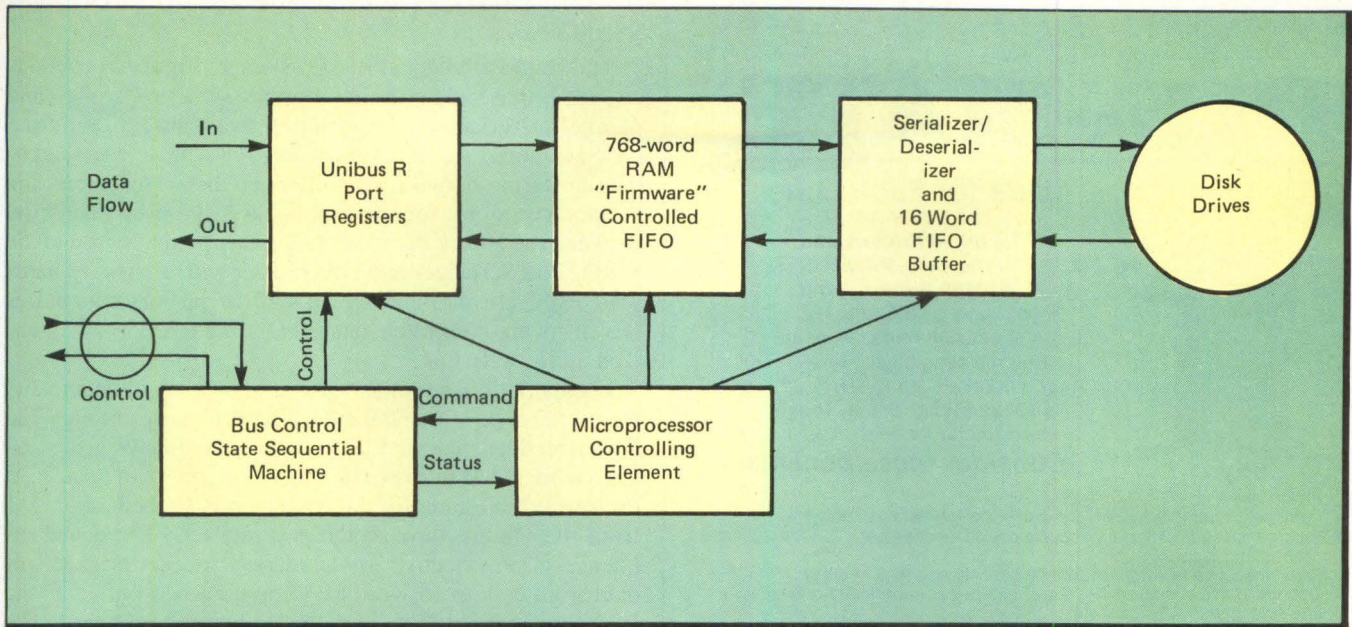


Figure 7: The "elastic" data buffering in the system. This buffering accommodates the asynchronism between the disk and the Unibus<sup>®</sup>.

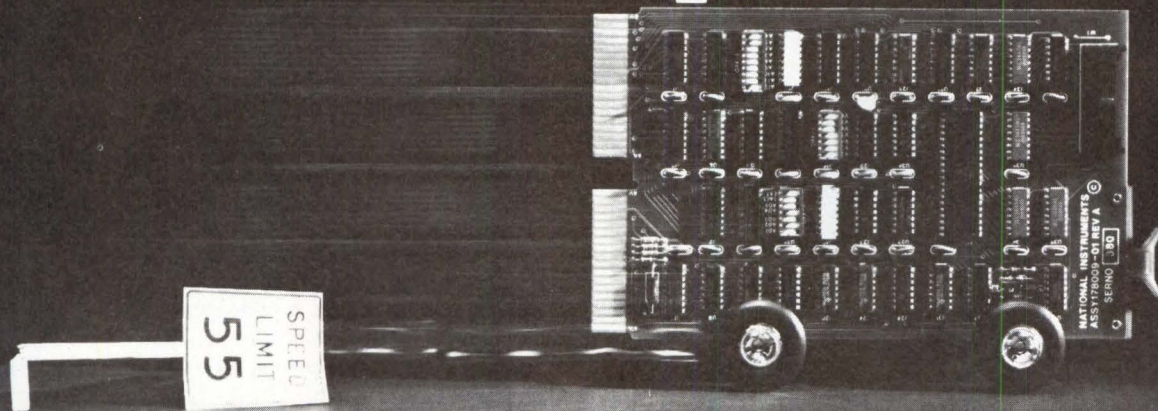
in the original DEC system. It also arbitrates DMA requests on the BUS, servicing the interrupts and generates the Unibus protocol.

Like the main  $\mu$ P the HOST Interface consists of a state sequential machine built around 4-bit binary counters with a 16-bit control word and a 100-ns cycle time. There are 256 words in its separate control memory and its operation is "pipelined" as with the main  $\mu$ P instruction bus.

The SMD Drive Interface communicates with the standard

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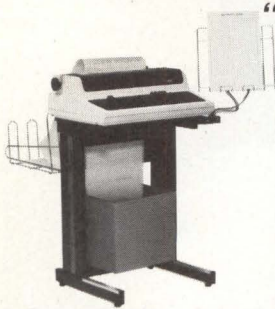
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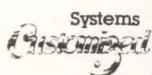
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The Data Pathing and Elastic Storage (**Figure 5**) contains circuitry that performs appropriate serial-to-parallel and parallel-to-serial conversion during data transfer to and from the SMD interface. It also provides 768 words (3 sectors) of data buffering between controller and disk. This allows the temporary storage required for the asynchronism that exists between the Host CPU's memory, other peripherals, and the SMD. The Serializer and Deserializer with a 16-word hardware FIFO are all implemented in LSI. The 768-word buffer is a firmware-controlled data FIFO using RAM array organized as  $1K \times 16$  bits.

**Figure 7** illustrates the "elastic" buffering of data to and from the disk. Data transfers bidirectionally through the Serializer/Deserializer FIFO, entering and leaving the 768 (1K) work RAM that operates under the control of the  $\mu P$ . At the appropriate time for the Unibus, it is strobed on or read from the Unibus through the port registers. The actual sequence is an effective asynchronous "bucket brigade" of data from disk to 16-word FIFO, to the RAM buffer, to the Bit-sequencer, and finally to the Unibus port on a read. The reverse data flow occurs on a disk write. This approach allows the  $\mu P$  to accommodate asynchronism within the system.

The Data and Header Error Detection and Data Correction Block (**Figure 5**) contains the circuitry to provide these functions. It has two basic sections. The first contains the Header CRC generation and checking functions and is implemented with a single LSI device. The second performs the ECC generation and checking and is implemented with MSI logic elements.

### self-test capability

It was possible to add automatic and continuous built-in-test to a large portion of the circuitry in the emulator card. The emulated system supports all pertinent DEC test diagnostics as well as performing those of its own. A thorough self-test is performed just after power-up with some continuous self-testing being performed in normal card operation. The results are displayed by on-board LEDs. This can dramatically decrease system down time to locate a failed card. Thus, it enhances the already decreased troubleshooting requirements provided by the reduction in system cards from 12 or more to just one.

Once a failed card is returned for field repair, the bad component still must be located. This is not easily accomplished with end-to-end tests. By altering the  $\mu P$ 's "Control Store" in the form of its firmware, special tests can be generated that thoroughly test the system and locate failed parts. The first approach was to generate a special set of Control Store firmware to work in conjunction with the host CPU. This ROM set is placed into the system in place of normal firmware.

During the design phase, it was recognized that a more powerful approach to testing would be of significant advantage in the system. In this case, the ability to replace the  $\mu P$  Control Firmware with an external RAM was added to the system. Now, the normal firmware would be replaced by these RAM-stored microcode diagnostic sequences that are loaded from the outboard CPU's own mass storage medium (floppy, cartridge, magnetic tape, etc.). This approach was called "Writable Control Store." With such a special fixture, far more complex testing can be done on a failed card to locate problem components. This feature is valuable to volume OEM houses that choose to purchase such a system to establish their own field repair depot. **D**



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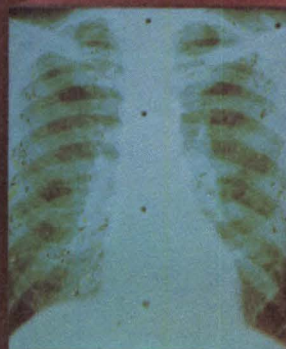
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## SIGGRAPH '81 Blends Art With Science

*dallas hosts eighth annual conference*

**F**ollowing the computer industry's rapid growth, SIGGRAPH '81 will have ten times the attendance that SIGGRAPH '74 had. And with reports painting a bright picture for computer graphics in the future, SIGGRAPH members are confident the growth trend will continue.

**By Bob Hirshon**

Computer match-making may not be the most highly regarded use of advanced digital electronics. But some of the resulting couples, as well as their progeny, have gone on to attain considerable note. The SIGGRAPH conference, held this year in Dallas, celebrates one unlikely couple, science and art, and especially their illustrious offspring, computer graphics. Representatives from both the scientific and artistic families will participate in the

celebration, featuring exhibits of state-of-the-art hardware, introductory graphics courses, and advanced technical sessions.

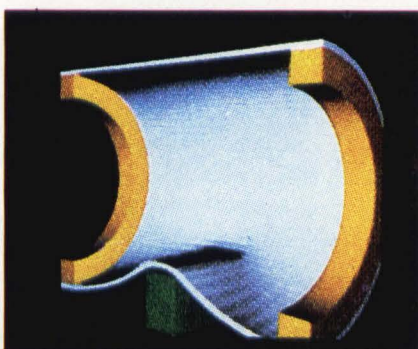
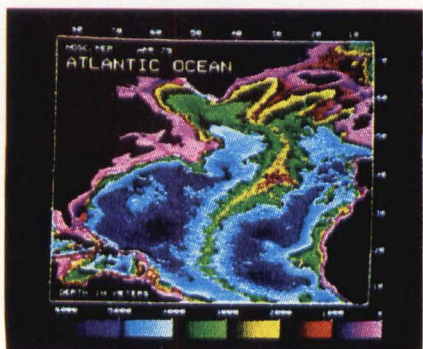
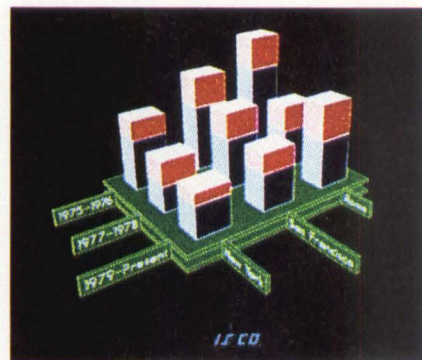
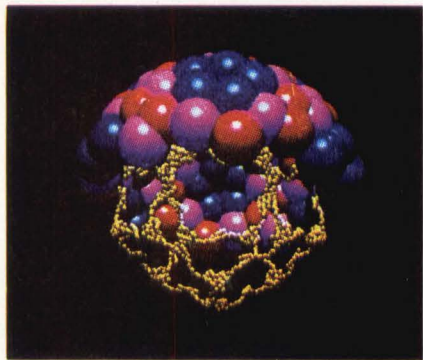
"The exhibits, which we started in the '75 conference, went from five exhibitors, that were given space, to 124 this year, covering 40,000 square feet of exhibit space," says Tony Lucido, committee co-chairman. This year's vendors will be demonstrating turnkey applications (CAD/CAM,

cartography, image processing), OEM products, film and paper hard copy devices, interactive vector and raster displays, graphical input devices, software support packages and time-sharing services.

Unlike most computer shows, SIGGRAPH's primary aim is to educate, not sell. In fact, the original show consisted only of seminars — there were no vendors at all. Today, even with exhibitors playing a large role in SIGGRAPH, education is the show's first responsibility. "We're predominantly an educational and technical group — not to the exclusion of the practitioner, but really in support of the practitioner," says Lucido. "We don't have any intentions to discard that — we intend to make sure it remains strong."

"Some of the vendors in the past," adds Doug Green, SIGGRAPH's other co-chairman, "have made the statement that they'd sure like to get as many potential paying customers as possible — but, on the other hand, we have to look to the future of the enterprise also, and make sure that the students of today are the buyers of five years from now."

During the first two days of the con-



This computer-generated art represents just a few of computer graphics' many applications. Top, left to right: Virus protein coat, Nelson Max, Lawrence Livermore National Lab; Fractal curves, Loren C. Carpenter, Boeing; 3-D bar chart, P. Preuss and A. Vinberg, ISSCO. Bottom, left to right: Atlantic Ocean Bathymetry, Larry McCleary, Naval Ocean System Center, San Diego; Steel cylinder bending over rail, Bruce Eric Brown, Lawrence Livermore National Lab; Mathematical function summation, M. Prueitt.



ference, there will be 18 one- and two-day tutorials and seminars. Tutorials are introductory courses in such topics as "How to Design User-Computer Interfaces" and "Introduction to Raster Graphics." Seminars will be somewhat more in-depth, and will include subjects such as "Introduction to Computer-Aided Design" and "Graphical CAD Systems for VSLI."

Thirty-five technical programs will be presented during the final three show-days. Each will last from one to two hours and most will be presented sequentially, allowing attendees to participate in most of the 35. Eight topic areas in computer graphics will be covered: Theory and Algorithms, Graphics Hardware, Interaction Techniques, Graphics Software and Languages, CAD/CAM, Applications, Animation, and Raster Graphics. "We received in the neighborhood of 150 papers this year," says Green. "They were reviewed by a team of reviewers and then the senior reviewers got together and the 35 best were chosen to actually be presented at the meeting."

Traditionally, evening film and videotape extravaganzas highlight SIGGRAPH, and this year will be no exception. Great pains have been taken to provide the best audiovisual equipment in ideal projection environments. Master of Ceremonies for the first of three evening shows will be Tony Lucido, of Intercomp Resource Development and Engineering, presenting an introduction to computer graphics.

On the following night, Pat Cole, of Lucasfilm, will deliver a show devoted to science and technology. "Material will be picked for how interesting the content is, for variety of techniques using computer graphics, for variety of sciences represented and for aesthetic appeal," explains Cole. "The film shows are just purely visual treats," she adds. "The content will be such that people will be able to learn something from it, but it's there mainly for the people to go and enjoy visually."

Thursday night is art and entertainment night, presented by Tom Defanti, of the University of Illinois. As an added feature, the A/V equipment in the theater will be available during lunch hours for attendees' informal showings.

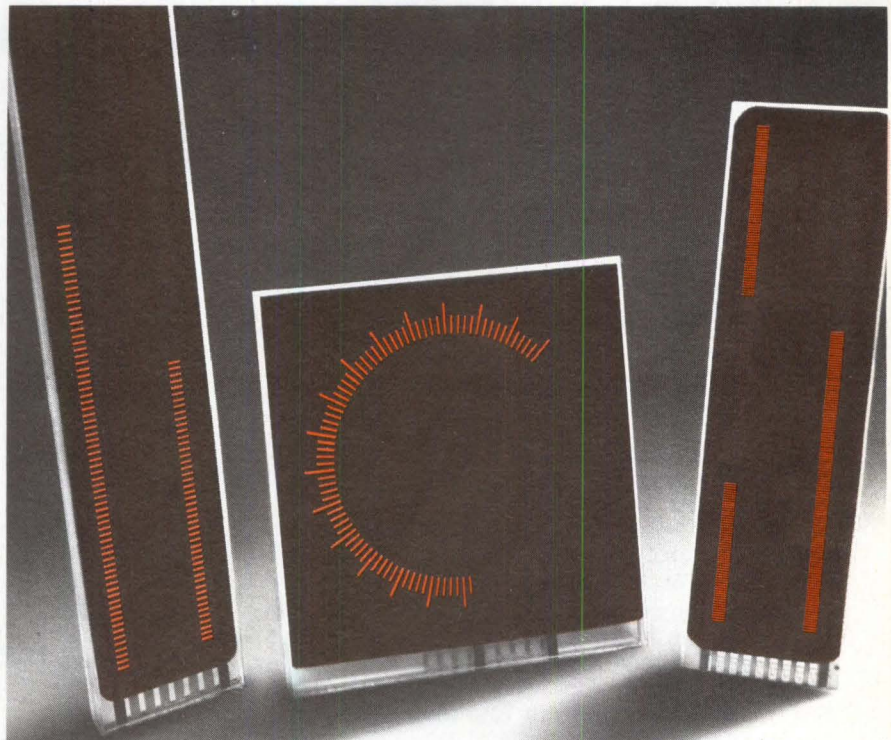
Because of the climatic conditions of Dallas in August, SIGGRAPH planners put much effort into insuring that attendees keep their cool. "We're putting on extra busses, and making sure they're all air-conditioned," says Green. "And everything is under one

roof this year; as a result, once people get to the convention center, they won't have to go out into the heat."

SIGGRAPH committee members expect about 8000 people to brave the Dallas summer and attend the conference this year. That's up about 20% from last year. What's behind this rapid growth? "Graphics is one of those things that has previously been very expensive," explains Green, "but with the cost of memory and the cost of computer display systems coming down so rapidly, it's becoming much

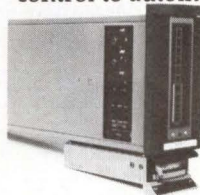
more affordable to a larger number of folks. Three or four years ago, the number of attendees who actually owned systems was fairly modest, because of the high cost. The cost factor is the driving factor behind the tremendous growth we've had."

This rapid growth has brought its share of problems, says Lucido, but nothing the committee can't handle. "It's grown fast enough so there have been growth pains," Lucido sums up, "but I think it's all been for the benefit of graphics." D



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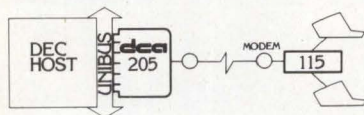
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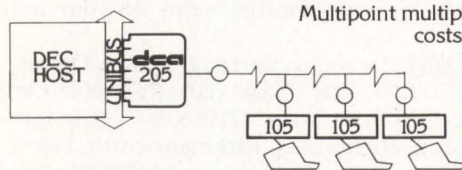
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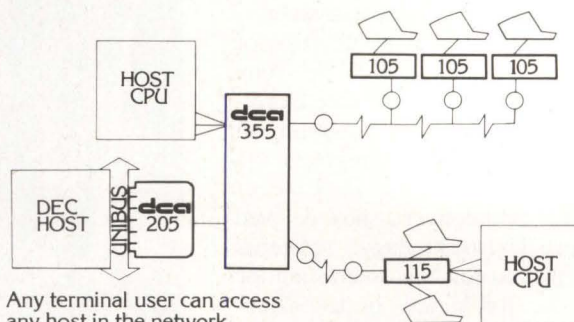
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# Cyclic Code Redundancy

## "designers' guide" protects data

**N**one of the methods described here will detect all possible errors that could occur in a data transfer system. The effectiveness of a code is a measure of how low the probability is that an error could get through the code system undetected.

Cyclic Redundancy Code or CRC-based systems have different effectiveness factors dependent on randomness of data transferred and on the actual generator polynomial used. Storage systems impose their own characteristics in determining randomness of errors, and thus which method of error detection to employ.

CRC-16 is most common in data communications and in disk applications because it is especially effective where errors are more likely to occur in bursts. Where errors are more likely to be single-bit, or two-bit errors, LRC may prove equally effective. Checksums are used to protect assembler object code integrity in development software, since it is virtually independent of the storage media, and also since it is relatively easy to generate and check.

The four-bit CRC algorithm described offers a good trade-off between execution speed and memory usage for applications that include data communications controllers mini-floppy disk controllers, tape controllers and many more. The approach outlined can be used to advantage in any computer that facilitates table look-up.

**By Rich Lee**

This article describes an efficient and effective means of accomplishing the task of error detection using Cyclic Redundancy Codes, (CRC). The principles described are generally applicable.

### **CRC background**

Codes are usually described in mathematics as closed sets of values that comprise all the allowed number sequences in the code. In data communications, transmitted numbers are essentially random data patterns which are not related to any predetermined code set. The sequence of data, then, is forced into compliance with the code set by adding to it at the transmitter. Thus, a string of original data would become the original string concatenated with a string of extra numbers that make the total string one of allowed code set values.

At the receiver, incoming data is checked to see if it is one of the allowed code set values. The assumption is made that if an error occurred in transmission, likelihood of the result also being a valid set member is very low. If the received data string is found to be of the allowed code set, it is assumed that no errors have occurred and that the data is valid.

Several points have emerged from the above discussion. (1) There is a need to have a scheme of determining what precise extra string to append to the original data stream, to make the concatenation of transmitted data a valid member of the code set. (2) There must be a consistent way of extracting the original data from the code value at the receiver, to deliver the actual data to the location where it is ultimately used. (3) For the code scheme to be effective, the set must contain allowed values sufficiently different from one another that expected errors will not be able to alter one allowed value such that it becomes a different allowed value of the code set.

A system for coding and detecting errors in common use in Data Communications and in systems using serial data storage devices is called CRC. The code set is made up of all strings of binary data that are evenly divisible by what is referred to as a "generator polynomial" — a specially selected number that results in a code set of values different enough from one another to achieve a certain low probability

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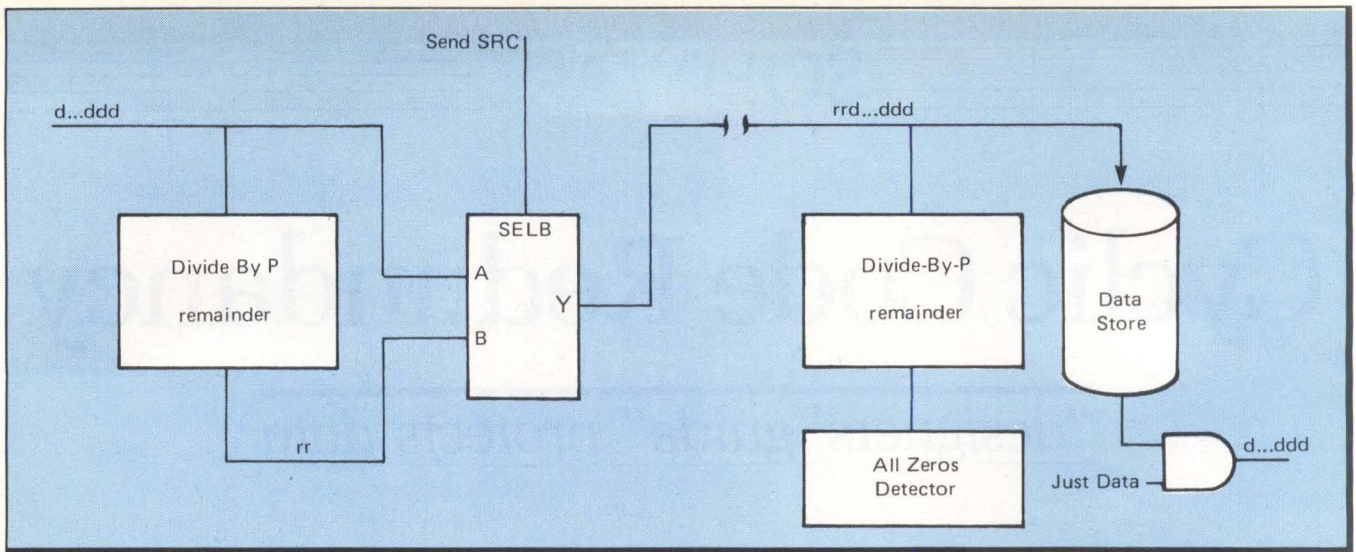


Figure 1: Error detection system.

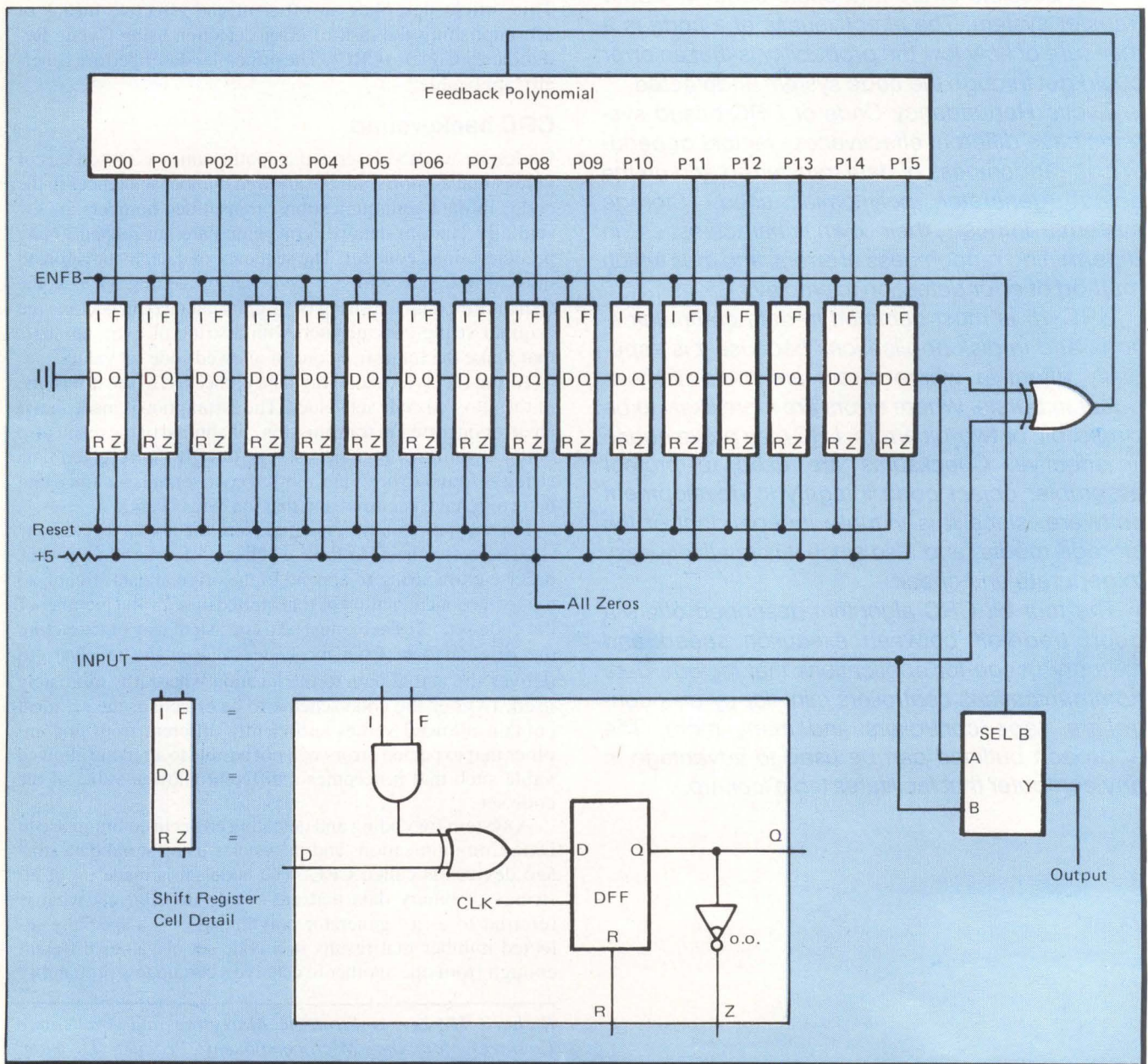


Figure 2: Register implementation.



other to achieve a certain low probability of an undetected error. To determine what to append to the string of original data, a division is made of the original string as it is being transmitted. When the last data is past, the remainder from the division is the required string to add since the string including the remainder will be evenly divisible by the generator polynomial. Since the generator polynomial is of a known length, the remainder added to the original string is of a fixed length.

At the receiver, the incoming string is divided by the generator polynomial, and if the incoming string does not divide evenly — that is if the remainder after division is not zero — then an error is assumed to have occurred. If the remainder is zero, then the data is assumed to be error free, and the data delivered to the ultimate destination is the incoming data with the fixed length remainder field removed. **Figure 1** illustrates the stages of this coding method.

In binary CRC schemes, the generator polynomial is designated as a sum of terms of "X" raised to the power of the bit the term represents. For example, the CRC-16 generator polynomial is actually the binary number, 1 1000 0000 0000 0101, while it is customary to represent it with the following expression:  $x^{16} + x^{15} + x^2 + x^0$ .

### shift register implementation

The division process is simpler in modulo-two arithmetic than it is in decimal arithmetic. Implementation of a divider for a 17-bit polynomial can be done using a 16-bit shift register with an exclusive-OR feedback gate for each term of the polynomial, except the most significant bit, (bit 16). The exclusive-OR gate that corresponds to bit 16 of the polynomial is the one with one input connected to the rightmost shift register bit and the other input connected to the incoming data stream. Input. The output of this gate is used to turn the feedback on and off to the rest of the shift register. **Figure 2** shows the classical shift register circuit used to perform the division for the case of the CRC-16 polynomial. To generate the remainder for transmission, the shift register is first preset to all zeros. The serial data is shifted in at the point marked Input. When the end of the data is reached, the final contents of the shift register are appended to the serial data stream by lowering the feedback enable input labelled ENFB. The stream thus generated is a member of the CRC-16 code set, since it is evenly divisible by

|         |     |             |  |                             |
|---------|-----|-------------|--|-----------------------------|
| FLAGGS: | EQU | 4           |  | ;FLAG REGISTER              |
| MSKCRC: | EQU | 1           |  | ;MASK FOR CRC FLAG POSITION |
| CRCU:   | EQU | 6           |  | ;UPPER CRC BYTE             |
| CRCL:   | EQU | 5           |  | ;LOWER CRC BYTE             |
| POLYU:  | EQU | H'AO'       |  | ;POLYNOMIAL <0-7>           |
| POLYL:  | EQU | H'01'       |  | ;POLYNOMIAL <8-15>          |
| GPO:    | EQU | 0           |  | ;TEMPORARY DATA STORAGE     |
|         |     |             |  |                             |
|         |     |             |  | CRC ONE-BIT SHIFT ALGORITHM |
|         |     |             |  | DATA IN GPO                 |
| CRCSHF: | LR  | K,P         |  | ;SAVE RETURN ADDRESS        |
|         | LI  | .NOT.MSKCRC |  | ;RESET CRC FLAG             |
|         | NS  | FLAGS       |  |                             |
|         | LR  | FLAGS,A     |  |                             |
|         |     |             |  |                             |
|         | LR  | A,GPO       |  | ;PICK UP DATA               |
|         | XS  | CRCL        |  | ;XOR WITH LOWER CRC BIT     |
|         | NI  | 1           |  | ;ONLY USE LOWEST BIT        |
|         | BZ  | CRC1        |  | ;BRANCH AROUND FLAG SET     |
|         |     |             |  | IF 0                        |
|         |     |             |  |                             |
|         | LR  | A,FLAGS     |  | ;SET CRC FLAG               |
|         | OI  | MSKCRC      |  |                             |
|         | LR  | FLAGS,A     |  |                             |
| CRC1:   | EQU | \$          |  |                             |
|         |     |             |  |                             |
|         |     |             |  |                             |
|         | LR  | A,CRCL      |  | ;SHIFT LOWER CRC BYTE       |
|         | SR  | 1           |  |                             |
|         | LR  | CRCL,A      |  |                             |
|         |     |             |  |                             |
|         | LIS | 1           |  | ;PROPAGATE UPPER BYTE LSB   |
|         |     |             |  | TO LOWER BYTE MSB           |
|         | NS  | CRCU        |  |                             |
|         | BZ  | CRC2        |  | ;BRANCH IF THE BIT IS 0     |
|         |     |             |  |                             |
|         | LR  | A,CRL       |  | ;ELSE SET CRCL MSB          |
|         | OI  | H'80        |  |                             |
|         | LR  | CRCL,A      |  |                             |
|         |     |             |  |                             |
| CRC2:   | LR  | A,CRCU      |  | ;SHIFT UPPER BYTE           |
|         | SR  | 1           |  |                             |
|         | LR  | CRCU,A      |  |                             |
|         |     |             |  |                             |
|         | LI  | MSKCRC      |  | ;TEST CRC FLAG FOR XOR OF   |
|         |     |             |  | POLY                        |
|         | NS  | FLAGS       |  |                             |
|         | BA  | CRC3        |  | ;BRANCH IF FLAG NOT SET     |
|         |     |             |  |                             |
|         | LI  | POLYL       |  | ;XOR LOWER PART             |
|         | XS  | CRCU        |  |                             |
|         | LR  | CRCU,A      |  |                             |
|         |     |             |  |                             |
| CRC3:   | PK  |             |  | ;RETURN POINT               |

Figure 3: CRC Shift Software Implementation

the polynomial.

The box in **Figure 2** labeled FEEDBACK POLYNOMIAL is an AND gate array. The output signals PXX refer to the X terms in the polynomial. CRC-16 would have the outputs, P00, P02 and P15 enabled such that when the input went high, those outputs would go high but the other outputs would not go high. In applications not requiring more than one polynomial, much of the

indicated circuitry could be eliminated. This example is intended to be general enough to handle any seventeen term CRC polynomial, simply by enabling the appropriate PXX outputs. The shift register cells are shown in detail in the insert at the bottom of the figure. The inverter inside the detail is used when testing the contents of the shift register for zero at the end of the receive operation.



| Input  | Feedback | CRC-16 Value After Shift Clock |      |      |      |
|--|----------|--------------------------------|------|------|------|
| 0  | 0        | 0000                           | 0000 | 0000 | 0000 |
| 1  | 1        | 1010                           | 0000 | 0000 | 0001 |
| 0  | 1        | 1111                           | 0000 | 0000 | 0001 |
| 1  | 0        | 0111                           | 1000 | 0000 | 0000 |
| 1  | 1        | 1001                           | 1100 | 0000 | 0001 |
| 0  | 1        | 1110                           | 1110 | 0000 | 0001 |
| 0  | 1        | 1101                           | 0111 | 0000 | 0001 |
| 1  | 0        | 0110                           | 1011 | 1000 | 0000 |
| 0  | 0        | 0011                           | 0101 | 1100 | 0000 |
| 1  | 1        | 1011                           | 1010 | 1110 | 0001 |
| 1  | 0        | 0101                           | 1101 | 0111 | 0000 |
| 0  | 0        | 0010                           | 1110 | 1011 | 1000 |
| 0  | 0        | 0001                           | 0111 | 0101 | 1100 |
| 0  | 0        | 0000                           | 1011 | 1010 | 1110 |
| 1  | 1        | 1010                           | 0101 | 1101 | 0110 |
| 1  | 1        | 1111                           | 0010 | 1110 | 1010 |
| 0  | 0        | 0111                           | 1001 | 0111 | 0101 |
| (Input value from this point is current shift register contents) |          |                                |      |      |      |
| 1  | 0        | 0011                           | 1100 | 1011 | 1010 |
| 0  | 0        | 0001                           | 1110 | 0101 | 1101 |
| 1  | 0        | 0000                           | 1111 | 0010 | 1110 |
| 0  | 0        | 0000                           | 0111 | 1001 | 0111 |
| 1  | 0        | 0000                           | 0011 | 1100 | 1011 |
| 1  | 0        | 0000                           | 0001 | 1110 | 0101 |
| 1  | 0        | 0000                           | 0000 | 1111 | 0010 |
| 0  | 0        | 0000                           | 0000 | 0111 | 1001 |
| 1  | 0        | 0000                           | 0000 | 0011 | 1100 |
| 0  | 0        | 0000                           | 0000 | 0001 | 1110 |
| 0  | 0        | 0000                           | 0000 | 0000 | 1111 |
| 1  | 0        | 0000                           | 0000 | 0000 | 0111 |
| 1  | 0        | 0000                           | 0000 | 0000 | 0011 |
| 1  | 0        | 0000                           | 0000 | 0000 | 0001 |
| 1  | 0        | 0000                           | 0000 | 0000 | 0000 |
| 0  | 0        | 0000                           | 0000 | 0000 | 0000 |

Figure 4: CRC shift table

The selector in the lower right hand portion of **Figure 2** is used to select the data on the signal labelled INPUT to be forwarded to the OUTPUT line, while the shift register is accumulating the CRC. The shift register contents are selected at the same time as the feedback enable is removed when it is desired to concatenate the CRC value to the data stream. The rightmost bit in the shift register is the first to be shifted out.

The shift register can also be implemented with a software algorithm. Assembly language is used to define the algorithm (**Figure 3**). Like the hardware implementation, the software algorithm also accommodates any polynomial.

By altering the value in the equation for POLYU and POLYL, any CRC generator polynomial can be facilitated. It is necessary to call the subroutine for each bit of data. As this routine may take up to 111  $\mu$ s to execute with a 4-MHz clock, the software implementation is often only useful for slower data transmission rates. The calling program is responsible for initializing the values of CRCU and CRCL, shifting each bit of data, and making the call to CRCSHF for each data bit. When the end of data is reached, the calling program places the CRC bytes into the data stream, CRCL first, followed by CRCU.

The table of **Figure 4** shows the values taken on by the shift register in the single bit shift approach in response to the input stream in the left column. The feedback gating, generated by the exclusive-OR of input data with the rightmost bit of the register, is shown in the next column. Notice its value in the lower half. Each line of the table shows the register contents after the clocking takes place. These values are the same whether the hardware or the software implementation is used.

### classical implementations

The hardware implementation of the single shift logic is usually fast enough for most applications. There are components made with selectable polynomials integrated into a single chip. The main drawbacks to hardware implementation are inherent cost, and single-sourcing of most single chip hardware. The drawbacks to software emulation center

| After First Shift |       | After Second Shift |       | After Third Shift |       | After Fourth Shift |       |
|-------------------|-------|--------------------|-------|-------------------|-------|--------------------|-------|
| F(0)              |       | F(1)               |       | F(2)              |       | F(3)               |       |
| F(0).XOR          | C(15) | F(1).XOR.          | C(15) | F(0).XOR.         | F(2)  | F(1).XOR.          | F(3)  |
|                   | C(14) | F(0).XOR.          | C(14) | F(1).XOR.         | C(15) | F(0).XOR.          | F(2)  |
|                   | C(12) |                    | C(13) | F(0).XOR.         | C(14) | F(1).XOR.          | C(15) |
|                   | C(11) |                    | C(12) |                   | C(13) | F(0).XOR.          | C(14) |
|                   | C(10) |                    | C(11) |                   | C(12) |                    | C(13) |
|                   | C(09) |                    | C(10) |                   | C(11) |                    | C(12) |
|                   | C(08) |                    | C(09) |                   | C(10) |                    | C(11) |
|                   | C(07) |                    | C(08) |                   | C(09) |                    | C(10) |
|                   | C(06) |                    | C(07) |                   | C(08) |                    | C(09) |
|                   | C(05) |                    | C(06) |                   | C(07) |                    | C(08) |
|                   | C(04) |                    | C(05) |                   | C(06) |                    | C(07) |
|                   | C(03) |                    | C(04) |                   | C(05) |                    | C(06) |
|                   | C(02) |                    | C(03) |                   | C(04) |                    | C(05) |
| F(0).XOR.         | C(01) | F(1).XOR.          | C(02) | F(2).XOR.         | C(03) | F(3).XOR.          | C(04) |

Figure 5: Four Bit CRC-16 Shift Table



| T(3) | T(2) | T(1) | T(0) | E(15) | E(14) | E(13) | E(12) | E(11) | E(10) | E(09) | E(08) | E(07) | E(06) | E(05) | E(04) | E(03) | E(02) | E(01) | E(00) |
|------|------|------|------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 0    | 0    | 0    | 0    | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 0    | 0    | 0    | 1    | 1     | 1     | 0     | 0     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 1     |
| 0    | 0    | 1    | 0    | 1     | 1     | 0     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 1     |
| 0    | 0    | 1    | 1    | 0     | 0     | 1     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 0    | 1    | 0    | 0    | 1     | 1     | 1     | 1     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 1     |
| 0    | 1    | 0    | 1    | 0     | 0     | 1     | 1     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 0    | 1    | 1    | 0    | 0     | 0     | 1     | 0     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 0    | 1    | 1    | 1    | 1     | 1     | 1     | 0     | 0     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 1     |
| 1    | 0    | 0    | 0    | 1     | 0     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 1     |
| 1    | 0    | 0    | 1    | 0     | 1     | 1     | 0     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 1    | 0    | 1    | 0    | 0     | 1     | 1     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 1    | 0    | 1    | 1    | 1     | 0     | 1     | 1     | 1     | 0     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 1     |
| 1    | 1    | 0    | 0    | 0     | 1     | 0     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 1    | 1    | 0    | 1    | 1     | 0     | 0     | 1     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 1     |
| 1    | 1    | 1    | 0    | 1     | 1     | 0     | 0     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 1    | 1    | 1    | 1    | 0     | 1     | 0     | 0     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 1     |
| 1    | 1    | 1    | 1    | 1     | 1     | 0     | 0     | 0     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 1    | 1    | 1    | 1    | 0     | 1     | 0     | 0     | 0     | 0     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |

Figure 6: Four Bit CRC-16 Look-up Table

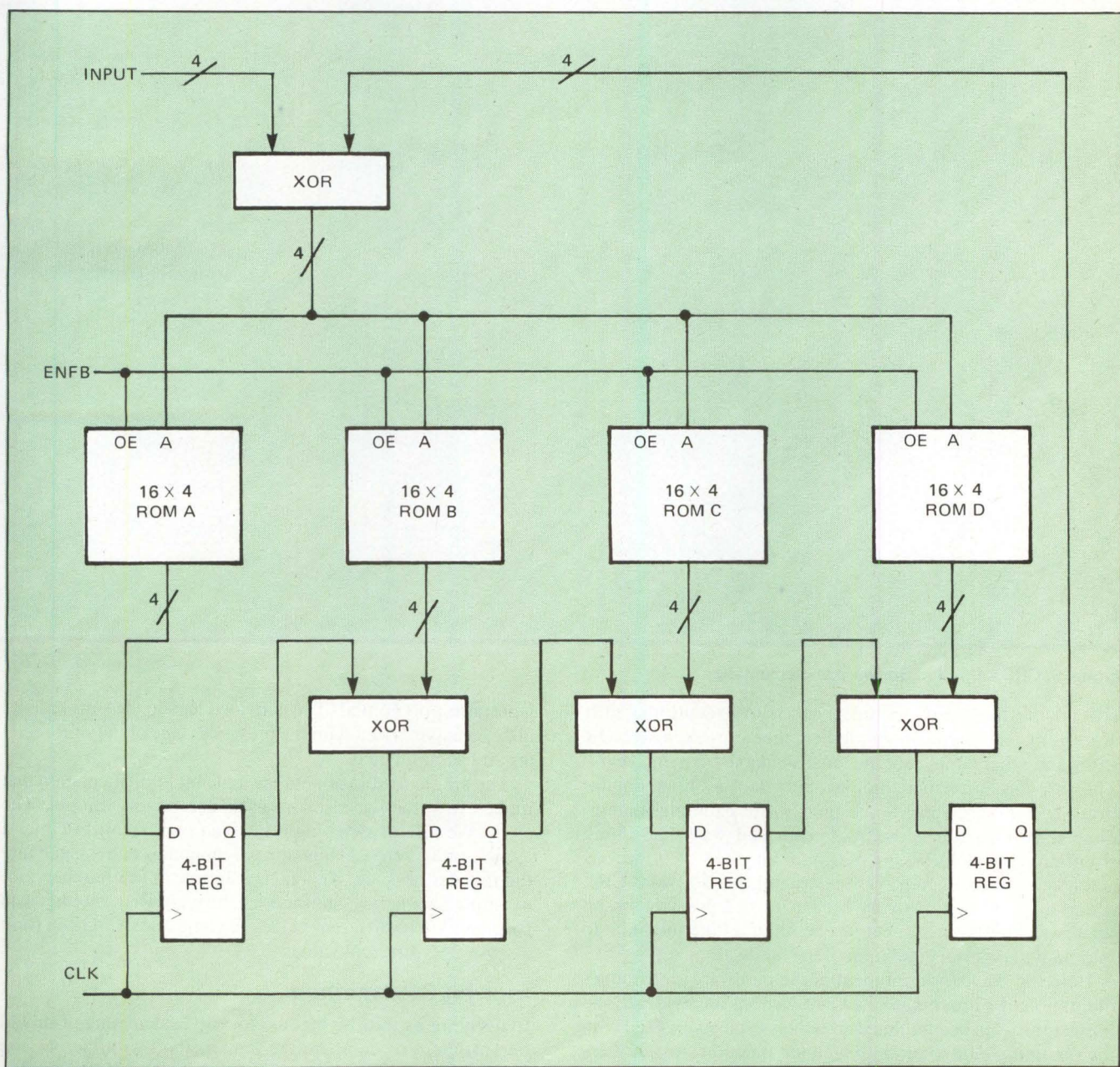


Figure 7. Four-bit shift CRC hardware implementation.



```

CRCU:
CRCL:
GPO:
GP1:
GP2:
.....
CRC4BT:
.....
CRC FOUR-BIT SHIFT ALGORITHM
DATA IN GPO
LR          K,P
DCI         TCRC16
XS          A,GPO
NI          CRCL
SL          HFO
ADC         1
LM          GP2,A
LR          GP1,A
LM          A,CRCL
LR          4
SR          CRCL,A
LR          A,CRCU
SL          4
XS          CRCL
XS          GP1
LR          CRCL,A
LR          A,CRCU
SR          4
XS          GP2
LR          CRCU,A
.....
FIRST NIBBLE SHIFT IS DONE
DCI         TCRC16
LR          A,GPO
SR          4
XS          CRCL
NI          HFO
SL          1
ADC         GP2,A
LM          GP1,A
LR          A,CRCL
SR          4
LR          CRCL,A
LR          A,CRCU
.....
UPPER CRC BYTE
LOWER CRC BYTE
TEMPORARY DATA STORAGE
.....
SAVE RETURN ADDRESS
SET DATA COUNTER TO BASE OF TABLE
FORM INDEX INTO TABLE
XOR DATA AND LOW NIBBLE OF CRC
.....
2 BYTE TABLE
LOOK-UP TABLE ENTRY
READ TABLE
STORE E(15)-E(08) IN GP2
E(07) THROUGH E(00) IN GP1
SHIFT LOWER HALF OF CRC RIGHT 4
.....
APPEND PART FROM UPPER HALF
MERGE TWO PARTS TOGETHER
DO THE XOR WITH TABLE VALUE
LOWER HALF IS DONE
SHIFT UPPER HALF
DO XOR WITH TABLE VALUE
UPPER PART DONE
.....
SET DATA COUNTER TO BASE OF TABLE
FORM INDEX INTO TABLE
THIS ONE IS FOR THE UPPER NIBBLE
XOR DATA AND LOW NIBBLE OR CRC
.....
2 BYTE TABLE
LOOK-UP TABLE ENTRY
READ TABLE
STORE E(15)-E(08) IN GP2
E(07) THROUGH E(00) IN GP1
SHIFT LOWER HALF OF CRC RIGHT 4
.....
APPEND PART FROM UPPER HALF

```

Figure 8: CRC 4-Bit Shift Software Implementation

around the large cost in time needed to execute the shift algorithm. The hardware implementation uses exclusive-OR gates and other simple components available for many years. The software implementation actually does a "blind emulation" of the hardware. Some micros, for example, manipulate data in a much more sophisticated way than doing simple exclusive-ORs and shifting a bit at a time. There is actually very little gained by restricting the software CRC accumulation function to one bit at a time. A possible reason for restricting the treatment to one bit at a time might be to maintain very strict emulation of the hardware.

Looking back for a moment at the hardware shift implementation of **Figure 2**, a few key functions are evident. The least significant accumulated amount is exclusive-ORed with the incoming data to produce a gating function that activates the feedback paths. The result of the gating function from above activates a feedback pattern that depends strictly on the

generator polynomial. The activated legs to the shift register are exclusive-ORed with the previous stage of the shift register and accumulated.

The single feature about the single bit implementation that makes it attractive also makes it deceptively simple. The exclusive-OR of two single bits can only result in either a "one" or a "zero". Thus, the polynomial is either gated into the register or is not. This fact is not true of hex numbers, for example. Two hex numbers exclusive-ORed together can form any of 16 different values. Bytes exclusive-ORed form a set of 256 different values.

#### four-bit CRC method

In deriving a multi-bit method for CRC calculating, it should be sufficient to compare the new method with the old and show that the differences are in implementation only and do not alter the function. This is true, since shifting several bits







| T(3) | T(2) | T(1) | T(0) | E(15) | E(14) | E(13) | E(12) | E(11) | E(10) | E(09) | E(08) | E(07) | E(06) | E(05) | E(04) | E(03) | E(02) | E(01) | E(00) |
|------|------|------|------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 0    | 0    | 0    | 0    | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 0    | 0    | 0    | 1    | 0     | 0     | 0     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 0    | 0    | 1    | 0    | 0     | 0     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 0    | 0    | 1    | 1    | 0     | 0     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 0    | 1    | 0    | 0    | 0     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 0    | 1    | 0    | 1    | 0     | 1     | 0     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 0    | 1    | 1    | 0    | 0     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 0    | 1    | 1    | 1    | 0     | 1     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 1    | 0    | 0    | 0    | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 1    | 0    | 0    | 1    | 1     | 0     | 0     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 1    | 0    | 1    | 0    | 1     | 0     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 1    | 0    | 1    | 1    | 1     | 0     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 1    | 1    | 0    | 0    | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 1    | 1    | 0    | 1    | 1     | 1     | 0     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 1    | 1    | 1    | 0    | 1     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 1    | 1    | 1    | 1    | 1     | 1     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |
| 1    | 1    | 1    | 1    | 1     | 1     | 1     | 1     | 1     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |

Figure 9: Four Bit LRC-16 Look-Up Table

**T**he four bit CRC algorithm described in this article offers a good trade off between execution speed and memory usage for applications that include data communications controllers, mini-floppy disk controllers, tape controllers and many more.

```

CRCU: EQU 6 ;UPPER CRC BYTE
CRCL: EQU 5 ;LOWER CRC BYTE
GPO: EQU 0 ;TEMPORARY DATA STORAGE

;
; CRC EIGHT-BIT SHIFT ALGORITHM
; DATA IN GPO
; CRC TABLE IS STORED LOWER BYTE BEFORE UPPER BYTE TO
; MAKE THIS IMPLEMENTATION FASTER
;
CRC8BT: LR K,P ;SAVE RETURN ADDRESS
;
; DCI T8CR16 ;SET DATA COUNTER TO BASE
; OF TABLE
; LR A,GPO ;FORM INDEX INTO TABLE
; XS CRCL ;XOR DATA AND LOW BYTE
; OF CRC
; BM MXOR ;UPPER HALF OF TABLE
; IF MINUS
;
; SL 1 ;FORM INDEX TO 2-BYTE TABLE
; BM MSHL ;2ND QUADRANT OF TABLE
; IF MINUS
;
; ADC ;ELSE 1ST QUADRANT OF
; TABLE
; LR A,CRCU ;XOR UPPER CRC WITH LOWER
; BYTE
; XM ; FROM TABLE
; LR CRCL,A ;SHIFT RIGHT 8
; LM ;GET UPPER BYTE FROM TABLE
; LR CRCU,A ;REPLACES UPPER CRC BYTE
; PK ;THIS LEG TAKES 33.5 CYCLES
;
MSOR: SL 1 ;FORM INDEX TO 2-BYTE TABLE
; BM MSXL ;FOURTH QUADRANT OF TABLE
; IF MINUS
;
; ADC ;ELSE THIRD QUADRANT
; LI H'40' ;OFFSET TO THIRD QUADRANT
; ADC ;
; ADC ;
; NEXT SECTION REPEATED IN THE INTEREST OF SPEED
; LR A,CRCU ;XOR UPPER CRC WITH LOWER
; BYTE
; XM ; FROM TABLE
; LR CRCL,A ;SHIFT RIGHT 8
; LM ;GET UPPER BYTE FROM
; TABLE
; LR CRCU,A ;REPLACES UPPER CRC BYTE
;
; PK ;THIS LEG TAKES 41.5 CYCLES

```

Figure 10: CRC 8-Bit Shift Software Implementation



hardware implementation, while **Figure 8** shows the software approach. The hardware implementation is shown mainly for reference and would not offer a great improvement in cost effectiveness over the single-bit shift approach.

The boxes in **Figure 7** marked XOR are 7486's, or equivalent. The ROMs and 4-bit registers are best implemented with  $32 \times 8$  PROMs and 8-bit D-flip-flops, such as 74288s and 74273s. For CRC-16, ROM A and ROM B contain the portion of the table of **Figure 6** designated E(15) through E(08), while ROM C and ROM D are programmed with E(07) through E(00). Each shift of the clock accomplishes what four clock shifts did in the implementation in **Figure 2**.

This implementation takes eight ICs, not counting those required for testing for all zeros. An advantage gained by this approach is that readily available parts are used throughout, and cycling at a 5-MHz clock rate would yield an equivalent data rate of 20 Mbits/sec.

The software implementation is a straightforward emulation of the hardware implementation of **Figure 7**. The table is the same as that in **Figure 6** for CRC-16. A different generator polynomial would require a different table, but the rest of the routine would be the same.

The software implementation is listed in **Figure 8**. The routine, including the CRC-16 table, takes up 84 bytes of memory. CRC4BT is called once for each byte of data and executes in 150  $\mu$ s in a K3870 with a 4 MHz crystal. This is six times as fast as the single bit shift routine listed in **Figure 3**, which occupies 42 bytes of memory. The speed improvement realized using the four-bit method permits  $\mu$ Cs to play an even more important role in data communications applications, where data rates up to 9600 Baud can be readily protected with CRC.

Let's consider some of the variations and alternatives for data protection.

### eight-bit shift algorithm

We covered the grouping of the basic CRC shift algorithm into four bits at a time. It is also possible to gain additional speed at the expense of memory usage by extending the approach to eight bits. The hardware would use two eight-bit exclusive-OR gates, two eight-bit registers, and a 256X16 ROM.

**Figure 10** lists the software routine for implementing the eight bit approach. The 256X16 table is built by first continuing the symbolic shift procedure, outlined in **Figure 5**, until the eighth shift. This produces the following list after eighth shift.

```

F(7)
F(6)
F(5).XOR.F(7)
F(4).XOR.F(6)

F(3).XOR.F(5)
F(2).XOR.F(4)
F(1).XOR.F(3)
F(0).XOR.F(2)

F(1).XOR.C(15)
F(0).XOR.C(14)
      C(13)
      C(12)

      C(11)
      C(10)
      C(09)
F(7).XOR.C(08)

```

Then, as before, the next step is to build the generator expressions for the F functions in terms of the T functions as follows:

$$\begin{aligned}
 F(0) &= T(0) \text{ where } T(i) = I(i).XOR.C(i) \\
 F(1) &= T(1).XOR.T(0) \\
 F(6) &= \\
 &T(6).XOR.T(5).XOR.T(4).XOR.T(3).XOR.T(2).XOR. \\
 &T(1).XOR.T(0) \\
 F(7) &= \\
 &T(7).XOR.T(6).XOR.T(5).XOR.T(4).XOR.T(3).XOR. \\
 &T(2).XOR.T(1).XOR.T(0) \text{ and} \\
 F(5).XOR.F(7) &= T(7).XOR.T(6) \\
 F(4).XOR.F(6) &= T(6).XOR.T(5) \\
 F(3).XOR.F(5) &= T(5).XOR.T(4) \\
 F(2).XOR.F(4) &= T(4).XOR.T(3) \\
 F(1).XOR.F(3) &= T(3).XOR.T(2) \\
 F(0).XOR.F(2) &= T(2).XOR.T(1)
 \end{aligned}$$

The table is generated by computing parity over the address, as indicated in the above expressions, letting each T term refer to the corresponding table address bit, (assuming the table base address to be zero). The C terms without coefficients in the list are assumed to have zero entries in the table, and so the corresponding column in the table would be filled with zeros.

The eight-bit routine shown in **Figure 10** executes in an average of about 82  $\mu$ s/byte, or about 45% faster than the four-bit method. Memory usage for the eight bit routine plus one look-up table is 568 bytes.

### LRC

LRC, Longitudinal Redundancy Code, is a special case of CRC where the particular polynomial chosen results in the same CRC code as would be obtained by doing a 16-bit wide exclusive-OR once every 16 bits. If the data stream were represented as a succession of 16-bit words, the LRC code added to the end of the stream would equal the first word exclusive-ORed with the second, exclusive-ORed with the third, and so on. When the check is made at the receiver, the result is zero if no errors occurred, since the exclusive-OR of anything with itself is zero.

LRC is also often done on an eight-bit word length, since software implementation is a little bit simpler than with sixteen bits. LRC, a form of CRC, can be handled by the CRC implementations discussed in this article. The polynomial for LRC-16 is  $X(16)+1$ ; and that for LRC-8 is  $X(8)+1$ . A table for LRC-16 in the four-bit implementation of section 2 could be constructed in the same way as the table for CRC-16 was done. The result is in **Figure 9**.

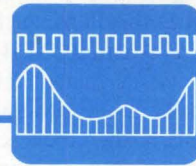
### checksum

The checksum — an accumulation of the remainder of modulo 256 addition of a string of data organized in bytes — is a method of error detection in widespread use throughout the  $\mu$ C industry since it is easily-generated and is very effective in detecting errors. Often, in the case of data which is coded into ASCII characters that represent the data in hexadecimal form, the checksum is taken over the values of the hex numbers rather than over the actual bit patterns themselves.

Typically, the initial value of the eight-bit checksum is minus one. This is so that when zero occurs often in the data, the effectiveness of the code is not diminished. Thus, when the checksum has been taken over received data, the final value is minus one — not zero. D



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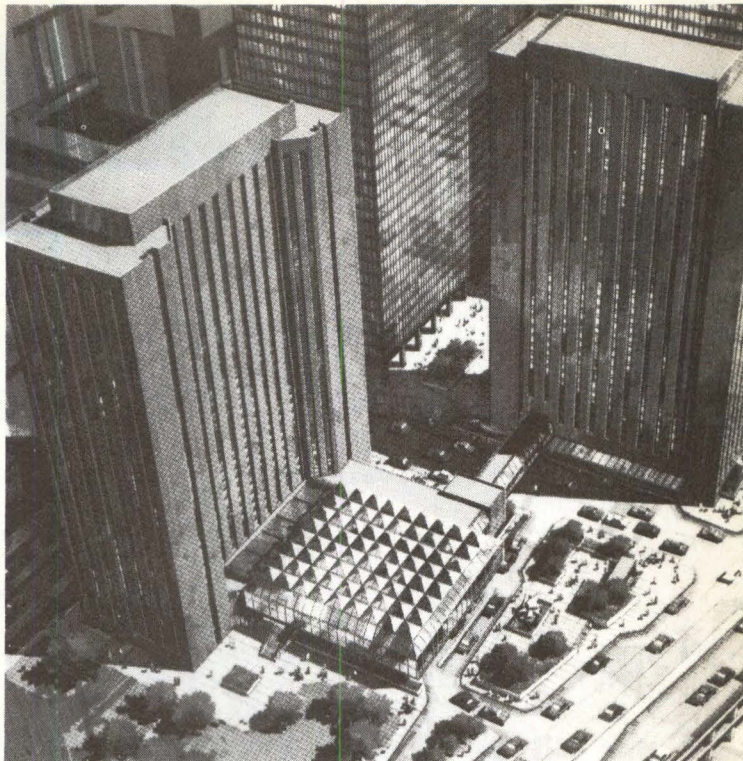
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Now you can harness the power of your DEC minicomputer for Intel 8086  $\mu$ P software development. PasPort is a cross-compiler developed by Intermetrics, Inc. that eliminates the need for "brute-force" software development. Rather than muscling out programs with multiple Microprocessor Development Systems (MDSs), PasPort allows you to develop software on any PDP-11 minicomputer systems running under UNIX or RSX-11M operating systems.

According to Ron Kole, manager of Intermetrics' Software Products Division, most developers have access to corporate mainframes or laboratory minis. By using them for software development, relying on an MDS only for final testing and integration, companies can save the price of several MDSs—quite a savings, considering MDSs cost from \$15K to \$25K each.

PasPort uses Pascal language conforming to the International Standards Organization (ISO) proposal. It supports comprehensive diagnostic capabilities, via an interpretive language, allowing the user to test application software on the host before sending it on to the MDS. This allows use of the many tools inherent in PDP-11 systems, including file management, source control systems, archives, large disks and high-speed printers. In addition, running PasPort on a multi-user host allows sharing of files and procedures; separately compiled routines can then interact via parameter passing or through global data areas.

PasPort consists of three segments: Compilation, Host Run-Time Support, and Target Run-Time Support.

### compilation

Compilation is essentially an error-checking process. The idea is to take the original Pascal algorithm created by the developer and translate it into a lower level, so that it can run on the PDP-11. First, the compilation process checks for syntactic errors (illegal

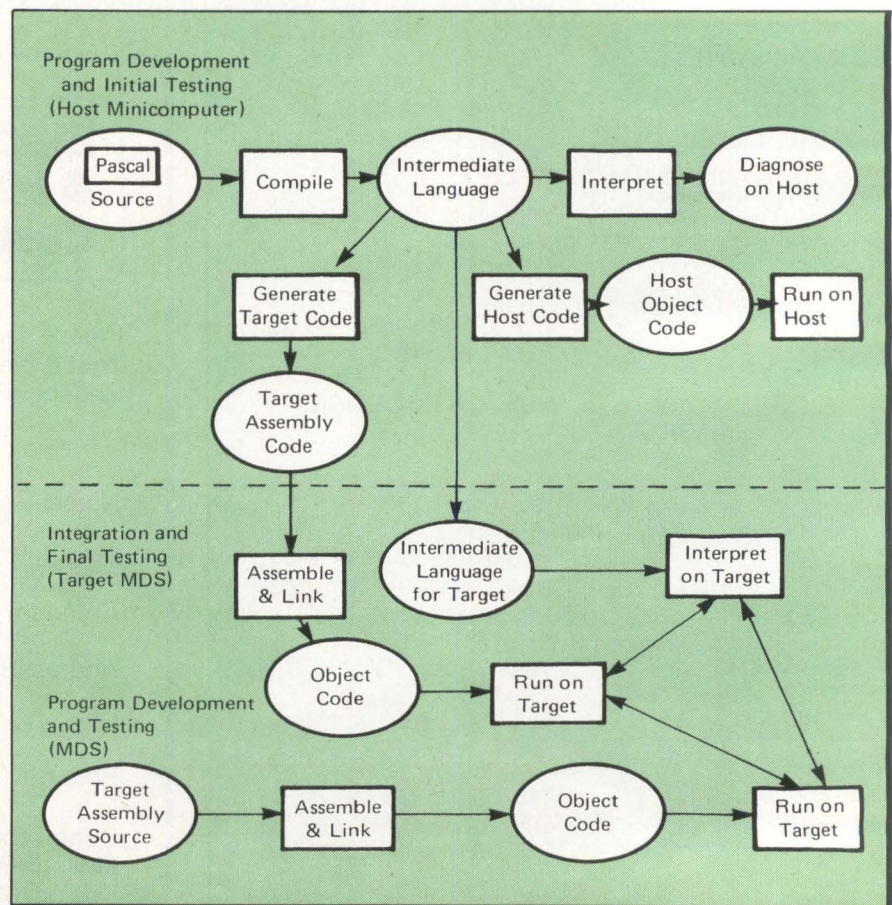
sentences and punctuation) and semantic errors (sentences that don't make sense), creating error messages to indicate where in the program the errors are. In addition, it lets the developer know if there are any variables he hasn't used, or if a variable hasn't been given a value. If the program checks out, the compiler then converts it to intermediate language, which is an object representation for a virtual machine; this intermediate form is similar, but more compact, than the standard P-code. PasPort compilation rates commonly reach 2000 to 3000 lines per minute.

### host run-time support

The next step is to run the program on the PDP-11 "in an environment that is

hostile to your program," as Kole puts it. "If you attempt to do anything in that program in any way fishy or illegal, you'd sure like to know about it, and that's the whole point of running it on the host," he explains. "Traditionally, this was done on the MDS, but it's very difficult, while you're running on the actual hardware, to get a lot of checking going on."

In addition to automatic dynamic checking, other run-time diagnostic features are available as options. A "profiler" records which source lines executed and how many times they were executed, so the developer knows which program paths have been tested. Also produced is an estimate of how much execution time each source statement required, revealing which





parts of the program are most time-consuming.

An option for UNIX system owners allows users to generate PDP-11 instructions from the Pascal program; a complete run-time library for this option is provided.

### target run-time support

"We certainly don't claim that you can do all your debugging on a PDP-11," says Kole. "Once you finish the host debugging phase, you still have to prove that the program works on the 8086."

PasPort provides two paths for moving the program from the host to the MDS. One is to send the intermediate language, with minor translation, to the MDS where there's a PasPort interpreter that will execute it on the 8086. This provides streamlined, efficient execution, without error-checking. The

other path consists of translating the intermediate language on the host into real 8086 instruction. Most users prefer this direct code because it is more time efficient, and it allows them to see the code directly. However, the slower, interpretive, intermediate code is more compact, and is suitable for non-time critical applications.

Intermetrics aims PasPort at a wide range of companies with expanding software development teams. "The target audience," explains Kole, "is really industrial companies that are finding that  $\mu$ Ps are the right thing for them in a product; this includes anywhere from 50-100 person companies that are building a new gadget to large companies that make a product of some kind which they are putting out with more capabilities."

Will software developers, accustomed to the control they have with an

MDS, accept the PasPort system? "Some software developers," answers Kole, "consider themselves craftsmen and artists and they will never want to give up twiddling those bits. But what they should realize is that PasPort actually allows them to become more creative, because they are freed from the detailed level of every instruction on the machine to really turn their attention toward solving a problem."

PasPort 8086 costs \$15K, and comes with a user's manual and the ISO Pascal draft standard reference manual. PasPorts available for other microprocessors (tentatively, Motorola's 68000 and Zilog's Z8000) will be available in the future.

by Bob Hirshon

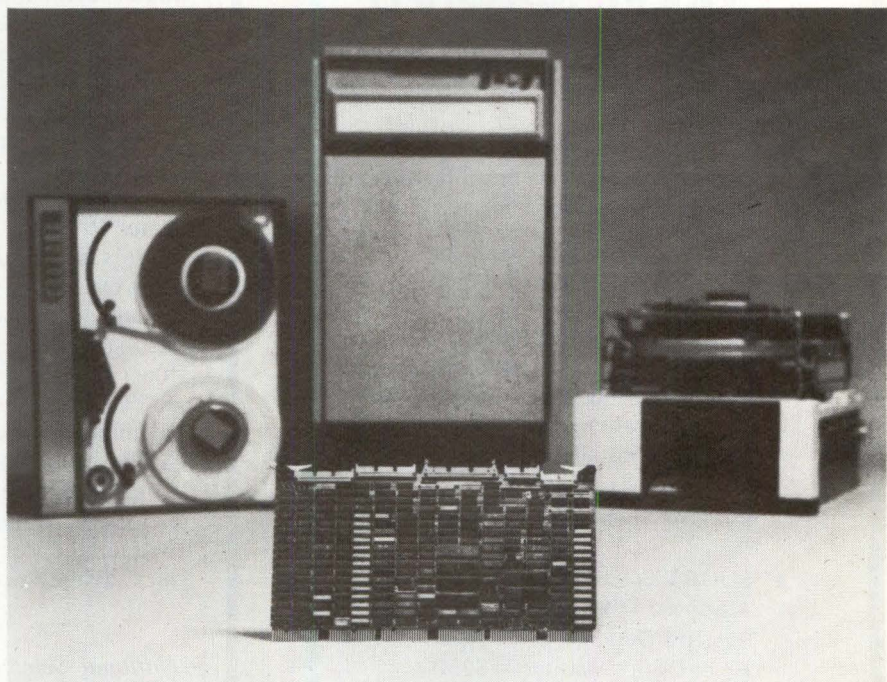
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## Compatible Multifunction Controllers Deliver Backplane Breathing Room

The design freedom one extra card slot provides system designers can be priceless, often saving considerable design time, hardware expense (expansion chassis and bus repeaters), and aspirin. One indication of how valuable that space is will be provided by the sales figures for multifunction controller boards introduced by Spectra Logic and National Semiconductor.

Spectra Logic's Spectra 20 and Spectra 21 handle removable pack or Winchester SMD disk drives and start/stop or streaming half-inch tape drives simultaneously, all on one board. Both models attach up to four SMD disk drives and up to eight formatted tape drives without modifying the operating system software. Spectra 20 is for Data General Nova and Eclipse users, and has been available since May; Spectra 21 is geared to DEC PDP-11 users, and should be available this month.

National Semiconductor's Hexacon controls three peripheral subsystems: disk, tape and a fixed-head-disk emulator they've introduced, called NURAM. Aggregate device transfer rate exceeds 2 MB/sec for up to four CDC 9762-type 67-MB disk drives, up to four Cipher Microstreamer tape drives (start/stop or streaming) and up to 8 MB of NURAM auxiliary memory. Hexacon works on any DEC UNIBUS system and is compatible



**Multifunction controller boards, manufactured by National Semiconductor and Spectra Logic (above) handle multiple peripheral subsystems, but use up only one card slot.**

with DEC operating systems. Production shipments are slated for September; NURAM production shipment should begin in October.

Each company uses a different design approach for its controller and, not surprisingly, each believes its approach is the only approach. One major difference between the two boards is

that Spectra Logic uses two  $\mu$ Ps, with a larger total chip count, and National Semiconductor uses one. As Jim Anderson, National Semiconductor staff engineer, puts it: "They (Spectra Logic) have a separate microengine for the tape unit. Tape units typically spend 20 to 22 hours a day not being used. That portion of their logic is wasted



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during those periods of the day. We wanted to be able to use that same expense more efficiently, and we believe we got a better plan for being able to take the logic we invested in and spread it across three peripherals."

Spectra Logic, however, believes that the one  $\mu$ P approach has its drawbacks: "It's the opinion of our engineers," says Steve Roberts, Spectra Logic Executive Vice President, "that they (National Semiconductor) really had to cut so many corners that there's no way they can do all those functions with just one  $\mu$ P."

"We do it successfully," counters Bill LeDuc, National Semiconductor Product Marketing Manager, "so what he (Roberts) thinks really isn't too material." LeDuc did add, "We were a little bit concerned as far as handling all three functions — whether or not we could get down the UNIBUS as rapidly as we hoped — and it far, far exceeded our expectations."

"We may be in for a surprise," says Roberts, "but our engineers believe that with four levels of interrupts going into one  $\mu$ P, there's absolutely no way that that can keep the disk, the tape, the UNIBUS and that NURAM thing all going at one time without jeopardizing and sacrificing a tremendous amount of performance."

"If you take their approach, that's true," answers LeDuc, "but we think it's the other way around: we think they're going to have a helluva time making theirs work with some high speed peripherals. This is my own impression, but the two microengine approach can lend itself to some arbitration problems between the two microengines — which one is going to have access to the UNIBUS — and when you start making that coordination between the two microengines — which one's going to transfer — somebody's clock has got to slow down."

"I don't think there's any point that can be made there," states Roberts, "we're shipping the Data General one, so there's no question but that it works and that it streams and does everything else."

On paper, Spectra Logic has the edge in transfer rate and also supports eight tape drives to National Semiconductor's four. In addition, Spectra Logic makes both Data General and DEC models. However, National Semiconductor has the advantage of being able to handle their high-speed bulk NURAM memory, and also has a larger buffer than Spectra Logic's. But the real test for the two controllers will be in the field, where reliability and maintenance of recorded specs will tell the story. And that's the test by which both companies say they're eager to be judged.

by **Bob Hirshon**

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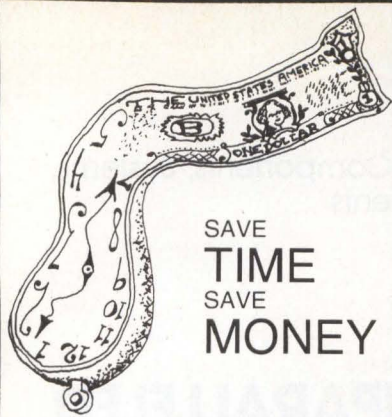
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august '81 editorial emphasis....

### COMPAT™ '81 Show Issue And Product Directory

This special computer compatible COMPAT issue next month will contain an industry first — the first directory that lists plug-compatible computer products from manufacturers offering compatible products for DEC, Data General, Hewlett-Packard, Perkin-Elmer, IBM, Intel, Motorola and other minicomputer and microcomputer makers. This directory will be saved and referred to for the next 12 months by OEM system designers and integrators whenever they need to compare or specify computer compatible products. No other compatible computer source or directory in existence lists such information. COMPAT is the industry's first show exclusively devoted to computer compatible products.

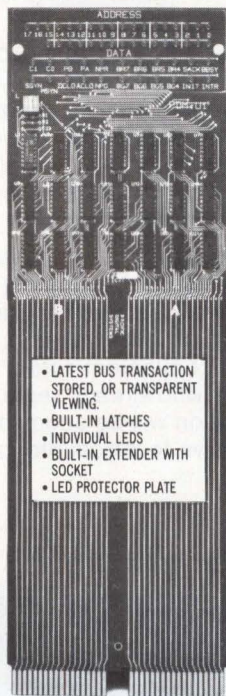
#### Graphic and Alphanumeric Display Terminals

A product showcase will spotlight current graphics and alphanumeric display terminal technology and list terminals of interest to system designers and OEM integrators and builders.

#### Computer System Power Supplies

This article will present criteria for selecting a power supply that is best suited for a particular application. This power supply report will cover various aspects of recent power supply technology and product choices that include linears and switches, build vs. buy criteria, and related design problems.

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(408) 732-0656

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Circle 54 on Reader Inquiry Card

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**MID-WESTERN STATES:** David Kingwill, Ed Krukowski, (312) 774-9660, The Flynn Group, 5526 N. Elston Ave., Chicago, IL 60630

**SOUTHWESTERN STATES:** Jerry Ambroze, (713) 780-3326, The Flynn Group, 2168 Augusta, Houston, TX 77057

**JAPAN:** K. Yanagihara, (03) 350-0272, 10-10 Shinjuku 3-chome, Shinjuku, Tokyo, 160, Cable Address: Yanacour, Tokyo



# ATE

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Send abstracts (200 - 500 words) and short biographies by September 15, 1981 to Mary Habosian, ATE Seminar/Exhibit, c/o Benwill Publishing Corp., 1050 Commonwealth Ave., Boston, MA 02215. Or call: (617) 232-5470.



## Glare Screen Provides Cure For Terminal Eyestrain

Every occupation has its hazard, from writer's cramp to tennis elbow — not to mention the newly-diagnosed "Space Invaders wrist" (reported in a recent issue of the New England Journal of Medicine). For video display terminal (VDT) operators, eyestrain is the ailment, and several display phenomena (flicker, radiation, and glare among them) currently receive blame for the problem.

Undoubtedly, surface glare is one major contributor to visual fatigue. Various light sources reflect on the surface of the VDT, distracting the eye of the VDT operator. Eyestrain results because the reflection appears, to the observer, to be at whatever distance from the operator the original object occurs. For example, the reflection of a window located ten feet from a VDT screen which is, in turn, located 14 inches from the operator will appear, to the operator, to be over ten feet away. As a result, the operator's eye, when distracted by the reflection, must refocus from 14 inches to ten feet. Constantly refocusing between these disparate points throughout an eight hour day creates eye fatigue.

Polaroid, which has had some experience dealing with glare, recently announced a circular polarizing filter that "absorbs harsh reflections and glare while improving contrast to make the VDT screen easier to read," according to Dr. Stewart Bennett, General Manager of Polaroid's Polarizer Division.

The filter traps not only reflections of light sources from around the room, but also ambient room light; eliminating this light results in a higher contrast image.

Inescapably, the CP-70 also filters some light produced by the VDT. According to Bennett, "the observer sees about half the light coming from the screen." However, he's quick to add, "if the brightness control on the VDT is turned up a bit, the letters are as bright as they are without the filter, although this is usually unnecessary

because of the improved contrast."

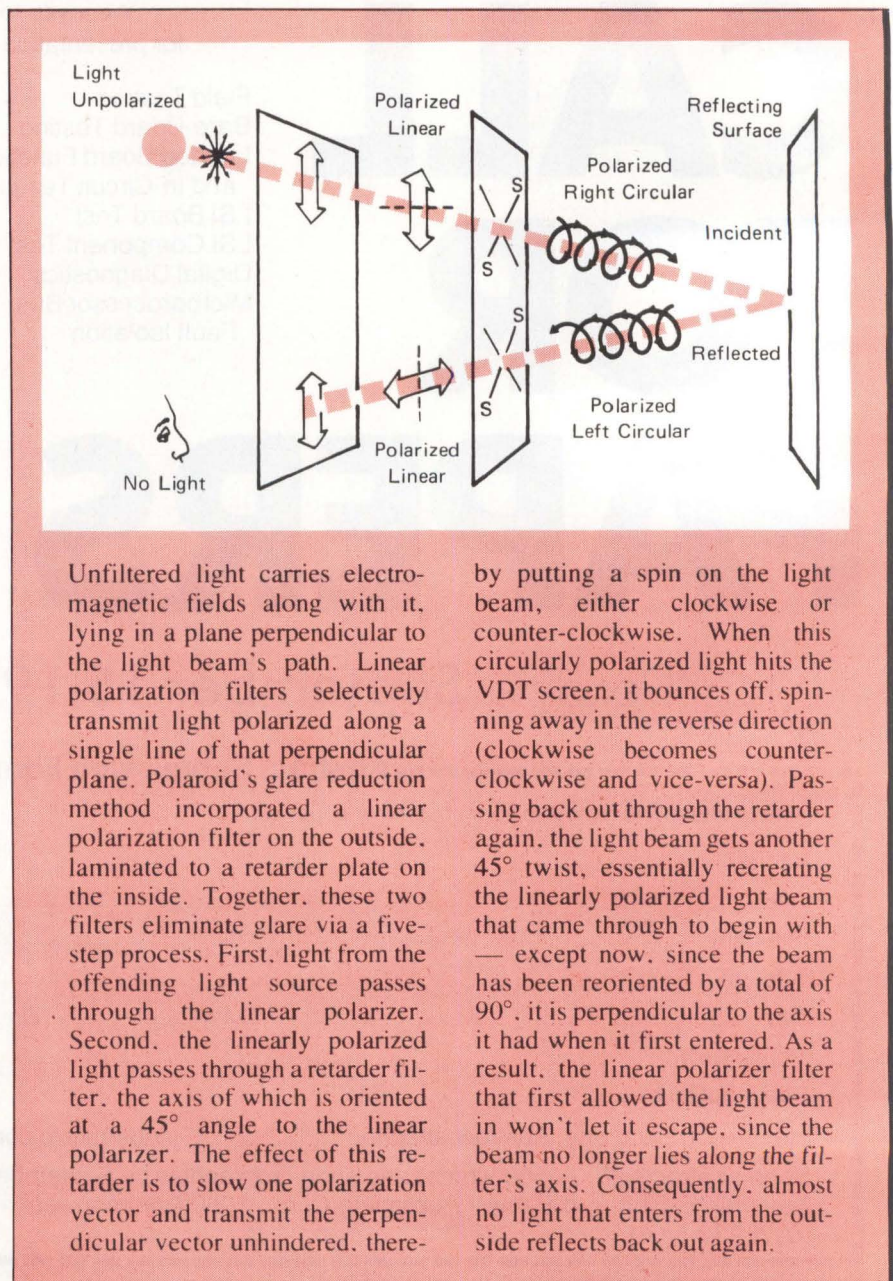
Polaroid claims their filter is superior to conventional frosted or tinted glare filters because these methods reduce image clarity and don't completely eliminate glare. Model CP-70 filters come in a variety of sizes and fit on existing terminals via adhesive Velcro

fasteners. Unit quantity prices range from \$68 to \$125.

by **Bob Hirshon**

*Polaroid Corp., Polarizer Div., 1 Upland Rd., Norwood, MA 02062.*

**Circle 197.**



Unfiltered light carries electromagnetic fields along with it, lying in a plane perpendicular to the light beam's path. Linear polarization filters selectively transmit light polarized along a single line of that perpendicular plane. Polaroid's glare reduction method incorporated a linear polarization filter on the outside, laminated to a retarder plate on the inside. Together, these two filters eliminate glare via a five-step process. First, light from the offending light source passes through the linear polarizer. Second, the linearly polarized light passes through a retarder filter, the axis of which is oriented at a 45° angle to the linear polarizer. The effect of this retarder is to slow one polarization vector and transmit the perpendicular vector unhindered, there-

by putting a spin on the light beam, either clockwise or counter-clockwise. When this circularly polarized light hits the VDT screen, it bounces off, spinning away in the reverse direction (clockwise becomes counter-clockwise and vice-versa). Passing back out through the retarder again, the light beam gets another 45° twist, essentially recreating the linearly polarized light beam that came through to begin with — except now, since the beam has been reoriented by a total of 90°, it is perpendicular to the axis it had when it first entered. As a result, the linear polarizer filter that first allowed the light beam in won't let it escape, since the beam no longer lies along the filter's axis. Consequently, almost no light that enters from the outside reflects back out again.



## Printer Produces Color Graphics

Growth of color displays for small business systems has long been hampered by lack of inexpensive color hard copy. While this is merely one limiting factor in an otherwise booming area, it's an annoying weak link for designers of low cost business systems.

This fall, Integral Data Systems will introduce industry's first answer to the problem: the Model 570 color printer. The Model 570 looks, sounds, feels and basically is just like a Model 560 Paper Tiger printer. But a newly-designed multicolor ribbon system and software package enable the 570 to print in eight colors, producing business graphics with surprisingly high color saturation and quality.

Like color printers from IBM, Ramtek and Trilog, Model 570 works by hammering conventional impact print wires against cyan, magenta, yellow or black ribbons. As with the IBM system, the colors are arranged in parallel, horizontal strips, which the print head accesses by shifting up and down. Like Trilog and Ramtek models, the 570 can mix primary colors to create additional colors (green, violet, orange and brown). And like Ramtek and IBM units, Model 570 makes one pass over each line for each color that the line requires. But unlike any of the above-mentioned printers, the 570 will sell for under \$3K, less than a third the price of other impact color printers.

Thanks to the overlapping dots produced by IDS's staggered nine-wire print head, Model 570's image quality equals or exceeds that of other color printers. Although resolution is only  $84 \times 84$  dots per inch, dot overlap eliminates most of the inter-dot white space, resulting in denser, higher-quality colors.

What you don't get with the 570 is high throughput. As a printer, it sails along at a respectable 150 cps. But multi-colors require multi-passes, and this can slow things down considerably. Plot speed is application-dependent: the more colors per line, the slower the 570 travels. Also, graphics that are more complex on the right side of the paper require more time than graphics that are detailed on the left, since the former requires the print head to travel the entire length of the line more times. Because plot speed is so application dependent, throughput benchmarks are

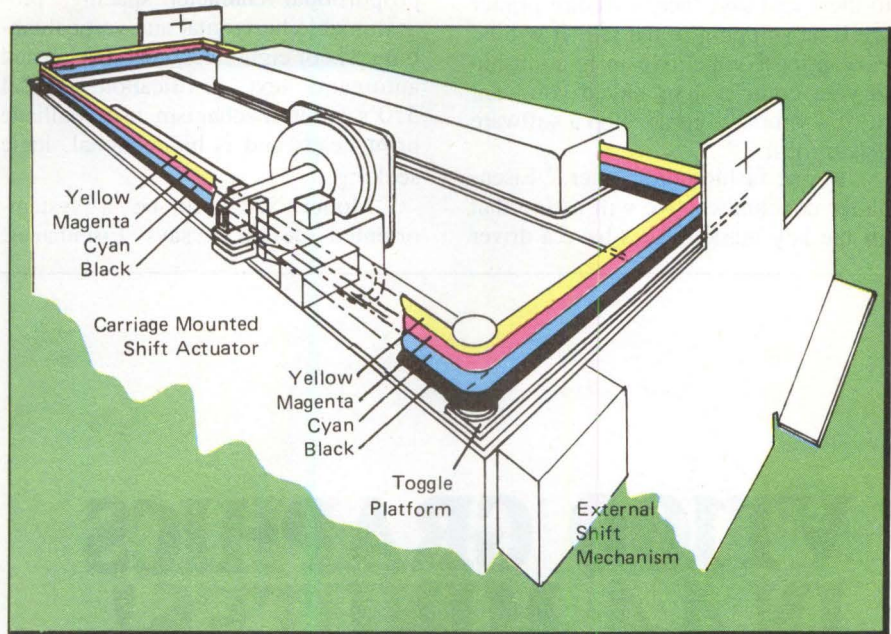


Figure 1: Model 570's mechanical shift automatically accesses each ribbon color.

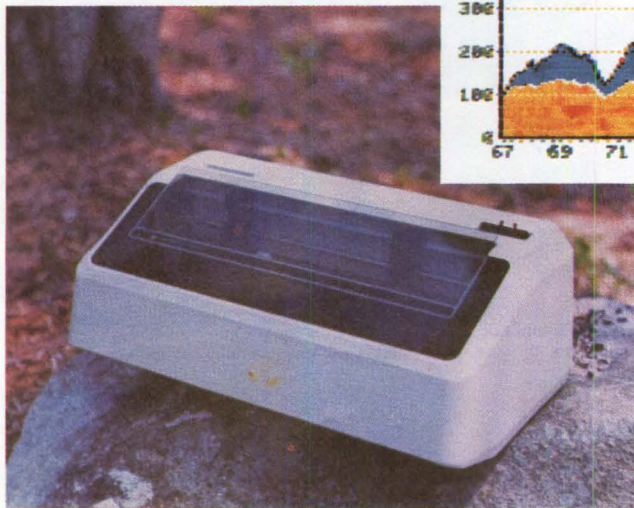
difficult to calculate. To give some idea, however, the business chart (Figure 2) requires about three minutes.

Making the 570 compatible to the many color graphic terminals currently in use was the most difficult design difficulty for IDS engineers to overcome, according to Peter Eisenhauer, IDS Marketing Manager. "The biggest problem we ran into was not so much the implementation of the mechanism," explains Eisenhauer, "but marrying the software with the design and trying to come up with a control scheme for

shifting from color to color that was reasonably compatible to the types of color operating systems that are out in the field."

Since it's impossible to develop a software driver compatible with every graphic display on the market, IDS had to select only the more popular offerings. They're developing some software in-house; the rest, they're farming out. "One of the key things in the color marketplace," says Eisenhauer, "will be to identify the key hardware to be involved with. Then we're going to

Figure 2: IDS 570 desktop (or rocktop) printer provides color graphics, as well as correspondence quality printing.





find the people that are using it, and go to them and say, 'here's a color printer we'll be shipping in the fall. It will be very price competitive in relationship to your color system and, if you want to, it's yours — go develop a software driver for it.' "

"In one fashion or another," Eisenhauer concludes, "we will assure that all the key marketplaces have a driver

that operates with their system."

As a printer, the 570 produces correspondence quality print in a 24x9 matrix cell and features six software selectable character sizes, mono or proportional character spacing, programmable horizontal and vertical tabbing, six or eight lines/inch spacing and automatic text justification. Model 570's print mechanism uses ballistic print heads and is bidirectional, logic seeking.

"Model 570 will be a system-oriented design," says Eisenhauer.

OEMs designing small business systems will be the primary potential market. According to a recent report by International Data Corporation of Framingham, MA (see Tech Trends, p. 13) the business graphics market will top \$1 billion by 1984. The report, titled "Graphics in the Office," predicts that most of these systems will be color and, furthermore, that the lack or ready availability of color hard copy will be a major factor in either hindering or propelling that trend. IDS's autumn introduction of the Model 570 will be industry's first step towards assuring the latter course.

by Bob Hirshon

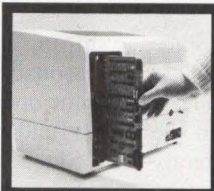
Integral Data Systems, Inc, Milford, NH 03055. Circle 200.

# VT100 GRAPHICS IN 4.4 MINUTES!

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## Smart Storage Tube Terminal Displays Two Colors

Two of the more imposing drawbacks of Direct View Storage Tube (DVST) displays have traditionally been lack of operator interactivity and lack of colors. Despite DVST's extremely high resolution, these liabilities have limited the displays' penetration in many markets. With the introduction of the new 4114 intelligent graphics terminal, however, Tektronix has made dramatic progress in overcoming the first of these problems. And, thanks to the 4114's two-color option, DVSTs have finally flown the monochromatic pigeonhole.

On-board microprocessing power enables the 4114 to manipulate data locally, without depending on the host computer. RAM capacity that is expandable to 800K bytes further reduces host dependence.

As a result, users can store a group of MOVE and DRAW commands — defining commonly used symbols, codes, background graphics, etc. — and then recall them to the screen as they're needed, without tying up the CPU. These picture segments can be drawn simply by specifying a segment identifier and a screen location.

In addition, 3000 short vectors of flicker-free refresh capability enables the 4114 to translate, rotate and scale picture segments locally, without erasure or repaint. This two-dimensional transform capability defines picture segments — potentially

Circle 51 on Reader Inquiry Card



quite complex ones — as display cursors, which are manipulated with the 4114's thumbwheel cursor control.

Another feature made possible by the 4114's refresh memory is a user-definable dialog area. This enables operators to specify a screen area expressly for scrollable text, so that terminal/host interactions don't overlap with graphics workspace.

Problems of slow repaint were overcome in the 4114, thanks to the large local RAM. Extremely complex graphics of up to 26,000 short vectors can be erased and redrawn in under 0.5 sec.

The new interactivity capabilities of the 4114 don't arise from any new technological breakthroughs, according to Mike Kondrat, display terminal Marketing Manager, but simply from increased memory and processing capacity. In fact, before introduction of the 4114, some of the less intelligent terminals were somewhat enhanced by OEMs who built in their own limited refresh memory.

As memory and processing costs come down further, user-interactivity of DVSTs will increase even more. But for now, according to Kondrat, being limited to 3000-vector interactivity isn't much of a limitation at all. "There are very few applications where users want selectable erase across the whole screen. So, from the applications aspect, the selective erase problem has been solved."

Unique to the 4114 is a two-color screen that Tektronix refers to as Option 31. Terminals equipped with this option display stored information in conventional green, but display refresh information in orange. For high-density applications, this enables users to distinguish the user-interactive pic-

ture area from the stored area.

A two-phosphor mix allows the 4114 to achieve two colors. These two phosphors get excited at different potentials. "You can excite the reddish phosphor," says Kondrat, "by not giving it enough potential, so it gets just excited enough to emit the red. But if you want to store it, you jack it up a little more in voltage, and that stores it on the screen."

Other key features of the 4114 include resolution of 4096 × 4096 addressable points (4096 × 3072 displayable) and data communications rates of

up to 19.2K baud. Options include single and dual flexible disks, up to 512K bytes additional RAM, graphic tablets, a bus extender, and a three-port peripheral interface. Model 4114 sells for \$17,500, or \$19,500 with color enhanced refresh, in unit quantities (OEM discounts available).

by Bob Hirshon

Tektronix, Inc., PO Box 500,  
Beaverton, Oregon 97077.

Circle 198.

## DEC Compatible Sealed Terminal....



### The terminal that defies damp, dirty environments

- Nonventilated (no fans, no filters)
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- NEMA 12 rated structural foam enclosure
- Sealed Membrane Keyboard
- VT 52 or Hazeltine 1420 compatible

Perfect for:

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- Operator Workstation
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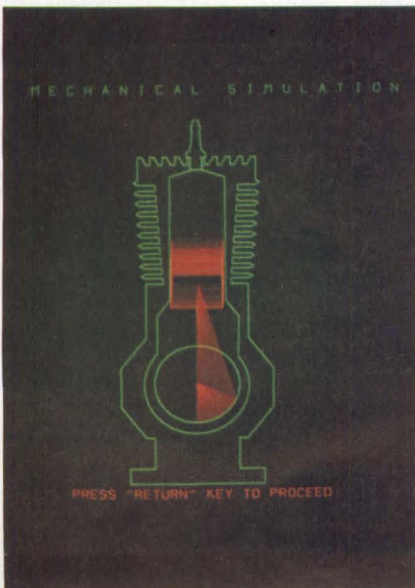
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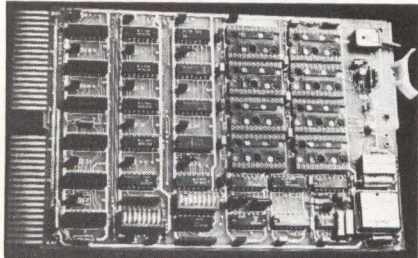
# New Products

Includes DEC and Other Computer Compatible Products

## EPROM MODULE

### Adds 8K Memory To LSI-11

The CCS-1220 EPROM Module provides LSI-11's with 8K words of EPROM type memory using 8 Intel 2716 compatible EPROMS. A R/W switch sets the card in program mode,



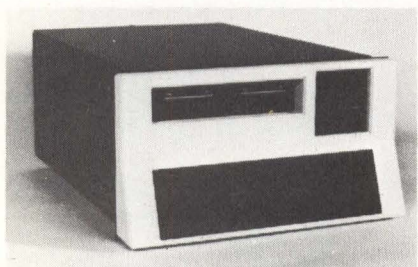
and disable programming when set in Read-Only mode. It allows programming of any memory location, individually, sequentially, or randomly under software control. Programming software consists of writing to the desired location, and timing out for 50 msec. \$475 with user's manual describing board operation and programming considerations. **Control Logic Inc**, Nine Tech Circle, Natick, MA 01760.

Circle 126

## COMPUTER SYSTEMS

### Compatible Alternatives To DEC Systems Marketplace

The 34 MAGNUM provides enhanced PDP-11/34 class performance while the 44 MAGNUM is an economic alternative to the PDP-11/44. Standard system configuration consists of a CPU with floating point and memory management, serial console interface, extended memory addressing to 4MB, dual TU58 cartridge tape units including interface, programmable line time clock, bootstrap loader, 8kB cache memory, microcoded ODT and maintenance console. The 34 MAGNUM comes with 256kB of memory, the 44 MAGNUM with 512kB as standard.



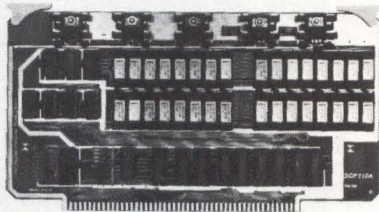
Other Unibus compatible controllers are optional. They are supported by RSTS/E, RSX-11M and RT11 operating systems. \$21,000 for the 34 MAGNUM, \$27,000 for the 44 MAGNUM, 60 days ARO. **Able Computer**, 1751 Langley Ave, Irvine, CA 92714.

Circle 129

## STATIC 64K RAM

### Uses New 100 nsec Chip

The SCP-110, a 64kB IEEE S-100 memory card, uses the 100 nsec Intel 2167 16K static chip. The chip allows memory management functions of offset and protection to be performed with the 8 MHz. 8086 CPU without a wait state. The card performs both 8-bit and 16-bit transfers, switching automatically. The chips are used in a power down mode to minimize cur-



rent. \$1295, OEM qty. discounts available. **Seattle Computer Products**, 1114 Industry Dr, Seattle, WA 98188.

Circle 130

## DEC-COMPATIBLE VIDEO TERMINAL

### Emulates The VT100 With Advanced Video Option

Model 3100 is designed for users who don't need the powerful editing capabilities of Cobar's 3132 terminal. Standard features include printer port, non-glare screen, 4 video attributes, set up prompt legends, 19,200-baud operation and screen save. \$1595, OEM and qty discounts available. **Cobar Inc**, 1181 North Fountain Way, Anaheim, CA 92806.

Circle 132

## PACKAGED VOICE TERMINAL

### Features Expanded Vocabulary

This fully-integrated voice data input terminal doubles the standard vocabulary from 64 words to 128 words. Model 5300 combines the Model 5000 speech recognition circuit board with

the Lear Siegler ADM-5 terminal. The two units are assembled, integrated and fully tested by Heuristics. The final product is a stand-alone, integrated voice input terminal, supplied with a noise-cancelling headset microphone. The terminal can accept either keyboard or voice input, or both simultaneously. \$3925. **Heuristics Inc**, 1285 Hammerwood Ave, Sunnyvale, CA 94086.

Circle 127

## LSI-11 DISK CONTROLLER

### Interfaces Two Shugart, Memorex or Fujitsu Disk Drives

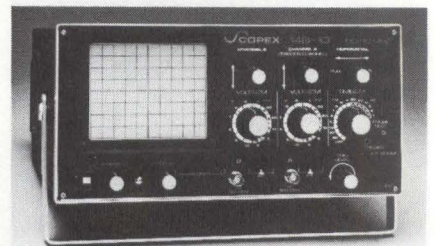
This low cost, single quad size disk controller interfaces DEC LSI-11, 11/2 or 11/23 microcomputers with two each Shugart SA4000, Fujitsu 2301 or 2302, and Memorex 101 or 102 along with other hard disk drives having a Shugart SA4000 type interface. Model DQ401  $\mu$ P-based controller, is compatible with RT-11 and RSX-11 software. Features include data buffer, automatic media flaw compensation, data error checking, on-board bootstrap and extended memory addressing to 256 kB. \$1580. **Dilog**, 12800-G Garden Grove Blvd, Garden Grove, CA 92643.

Circle 146

## DUAL TRACE OSCILLOSCOPE

### Inexpensive Scope For Floppies

The Scopex 14D-10 has a full 10 X 8 cm display on a flat face tube backed by IC circuitry with switched mode power supplies. Features include 10



MHz plus bandwidth at a Y sensitivity of 2mV/cm on both channels, full X-Y facility, Add and Invert capability, wide range time base with push button selection of trigger modes. Measuring accuracy is 3% on both X and Y axes. Trace locate and probe compensation are included. \$699. **Intratec**, Div. of British Aerospace, Dulles Int'l Airport, Box 17414, Washington, DC 20041.

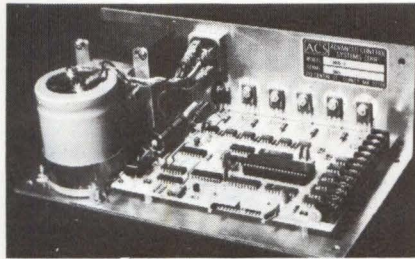
Circle 152



## μP-BASED CONTROLLER/DRIVER

For Use With 3, 4 or 5 Phase Stepping Motors

Suitable for OEM applications in automation, robotics and research and development, the MCU-3 provides all the required power supplies to drive a

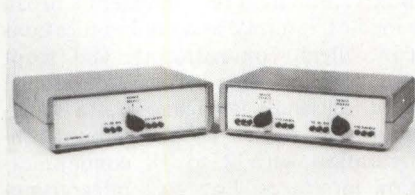


stepping motor, control bus buffering and optical isolation for field connections. Up to 16 MCU-3's can be paralleled on the system control bus, which is directly compatible with most of the 8-bit μP's. Three groups of instructions — initialize, command and read status — provide the flexibility for a wide range of motion control applications. The MCU-3 is \$394. Also available is the MDB-6B high speed, high power stepping motor driver for use with 4 phase stepping motors. It is suitable for OEM applications in multi-axis motion controllers. \$245. **Advanced Control Systems Corp.**, 213 Centre St, Quincy, MA 02169. **Circle 131**

## TERMINAL SWITCHERS

Manual or Remote Control

This family is fully compatible with WANG, H/P, IBM and DEC equipment. The GBNC-S8 can switch one terminal between 3 or more CPU's or



modems. A 3 position switch allows selection of which CPU or modem will be connected to the terminal. The GBNC-S8RC, with remote control, connects 3 terminals to one common CPU port. Each terminal has a small control box which requests a connection to the CPU. Only one terminal is connected while the other two wait until the CPU port becomes available. The GBNC-S8 is \$139; the GBNC-S8RC is \$298. OEM discounts available. **Giltronix Inc.**, 450 San Antonio Ave, Palo Alto, CA 94306. **Circle 141**

## CONVERSION PACKAGE

For PDP-11 to VAX-11 Assembly Language Conversion

CONPAX runs on both PDP-11 and VAX-11 computers and produces

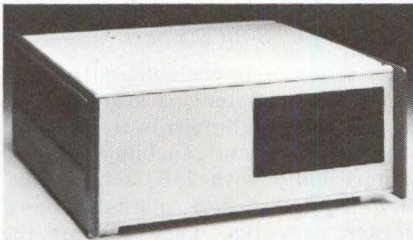
VAX-11 assembler source code in less time and with fewer errors than manual conversion. Editing procedures and a post-processor allow the user to select the desired conversion and eliminate unwanted alternatives. It automatically handles details such as supplying octal radix indicators, translating ASCII literals to VAX-11 format, and substituting standard VAX-11 register names. The conversion process is controlled by tables which can be used to fine tune the conversion for particular programming environments and to produce special conversions (including multi-line) of PDP-11 opcodes, macros, or operands. An initial \$1500 fee includes consultation, training and conversion of 500 lines. Additional conversion is \$.50/line. Permanent license is \$5000. **PSI**, (Pennington Systems Inc), 65 S. Main St, Pennington, NJ 08534.

**Circle 138**

## WINCHESTER STORAGE MODULE

EXORbus Compatible Series

Each configuration of the 9670 series is a complete storage system with one or more drives, an intelligent control-

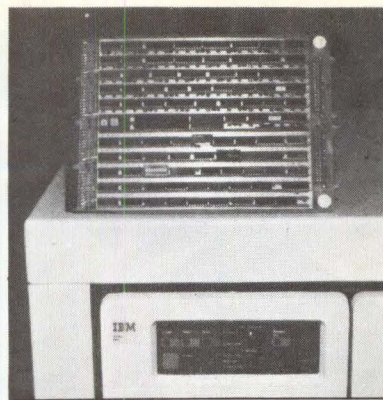


ler and a power subsystem. Normal configuration includes an 8" Winchester disk drive and an 8" double sided floppy. Variations can include any combination of Winchester and 8" floppy disk drives to a max of 4 drives. The storage module controller responds to 10 high level commands and features full sector buffering and burst error correction. The system also supports Enhanced Programmed Data Transfer. The 10MB Winchester/1MB floppy configuration is \$5295. **Creative Micro Systems**, 11642-8 Knott St, Garden Grove, CA 92641. **Circle 180**

## COLOR GRAPHICS TERMINAL

For VT100 Users

The ColorScan 10 has a built-in line ruling set and 8 colors for both foreground and background information. Includes a non-glare 12" screen in either an 80- or 132-column by 24-line format and a detachable typewriter-style keyboard with separate numeric pad. Features split screen, regional scrolling, smooth scrolling and double high/wide characters. \$3,795, OEM discounts available. **Datamedia Corp.**, 7401 Central Highway, Pennsauken, NJ 08109. **Circle 151**



## SERIES/1 CONTROLLER FOR IBM 3203-5 LINE-PRINTER

The Computerm Line Printer Controller for the IBM 1403, 3211 and 3203-5 line printers provides complete line printer support with *no changes* required in the Series/1 system software. The controller is transparent to the host and operates in Cycle Steal and Direct Program Control (DPC) modes. It is completely compatible with the host computer drivers and operating systems through emulation of the Series/1 4973 Printer.

The price of this interface is \$2,995.00. OEM and quantity discounts available, 90 days ARO. **Computerm Corporation**, 1670 Golden Mile Highway, Monroeville, PA 15146. (412) 325-1344.

**Circle 56 on Reader Inquiry Card**

## Realtime troubleshoot complete LSI-11 computer systems in 15 minutes...

The CAS-11 is a powerful, interactive LSI-11 computer-based system analyzer. It can debug and solve problems encountered in the laboratory, on the production line or at customer installations caused by total malfunction, random errors, software development or peripherals interaction. In as little as 15 minutes, the CAS-11 can fully activate the system under test, including the operating mode of the CPU, without system performance degradation. Call or write.

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## New Products

### INTERACTIVE TERMINAL

*Supported by SDRC Graphics System*

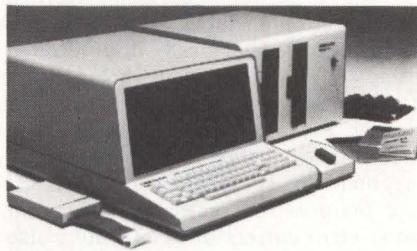
The Series II features a high contrast vector display with 2048 X 2048 addressability and built-in firmware for fast, dynamic interaction. Used with SDRC SUPERTAB, it simplifies finite element pre-processing because menus and segmented pictures stored in the terminal improve response time. Using a light pen or data tablet, the Series II supports direct interaction with the geometric model and finite element mesh. SDRC OUTPUT DISPLAY, the supplemental post-processing software, enables designers to visualize analytical results with accurate line drawings or contour plots. Local processing and picture storage permits observation of animated behavior under static and dynamic loads. Series II Graphics Terminal is \$15,750. Imlac, 150 A St, Needham Heights, MA 02194.

Circle 128

### DEVELOPMENT SYSTEM

*Provides Full 8-Bit Support*

This series of upgradable, entry level development system packages provide complete 8-bit chip hardware and software development capability, upward compatibility with 2302 slave emulation systems and hard-disk-based cluster networks. They support the 8080, 8085, Z80, 6800 and 6802



processors and include CRT, keyboard, selected CPU, 64K of static RAM, in-circuit emulator and logic analyzer in one compact console; plus a 1MB dual-drive, double-density disk and programmers for 2704/2708 and 2716/2532/2732 EPROMs. Each system offers a full complement of hardware and software features. \$17,950. GenRad, Development Systems Div, 5730 Buckingham Pkwy, Culver City, CA 90230.

Circle 148

### PLOTTING WORK STATION

*Offers Remote Graphics Manipulation and Plotting*

The 444 supports remote job entry, electrostatic plotting/printing and graphics manipulation capability — scaling, rotation, mirroring, window-

ing. It accepts unsorted vectors in the Versatec Random Format (VRF) as well as sorted vector, compressed raster, raster and print data formats. Emulating HASP multileave remote workstations, the system provides IBM software and system protocol compatibility without modification of the



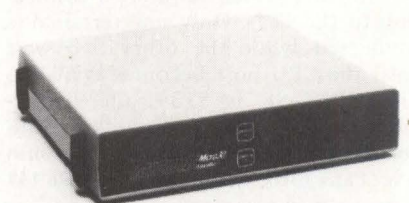
operating system. Components include  $\mu$ P with 64 kB of memory, CRT display, 24 MB disk, and a bipolar algorithmic processor (BAP) to perform vector sorting and raster generation. The system will support any two Versatec printer/plotters in any mix of paper widths. It can generate up to 15 different font styles and create different line styles and widths. The 444 Remote Plotting Work Station is \$35,000, 90 days ARO. Versatec, a Xerox Co, 2805 Bowers Ave, Santa Clara, CA 95051.

Circle 192

### COMMUNICATION PROCESSOR

*Microcomputer System for Datacomm Applications*

Designed for data communications requirements using both async and sync communications protocols, the OrangeBox can be used to implement a broad range of terminal and communications controllers, concentrators, and front end devices, using software developed by the user. It is packaged as a stand-alone unit or in a 19" rack mount configuration with 2 to 18 communication interfaces. Low-cost integral modems are available for operation at 2400, 4800 and 9600 bps. It has a Z80-A microcomputer and associated SIO integrated circuits for implementation of communications firmware using EPROMs. The standard Micro30



OrangeBox with 6 RS-232C I/O interfaces is \$1500, qty and OEM discounts available. Micom Systems Inc, 9551 Iroindale, Chatsworth, CA 91311.

Circle 185



## OFFICE/BUSINESS MICROCOMPUTER

### *Self-Contained, Typewriter-Size System*

This stand-alone system contains the  $\mu$ P as well as all other essential components in a single console. The typewriter keyboard has 100 key stations, a numeric pad and 32 function keys. The Microlite II also has a 24-line by 80-character plasma display and houses two 5-1/4" floppy disk drives that can store up to 350,000 characters per disk. An optional dot matrix printer can also be housed in the console. Other options include floppy disk drives with a 500 kB, 8" capacity. Up to 4 drives can be supported. Rigid disk drives with 27/54/208MB removable or 24/40MB Winchester fixed

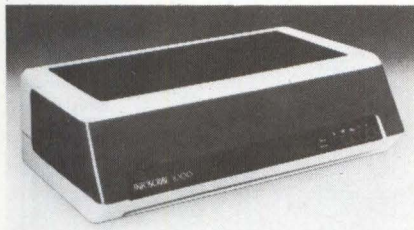


media are available for high speed and larger capacity needs. Letter-quality printing is provided by a separate daisywheel printer, and a 300 lpm line printer provides high volume printing. **Q1 Corp**, 125 Ricefield Lane, Hauppauge, NY 11787. **Circle 189**

## SERIAL MATRIX PRINTER

### *No Duty Cycle Limitations*

This unit has a 180 cps print speed and up to 136 column output. It can produce data processing as well as correspondence quality characters. In graphics mode it has a resolution of 70



dots/in. on both the vertical and horizontal axes. The printer stores a standard ASCII 96-character set together with an alternate character set in ROM, and a third character set may be downloaded from the host CPU. Other features include bidirectional printing with logic seeking, vertical and horizontal tabbing, up to 6 copies, adjustable form-feed tractors to handle paper widths from 1.5 to 16", options of 10, 12 and 16.5 cpi may be selected at either 6 or 8 lpi, and double-wide and double-density printing. The input buffer can be expanded from 1024

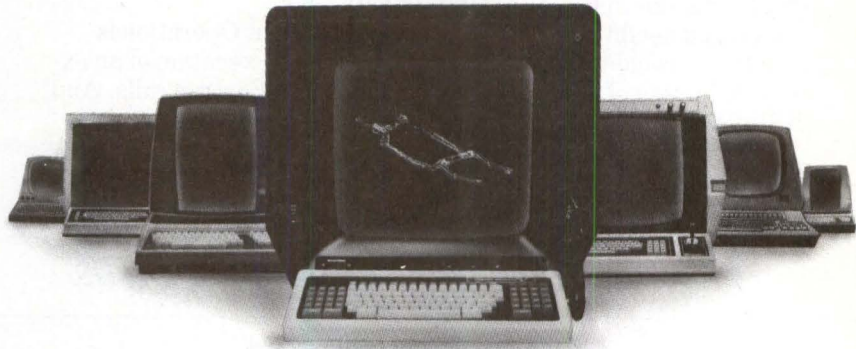
characters to 4096 characters. Foreign or special character sets may be used. The Infoscribe 1000 is \$1795, under \$1000 in OEM qty. **Infoscribe Inc**, 2720 S. Croddy Way, Santa Ana, CA 92704. **Circle 182**

## TAPE SYSTEMS INTERFACE

### *Group 3000 Tape Systems Shared Between HP CPUs*

With the SMASH (Shared Mass Archive Storage Host) interface, high performance 6250 tape technology can be shared over a network of CPUs, pro-

viding the advantages of higher recording density, increased throughput, and access to a larger, expandable, data base. The unit is contained within the cabinet of the Group 3000 tape controller. Switching selection for network CPUs is operator-activated between 2, 3 or 4 HP CPUs. Group 3000 operates at a speed of 125 ips, records at triple density 800/1600/6250 bpi or dual density 1600/6250 bpi. The SMASH unit is from \$14,000 to \$28,000. **Quallex Technology Inc**, 6925 Canby Ave, Building 109, Reseda, CA 91335. **Circle 190**



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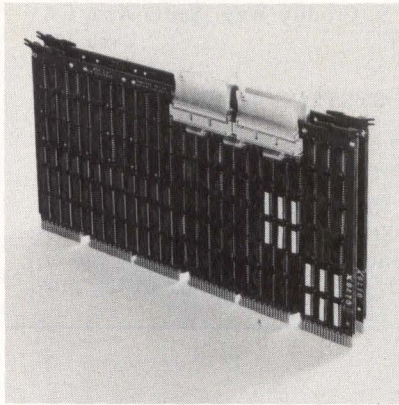
Our new MSP-3X is only about half as fast as our MSP-3. But at \$4950 its price is also less than half that of any other array processor on the market.

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## New Products

### LOGIC ANALYSIS SYSTEM

*For Standard 19" Rack Mounting*

The rack mounting package allows up to 96 channels of logic analysis for



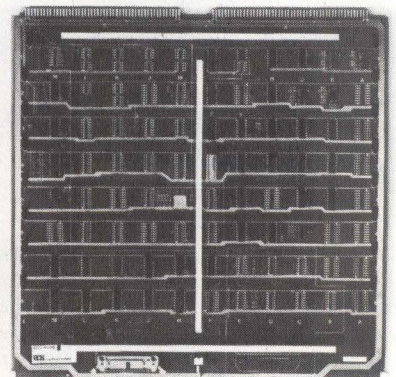
ATE and other system test applications. Five configurations are possible which arise from the package's ability to accept one or two PI-600 series modules so that the user can specify the analysis configuration best suited for his system test application. A keyboard, CRT, and the associated electronics are not required. The analysis system is designed to be incorporated into an IEEE-488 set-up and acts as a LISTENER/TALKER on the bus. The PI-600 rack mounting package is from \$6,750 to \$14,900. **Paratronics Inc.**, 2140 Bering Dr, San Jose, CA 95131.

Circle 188

### PRINTER CONTROLLERS

*Give DG Computers Up To 1500 LPM Capability*

These controllers, for the Nova and Eclipse, accommodate BDS band printers with speeds of 300, 600, 900 and 1500 lpm. Speed selection is through on-board switches. Both are completely bus and software compatible with the minicomputer. Model



DPC 40-DS employs an 8-bit parallel data-transfer bus which handles a full ASCII 96-character set along with vertical format paper-movement instructions. Model DPC 50-DS has a 16-bit parallel input from the computer with an 8-bit parallel output bus to the computer for handshake signals. It has a 256-bit RAM, permitting the

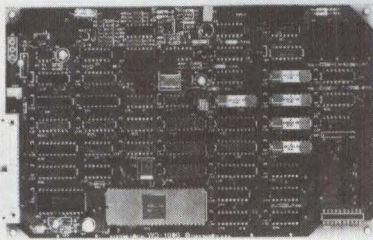


computer to set and clear horizontal tabs in any of 132 positions. Both controllers buffer two data words with transfer rates to 100kB/sec. With controller, printers range from \$3250 to \$34,400. **BDS Corp**, 1120 Crane St, Menlo Park, CA 94025. **Circle 134**

#### DISK CONTROLLERS

##### *Drive Winchester Market Faster*

These two controllers bring Winchester capabilities to the marketplace with less development time and cost to design custom drive controllers. Containing 56 devices, the WD1000 controller board features all necessary buffers, a 5 Mbits/sec transfer rate, and control for up to 4 drives and 8R/W heads. The WD1100's 5 MSI chips (address mark detector, CRC generator/checker, MFM generator, serial/parallel converter, and parallel/serial converter) take the place of 75 chips to provide an ST500/SA1000 interface. Available in a plastic 20-pin dual-in-line package or a 20-pin ceramic DIP. In quantity 250, the WD1000 board is \$395, and



the WD1100 chip set is \$48. **Western Digital Corp**, 3128 Red Hill Ave, Newport Beach, CA 92663. **Circle 143**

#### MICRO-BASED COMPUTER SYSTEM

##### *Personal Computer for Professionals*

The PC-8000 desktop computer houses processor, memory and flexible disk subsystem in a compact keyboard/display unit, available with monochrome or 8 color graphics. It supports multiple operating systems, programming languages and application packages, along with a wide variety of peripheral devices. Uses include data and word processing by professionals and managers in small businesses, and in large corporations as a remote terminal and as a standalone desktop support system. Hardware configuration consists of a Z-80 compatible  $\mu P$  with up to 64 kB RAM plus optional 32 kB ROM. The 12" CRT permits selection of variable screen widths, variable-size U&L case characters, 3 types of viewing — static paging, scrolling and split-screen — graphics, selection of an alternate character set, blinking, inverse video and an operator prompt line. From \$1600. **NEC Information Systems Inc**, 5 Militia Dr, Lexington, MA 02173. **Circle 186**

## pedestal bases and components for terminal stands



The EST Company offers a complete line of pedestal bases and components for stationary or movable stands for terminals or printers.

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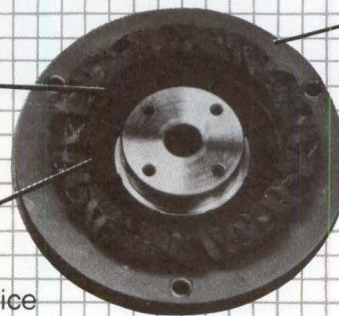
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## New Products

### SINGLE BOARD COMPUTERS

#### 16-Bit Multibus Compatible

Each of the products conforms to the Multibus standards, including multimaster capability, and are compatible with both 8- and 16-bit peripheral boards. The FT-86C and FT-86M are designed around Intel's 8086. The FT-86C/FP and FT-86M/FP incorporate Intel's 8087 Numeric Data Processor. The FT-68M is designed around Motorola's MC68000. Using the 8086/8087 combination, focus is on 6 OEM and System House application segments: Business Data Processing, Process Control, Numeric Control, Robotics, Graphics, and Data Acquisition. The FT-86M and FT-68M are designed for users needing to both support and protect large memory requirements. The FT-86M directly addresses 1MB and supports mapping addresses of 8MB. The Motorola 68000 based FT-68M directly addresses 15MB. The GATEWAY SERIES products, including the



8087 NDP, range from \$1,250 to \$2,950. **Forward Technology Inc.**, 1440 Koll Circle, Suite 105, San Jose, CA 95112. **Circle 163**

### DC SERVO MOTORS BROCHURE

#### For Computer Peripheral and WP Equipment

The Snapper series, permanent-magnet servo motors offer a range of 10 off-the-shelf motor lengths, 2 motor diameters and 8 standard winding options to provide the designer with broad mechanical and performance flexibility. Features include fast accelerations, low clogging, long brush life and rugged construction. The brochure includes a Motor Characteristics chart, notes on communication, conversion tables, diagrams and a list of options. **EG&G Torque Systems**, 36 Arlington St, Watertown, MA 02172. **Circle 161**

### COMPUTER SYSTEMS

#### Expanded DecSystem 10/20 Compatible Product Line

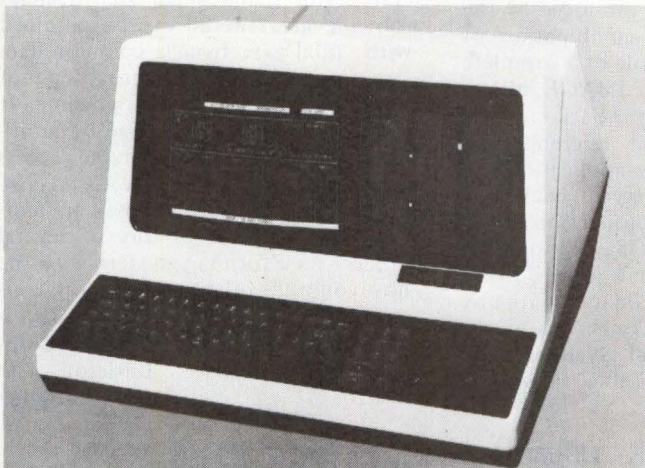
Models F4 and F5 are based on generalized, user-microprogrammable processors which can emulate the DecSystem 10/20 family. They can execute the same instruction set as any of the PDP-10 models and are capable of running the TENEX, TOPS-10, TOPS-20 or other PDP-10 operating systems. Also offered is the language C and the Unix operating system supported by a microcoded architecture. They are equipped with a display based diagnostic  $\mu$ P for remote hardware and software maintenance. With these new additions, the F series covers a performance range from very small (personal) configurations to the fastest PDP-10 compatible machine available. The F5 is from \$50-\$80,000, the F4 is \$200,000. **Foonly**, 160 S. Whisman Rd, Mountain View, CA 94041. **Circle 162**



## DESKTOP BUSINESS COMPUTER

*Includes Integral 5MB Winchester Disk*

System 1500 expands the use of low-cost desktop computers to business applications previously reserved for higher-priced minicomputers. Several applications may be on-line concurrently without changing floppies. An inte-



grated 700 kB double-sided, double-density flexible disk drive is used as backup to the Winchester for program and data transfer via removable flexible diskettes. Eight flexible diskettes can back up the full Winchester capacity. The high speed Winchester disk transfers data at a speed of 5 Mbits/sec. The disk can be configured to appear as one continuous disk with a capacity of 5.2 MB or as two separate 2.5MB disks. An automatic error correction feature allows the disk controller to automatically correct up to 11 bits per physical sector. The system includes a solid state keyboard with a 60-key typing array and a 13-key adding machine cluster, up to 64 kB RAM, a 12" CRT formatted in 24 lines of 80 characters, an 8 bit Z80 processor and interfaces for communications and printer output. A complete set of accounting and word processing applications software packages are available. \$9995. **Digilog Business Systems Inc.**, Babylon Rd, Horsham, PA 19044. **Circle 156**

## THREE PHASE AC POWER CONTROLLER

*VAX Compatible*

The MPD-416 is electrically and mechanically interchangeable with the DEC 869 AC power controller and is lower in cost. It distributes 3 phase power in computer, industrial control and electronic test systems. The controller is rated at 240/416 VAC @ 45A (15A per phase) with 6 unswitched and 12 remotely switchable outlets. Standard features include a high performance EMI filter, transient suppressors,



magnetic circuit breakers, local-off-remote switch, delayed output for multi-controller sequencing, remote disable, emergency shut down. The MPD-416 is \$1300. OEM and qty. discounts available. **Marway Products Inc.**, 2421 S. Birch St, Santa Ana, CA 92707. **Circle 170**

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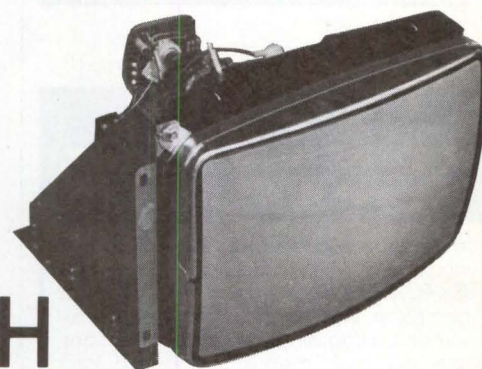
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## New Products

### SESSION PLAYBACK SOFTWARE

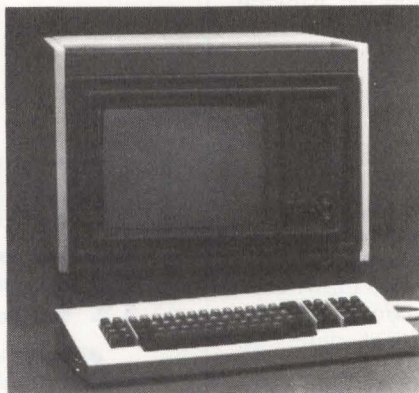
*DEC VT100 Compatible*

This package runs against session documenting log files produced by the program DOC. The combination of DOC to create a log file of a complete session, together with IMAGE, allows replay of the session back to the screen for subsequent reference and training. The dynamic application run example may be played back one frame at a time for inspection. Also, an accurate mapping may be put out as a printed document. The IMAGE package is \$295, may be used with any number of VT100s connected to the system. **Clyde Digital Systems**, Box 348, Bedford, MA 01730. **Circle 149**

### COLOR GRAPHIC CRT TERMINAL

*Wide Variety of Features*

The display has 1,920 alphanumeric characters in a 24 line by 80 column format with 720 X 288 graphic resolution. In addition to the full ASCII character set, each unit has 1,280 user defined programmable symbols on a single plane. The keyboard is detached and has 87 keys. There are 8 keys for editing and special functions plus 24 programmable function keys. The user can view two pages of data by horizontal or vertical scrolling. Split screen is standard with up to 4 independently addressable and scrollable screens. The



MVI-7 is \$3500, qty. discounts available. **Colorgraphic Communications Corp**, 2379 John Glenn Dr, Atlanta, GA 30341. **Circle 181**

### INTERACTIVE MAPPING SYSTEM

*New Technology in Mapping Systems*

Many of the problems of the commonly used arc-node based mapping systems have been solved by this new hierarchically structured data base technique. It uses a tree structure of hexagon-line aggregates to provide

direct access by location into area data bases. One of the features of this architecture is the ability to use the aggregates to store general representations of the information content of their constituent data points. For users of graphic display systems this means that wide area displays showing general features and small area displays showing great detail can be obtained with equal ease from a common data structure. High speed processing of masses of pixels is also possible. It supports simultaneous usage by multiple users and features rapid access rates. The IMS uses the VAX 11/780 as the host processor and may be interfaced to Megatek or any of several others. As a turn-key system with the host computer, all software, peripherals and graphic display, the IMS is \$400,000. **Interactive Systems Corp**, 5500 S. Sycamore, Littleton, CO 80120. **Circle 167**

### NTR COMMUNICATIONS PROTOCOL

*For DG Minicomputers*

This data communications software allows the NOVA and ECLIPSE to connect to UNIVAC mainframes using the NTR remote job entry protocol. It supports all standard features of the protocol, including multiple I/O streams, a console, full duplex operation, space compression, and extensive remote operator control over output peripherals. It interfaces with RTOS, RDOS and AOS. Any peripheral supported by the operating system may be used for input or output, and each I/O stream is treated independently and can be assigned to different peripherals. Initial CPU license is \$2750, discounts for multiple sites or OEM. **Gamma Technology Inc**, 2452 Embarcadero Way, Palo Alto, CA 94303. **Circle 135**

### PDP-11 WP SOFTWARE

*For RSX-11M, -11M-Plus Operating Systems*

Under RSX-11M, it runs on PDP-11/23's through 11/70's and can be tailored to the size of the system. It allows running extensive word processing tasks concurrently with data processing. Features include an expanded dictionary of 30,000 words supplied, and 35,000 available for customized applications. WORD-11 is a multi-user, menu-driven system allowing the interactive creation, editing and printing of documents. Written entirely in MACRO-11. A single CPU license for WORD-11 on RSX-11M is \$7500 including installation, training and support. **Data Processing Design**, 181 W. Orangethorpe, Suite F, Placentia, CA 92670. **Circle 147**



## Use "TouchGraphic" Panels As On-Off Switch, Adjustable Vernier And X-Y Controller

Since the TouchGraphic panel processes and outputs information digitally, you can interface it to a computer bus, enabling users to convert serial data outputs to parallel data. In **Figure 1**, buffer RAMs store data, freeing the computer for other tasks. Then, once RAMs are filled with X-Y data, it quickly retrieves data when necessary or upon request, thus providing optimum utilization of the computer in applications like laser drilling, numeric-controlled systems, computer-controlled medical instrumentation, etc.

Since each system and application is different, TouchGraphic provides flexibility in applying the X-Y data to the system. In computer-controlled systems, you need accurate timing data to determine the relationship of the various signals. In this application, TouchGraphic's panel frame sync output provides this timing signal.

**Figure 2** shows how the TouchGraphic panel can provide X-Y data and serve as an on-off switch in applications such as laser beam drilling or E beam systems. In the X-Y mode, the operator draws the finger across the panel to create the desired pattern or to position the cursor. By tapping the panel, he triggers the system to fire or automatically change programs.

TouchGraphic provides extra pulses automatically, so the system can be programmed to detect number of panel taps or pulses sent to indicate the changes which must be made.

For example, in the laser drilling application, it is easy to multiplex the X-Y to position laser number one. Then, by tapping the panel — say twice — you can move on to position the second laser and so on. Or, the tapped input can be processed to move the system into a different mode of operation. This permits the operator to change from gross cursor movements to very fine cursor movements simply by tapping the "light table."

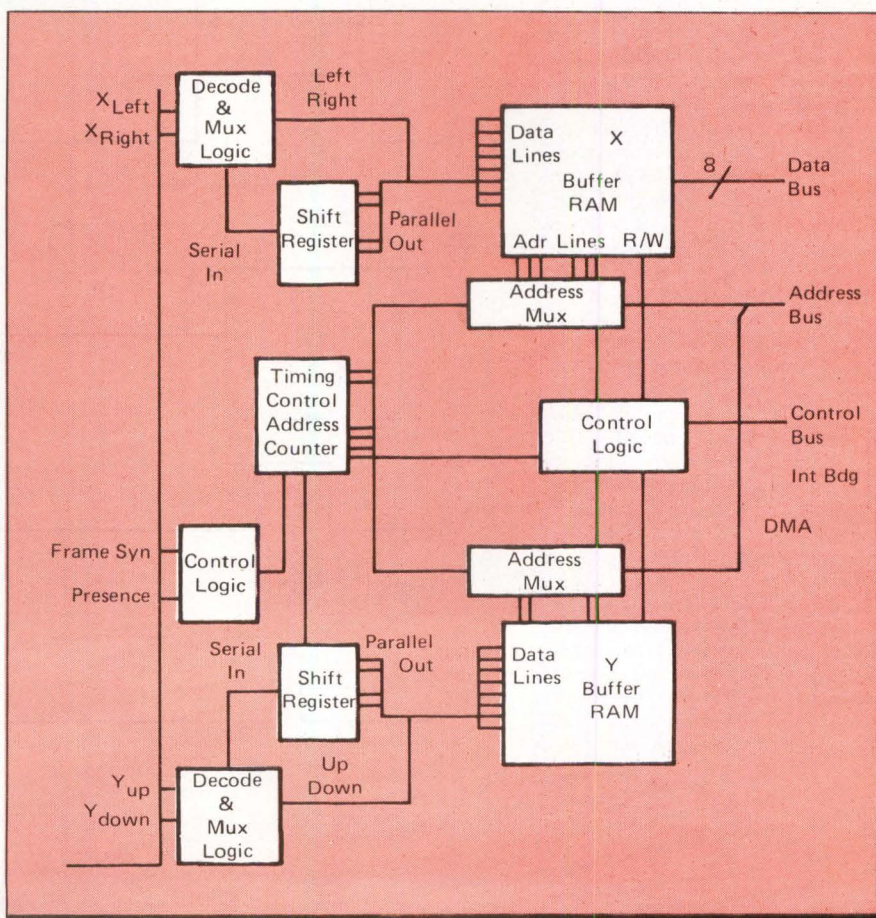
Using the system's clock, the designer sets up the system to deter-

mine how rapidly the finger moves across the panel by counting the pulses and speed from point A to point B. Then, by tapping the panel, the system can be reconfigured to permit the user to change from gross to fine movements. Finger movements across the entire four inches of the TouchGraphic panel may result in only four or five data input movements. In this way, very accurate and fine movements can be made even if the finger is very shaky on the panel.

**Figure 3** shows how the designer can also use the presence switch detection circuitry in TouchGraphic to provide an adjustable vernier. In this application, TouchGraphic provides direct counts of one on one. Or, it can provide  $\frac{1}{2}$ ,  $\frac{1}{4}$ ,  $\frac{1}{8}$ , ... on the X or Y axis. In this applica-

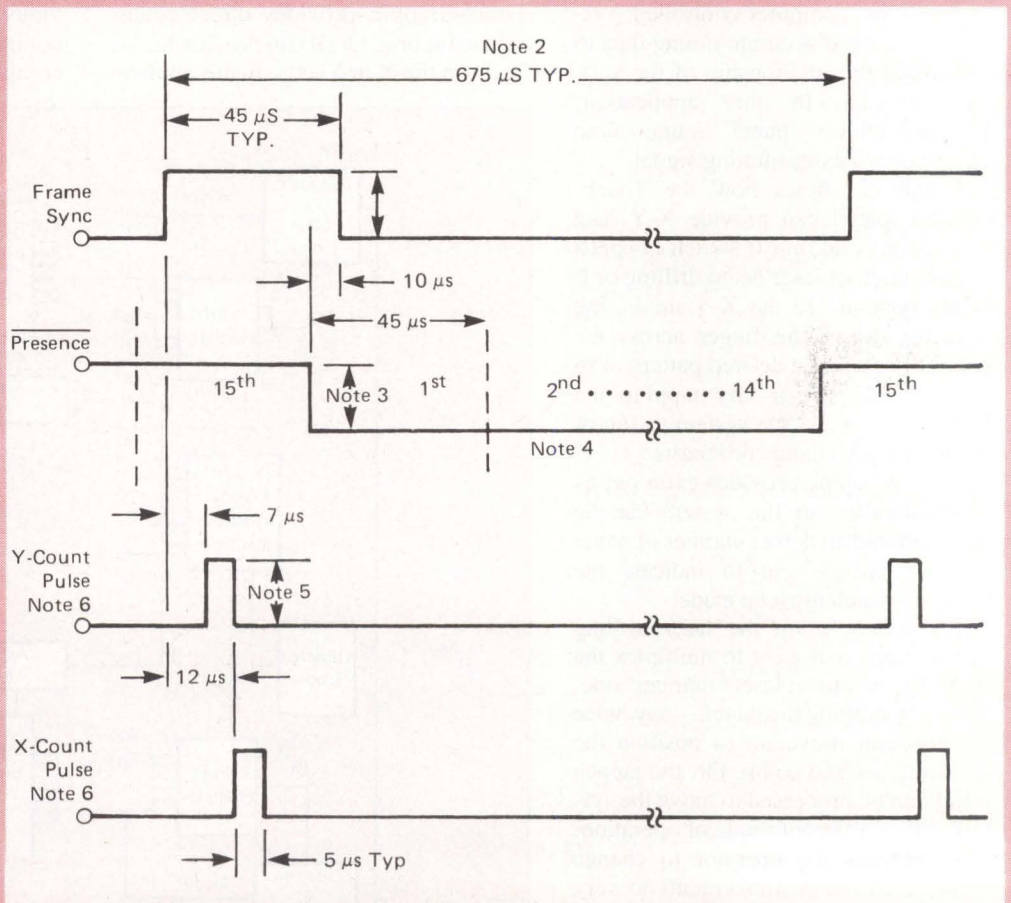
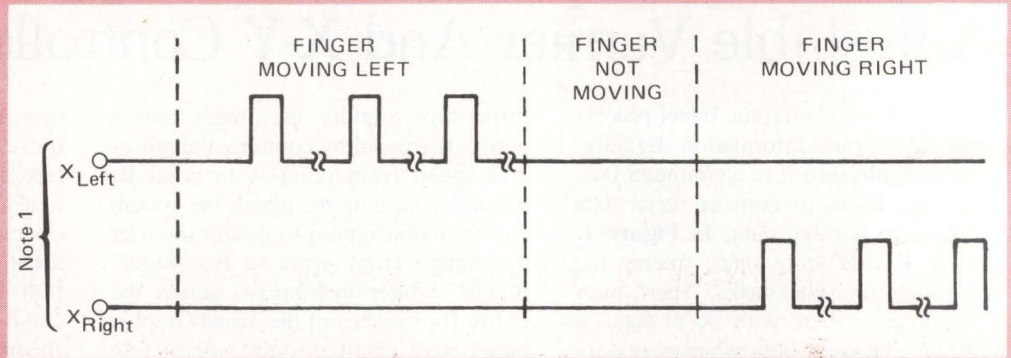
tion, the operator gets a predetermined movement with a certain number of taps on the panel. Then, by tapping the panel a different number of times, the operator gets another level of movement. Thus, with single-hand operation, users change the resolution of the cursor movement. In this application, the presence detection switch and counters not only detect finger presence but also reformat the pulse count control.

Let's look at some general applications, construction and advantages in greater detail. The TouchGraphic unit replaces trackballs, joysticks, light pens, twin knobs, pushbutton cursors and other controlling devices. It provides smooth, accurate, real-time X-Y control. In applications that involve computer graphics, freehand graphics,

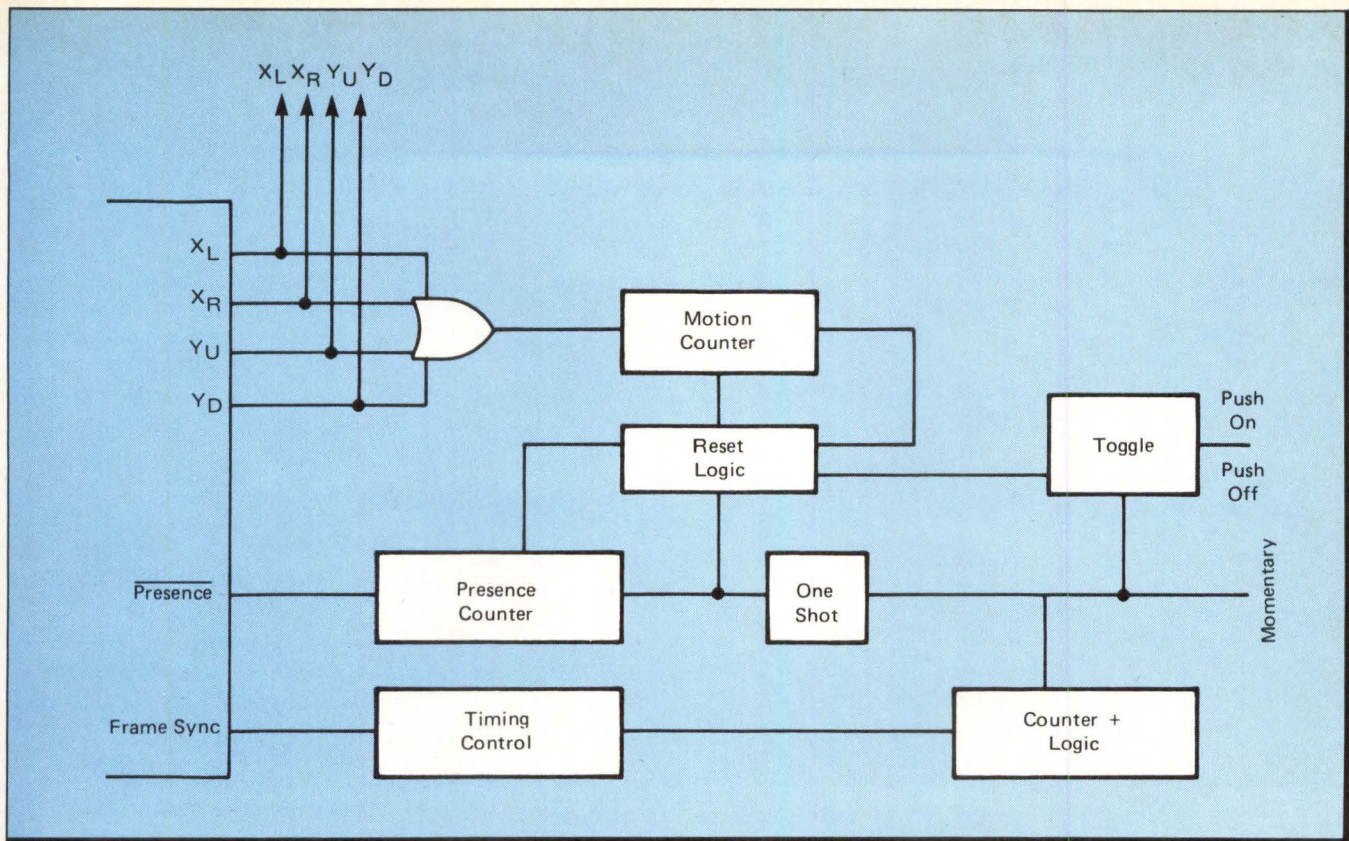




1. X count output shown for left-right finger motion; Y count outputs similar for up-down finger motion. Arbitrary terms left-right, are for reference only.
2. Since a valid output pulse may only occur when frame sync is high, there will be a minimum of about  $675 \mu\text{s}$  between one output pulse and the next. Since there are 15 sensors/ inch, internal logic and timing limits the maximum finger velocity which may be sensed at approximately  $60''/\text{sec}$ .
3. Presence output and frame sync output are both internally pulled up to  $V_+$ , and should be connected to a high impedance input (CMOS 4045 or 4050).
4. When a finger touches anywhere on the TouchGraphic surface, there will be a low-going pulse on the presence output. Activated from a minimum of  $45 \mu\text{s}$  for one sensor to a maximum of  $\approx 630 \mu\text{s}$  for 14 sensors activated. If the length of the TouchGraphic surface covered is greater than  $1''$ , 15 or more sensors will be activated disabling all count output pulses ( $X_L$ ,  $X_R$ ,  $Y_U$ ,  $Y_D$ ), until the number of sensors activated drops to 14 less.
5. All count outputs ( $X_L$ ,  $X_R$ ,  $Y_U$ ,  $Y_D$ ) are open collector and must be pulled up externally to user's logic level ( $4.7 \text{ kilohms}$  to  $+5\text{V}$  suggested,  $V_H$  cannot exceed  $+15\text{V}$ ).
6. All X and Y count output pulses will be  $\approx 5\mu\text{s}$  wide, with Y up or down pulses going true  $\approx 7\mu\text{s}$  after the leading edge of frame sync, and X left or right pulses going true  $\approx 12 \mu\text{s}$  after the leading edge.







drawing, tracing, digitizing and tracking, it is a far superior and more economical input device. It provides even greater capabilities and flexibility in many applications where previously only a simple positioner was justified. For example, it provides capabilities found individually in a trackball, joystick and light pen. It is a solid-state 2-D positioning and tracking device that produces X-Y positioning signals, as we said, when the finger is moved across its surface. It has no moving parts to break down or wear out, since moving a fingertip across the surface as though rolling an imaginary ball or small thumbwheel permits sensors embedded under the MicroProximity sensing surface to detect the presence, motion and direction of motion. For many applications it provides coarse and fine control of the X-Y movement. It can be wiped up to 60 ips for rapid slewing to a distant position or wiped one step at a time even in high resolution systems.

As the finger moves, proprietary sensing circuitry produces X-right, X-left, Y-up and Y-down output signals on four lines. A fifth output line provides a "presence" signal, indicating fingertip presence on the surface even when stationary. The positioner digital output is TTL- and CMOS-compatible, so it interfaces to computers,  $\mu$ Ps or digital counters. The surface is compact and virtually indestructible. The

entire control mechanism is 4"×4"×1/2". It is rugged and chemical resistant.

### how does it work?

It is a VSL hybrid system operating on the proprietary high-speed MicroProximity "capacitive" sensing principle. As the fingertip touches and glides across the sensing surface, capacitive coupling causes sequential activation of one or more of 3600 sensors on two axes simultaneously. This information is internally processed to produce an output pulse train, which then provides information on the number of incremental steps and the moving finger's direction.

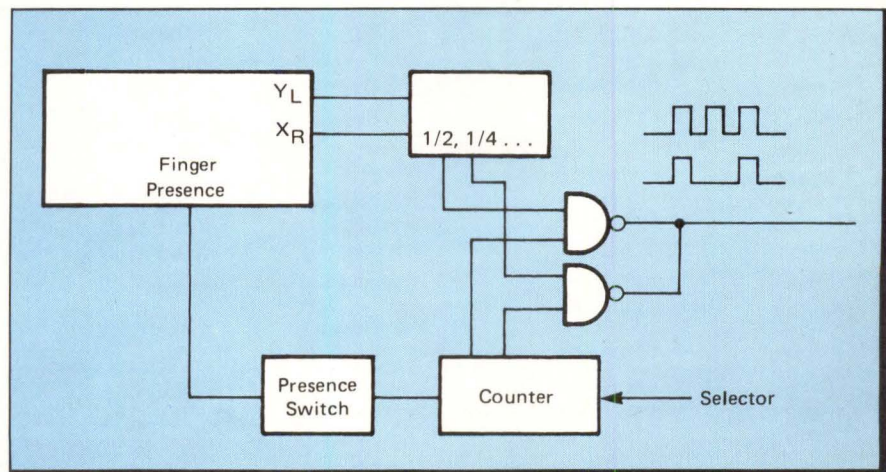
It is constructed as a block-like multi-laminate of an insulated touch

surface, sensor array, circuit carrier board, mounting bezel and back panel. The sensor array and circuit board are connected inside the block. On the circuit board, active elements are wire-bonded chips.

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by the Engineering Staff

Engineering Staff, TASA, Inc., 2346 Walsh Ave., Santa Clara, CA 95051.





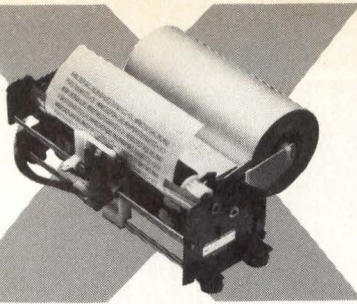
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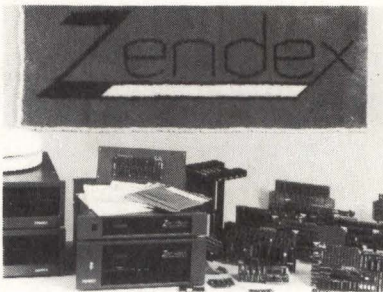
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